

40-pin Data Sheet – megaAVR® 0-series

Introduction

The ATmega4809 microcontrollers of the megaAVR® 0-series are using the AVR® processor with hardware multiplier, running at up to 20 MHz, with a wide range of Flash sizes up to 48 KB, up to 6 KB of SRAM, and 256 bytes of EEPROM in 28-, 32-, 40-, or 48-pin package. The series uses the latest technologies from Microchip with a flexible and low-power architecture including Event System and SleepWalking, accurate analog features and advanced peripherals.

The devices described here offer a Flash size of 48 KB in a 40-pin package.



Important: The 40-pin version of the ATmega4809 is using the die of the 48-pin ATmega4809 but offers fewer connected pads. For this reason, the pins PB[5:0] and PC[7:6] must be disabled (INPUT_DISABLE) or enable pull-ups (PULLUPEN).

Features

- AVR® CPU
 - Single-cycle I/O access
 - Two-level interrupt controller
 - Two-cycle hardware multiplier
- Memories
 - Up to 48 KB In-system self-programmable Flash memory
 - 256B EEPROM
 - Up to 6 KB SRAM
 - Write/Erase endurance:
 - Flash 10,000 cycles
 - EEPROM 100,000 cycles
 - Data retention: 40 Years at 55°C
- System
 - Power-on Reset (POR) circuit
 - Brown-out Detector (BOD)
 - Clock options:
 - 16/20 MHz low-power internal oscillator
 - 32.768 kHz Ultra Low-Power (ULP) internal oscillator
 - 32.768 kHz external crystal oscillator
 - External clock input

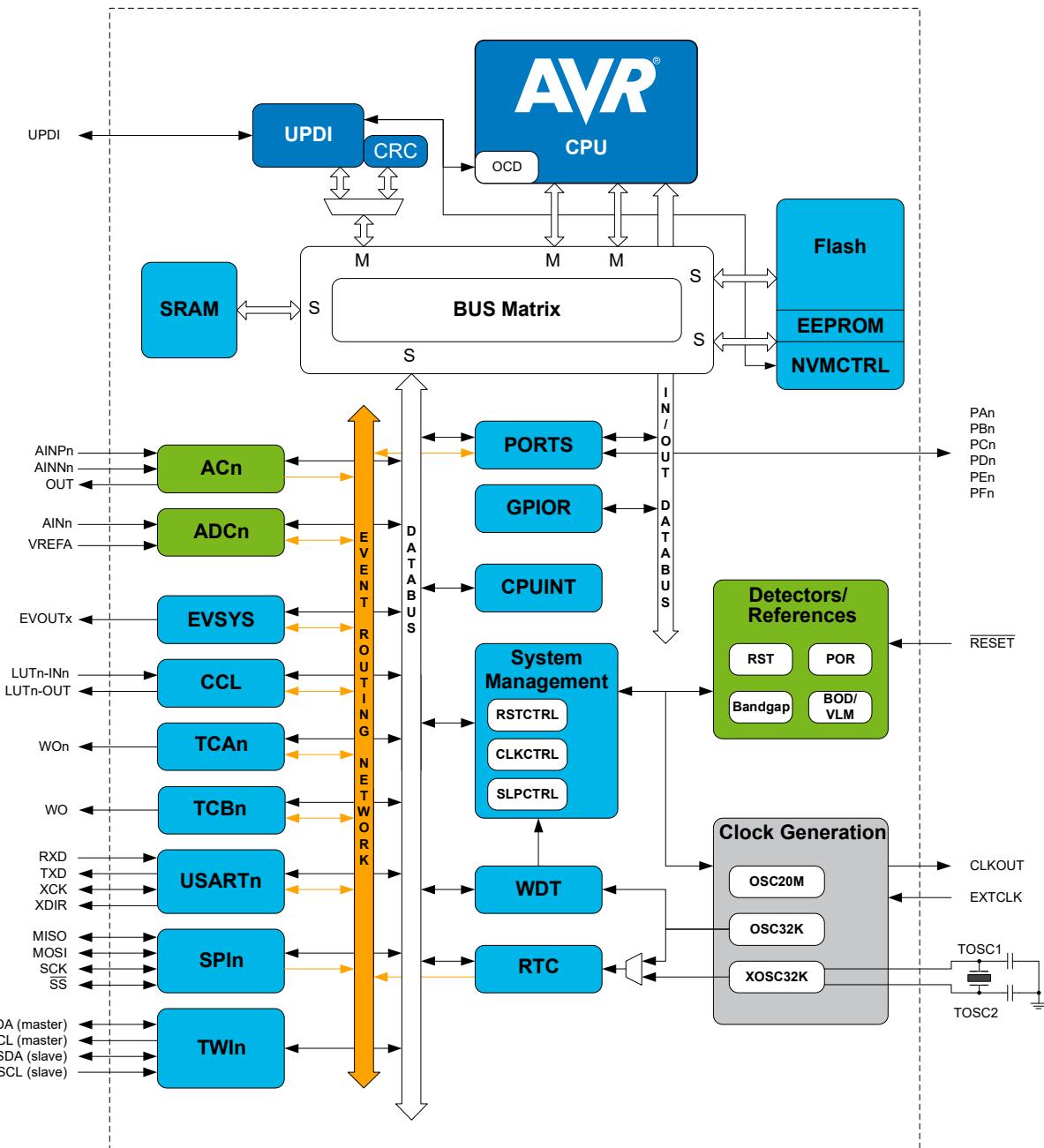
- Single pin Unified Program Debug Interface (UPDI)
- Three sleep modes:
 - Idle with all peripherals running for immediate wake-up
 - Standby
 - Configurable operation of selected peripherals
 - SleepWalking peripherals
 - Power-Down with limited wake-up functionality
- Peripherals
 - One 16-bit Timer/Counter type A (TCA) with a dedicated period register and three compare channels
 - Four 16-bit Timer/Counter type B with input capture (TCB)
 - One 16-bit Real-Time Counter (RTC) running from an external crystal or an internal RC oscillator
 - Four USART with fractional baud rate generator, auto-baud, and start-of-frame detection
 - Master/slave Serial Peripheral Interface (SPI)
 - Dual mode Master/Slave TWI with dual address match
 - Standard mode (Sm , 100 kHz)
 - Fast mode (Fm , 400 kHz)
 - Fast mode plus (Fm+ , 1 MHz)
 - Event System for CPU independent and predictable inter-peripheral signaling
 - Configurable Custom Logic (CCL) with up to four programmable Look-up Tables (LUT)
 - One Analog Comparator (AC) with a scalable reference input
 - One 10-bit 150 kspS Analog to Digital Converter (ADC)
 - Five selectable internal voltage references: 0.55V, 1.1V, 1.5V, 2.5V, and 4.3V
 - CRC code memory scan hardware
 - Optional automatic scan before code execution is allowed
 - Watchdog Timer (WDT) with Window mode, with separate on-chip oscillator
 - External interrupt on all general purpose pins
- I/O and Packages:
 - 34 programmable I/O lines
 - 40-pin PDIP
- Temperature Range: -40°C to 125°C
- Speed Grades -40°C to 105°C:
 - 0-5 MHz @ 1.8V – 5.5V
 - 0-10 MHz @ 2.7V – 5.5V
 - 0-20 MHz @ 4.5V – 5.5V
- Speed Grades -40°C to 125°C:
 - 0-8 MHz @ 2.7V - 5.5V
 - 0-16 MHz @ 4.5V - 5.5V

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1. Block Diagram



2. Pinout

2.1 40-pin PDIP

PC0	1	40	PA7
PC1	2	39	PA6
PC2	3	38	PA5
PC3	4	37	PA4
VDD	5	36	PA3
GND	6	35	PA2
PC4	7	34	PA1
PC5	8	33	PA0 (EXTCLK)
PD0	9	32	GND
PD1	10	31	VDD
PD2	11	30	UPDI
PD3	12	29	PF6
PD4	13	28	PF5
PD5	14	27	PF4
PD6	15	26	PF3
PD7	16	25	PF2
AVDD	17	24	PF1 (TOSC2)
GND	18	23	PF0 (TOSC1)
PE0	19	22	PE3
PE1	20	21	PE2

ATmega4809 – 40-pin Pinout

Power	Functionality
Input supply	Programming, debug
Ground	Clock, crystal
GPIO on VDD power domain	TWI
GPIO on AVDD power domain	Digital functions only
	Analog functions

3. I/O Multiplexing and Considerations

3.1 Multiplexed Signals

PDIP40(4)	Pin name (1,2)	Special	ADC0	AC0	USARTn	SPI0	TWI0	TCA0	TCBn	EVSYS	CCL-LUTn
33	PA0	EXTCLK			0,TxD			0-WO0			0-IN0
34	PA1				0,RxD			0-WO1			0-IN1
35	PA2	TWI			0,XCK		SDA(MS)	0-WO2	0-WO	EVOUTA	0-IN2
36	PA3	TWI			0,XDIR		SCL(MS)	0-WO3	1-WO		0-OUT
37	PA4				0,TxD ⁽³⁾	MOSI		0-WO4			
38	PA5				0,RxD ⁽³⁾	MISO		0-WO5			
39	PA6				0,XCK ⁽³⁾	SCK					0-OUT ⁽³⁾
40	PA7	CLKOUT		OUT	0,XDIR ⁽³⁾	SS				EVOUTA ⁽³⁾	
1	PC0				1,TxD	MOSI ⁽³⁾		0-WO0 ⁽³⁾	2-WO		1-IN0
2	PC1				1,RxD	MISO ⁽³⁾		0-WO1 ⁽³⁾	3-WO ⁽³⁾		1-IN1
3	PC2	TWI			1,XCK	SCK ⁽³⁾	SDA(MS) ⁽³⁾	0-WO2 ⁽³⁾		EVOUTC	1-IN2
4	PC3	TWI			1,XDIR	SS ⁽³⁾	SCL(MS) ⁽³⁾	0-WO3 ⁽³⁾			1-OUT
5	VDD										
6	GND										
7	PC4				1,TxD ⁽³⁾			0-WO4 ⁽³⁾			
8	PC5				1,RxD ⁽³⁾			0-WO5 ⁽³⁾			
9	PD0		AIN0					0-WO0 ⁽³⁾			2-IN0
10	PD1		AIN1	P3				0-WO1 ⁽³⁾			2-IN1
11	PD2		AIN2	P0				0-WO2 ⁽³⁾		EVOUTD	2-IN2
12	PD3		AIN3	N0				0-WO3 ⁽³⁾			2-OUT
13	PD4		AIN4	P1				0-WO4 ⁽³⁾			
14	PD5		AIN5	N1				0-WO5 ⁽³⁾			
15	PD6		AIN6	P2							2-OUT ⁽³⁾
16	PD7	VREFA	AIN7	N2						EVOUTD ⁽³⁾	
17	AVDD										
18	GND										
19	PE0		AIN8			MOSI ⁽³⁾		0-WO0 ⁽³⁾			
20	PE1		AIN9			MISO ⁽³⁾		0-WO1 ⁽³⁾			
21	PE2		AIN10			SCK ⁽³⁾		0-WO2 ⁽³⁾		EVOUTE	
22	PE3		AIN11			SS ⁽³⁾		0-WO3 ⁽³⁾			
23	PF0	TOSC1			2,TxD			0-WO0 ⁽³⁾			3-IN0
24	PF1	TOSC2			2,RxD			0-WO1 ⁽³⁾			3-IN1
25	PF2	TWI	AIN12		2,XCK		SDA(S) ⁽³⁾	0-WO2 ⁽³⁾		EVOUTF	3-IN2
26	PF3	TWI	AIN13		2,XDIR		SCL(S) ⁽³⁾	0-WO3 ⁽³⁾			3-OUT
27	PF4		AIN14		2,TxD ⁽³⁾			0-WO4 ⁽³⁾	0-WO ⁽³⁾		
28	PF5		AIN15		2,RxD ⁽³⁾			0-WO5 ⁽³⁾	1-WO ⁽³⁾		
29	PF6	RESET			2,XCK ⁽³⁾						3-OUT ⁽³⁾
30	UPDI										
31	VDD										
32	GND										

ATmega4809 – 40-pin I/O Multiplexing and Considerations

Note:

1. Pin names are of type Pxn , with x being the PORT instance (A,B,C, ...) and n the pin number.
Notation for signals is $\text{PORT}x_\text{PIN}n$. All pins can be used as event input.
2. All pins can be used for external interrupt, where pins Px2 and Px6 of each port have full asynchronous detection.
3. Alternate pin positions. For selecting the alternate positions, refer to the PORTMUX documentation.
4. The 40-pin version of the ATmega4809 is using the die of the 48-pin ATmega4809 but offers fewer connected pads. For this reason, the pins PB[5:0] and PC[7:6] must be disabled (INPUT_DISABLE) or enable pull-ups (PULLUPEN).

4. Electrical Characteristics

4.1 Disclaimer

All typical values are measured at $T = 25^{\circ}\text{C}$ and $V_{\text{DD}} = 3\text{V}$ unless otherwise specified. All minimum and maximum values are valid across operating temperature and voltage unless otherwise specified.

Typical values given should be considered for design guidance only, and actual part variation around these values is expected.

4.2 Absolute Maximum Ratings

Stresses beyond those listed in this section may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Table 4-1. Absolute Maximum Ratings

Symbol	Description	Conditions	Min.	Max.	Unit
V_{DD}	Power Supply Voltage		-0.5	6	V
I_{VDD}	Current into a V_{DD} pin	$T_A = [-40, 85]^{\circ}\text{C}$	-	200	mA
		$T_A = [85, 125]^{\circ}\text{C}$	-	100	mA
I_{GND}	Current out of a GND pin	$T_A = [-40, 85]^{\circ}\text{C}$	-	200	mA
		$T_A = [85, 125]^{\circ}\text{C}$	-	100	mA
V_{PIN}	Pin voltage with respect to GND		-0.5	$V_{\text{DD}} + 0.5$	V
I_{PIN}	I/O pin sink/source current		-40	40	mA
$I_{\text{C1}}^{(1)}$	I/O pin injection current except for the RESET pin	$V_{\text{pin}} < \text{GND} - 0.6\text{V}$ or $5.5\text{V} < V_{\text{pin}} \leq 6.1\text{V}$ $4.9\text{V} < V_{\text{DD}} \leq 5.5\text{V}$	-1	1	mA
$I_{\text{C2}}^{(1)}$	I/O pin injection current except for the RESET pin	$V_{\text{pin}} < \text{GND} - 0.6\text{V}$ or $V_{\text{pin}} \leq 5.5\text{V}$ $V_{\text{DD}} \leq 4.9\text{V}$	-15	15	mA
T_{storage}	Storage temperature		-65	150	$^{\circ}\text{C}$

Note:

- If V_{PIN} is lower than GND-0.6V, then a current limiting resistor is required. The negative DC injection current limiting resistor is calculated as $R = (\text{GND} - 0.6\text{V} - V_{\text{pin}})/I_{\text{Cn}}$.
 - If V_{PIN} is greater than $V_{\text{DD}} + 0.6\text{V}$, then a current limiting resistor is required. The positive DC injection current limiting resistor is calculated as $R = (V_{\text{pin}} - (V_{\text{DD}} + 0.6))/I_{\text{Cn}}$.

4.3 General Operating Ratings

The device must operate within the ratings listed in this section in order for all other electrical characteristics and typical characteristics of the device to be valid.

ATmega4809 – 40-pin Electrical Characteristics

Table 4-2. General Operating Conditions

Symbol	Description	Condition	Min.	Max.	Unit
V _{DD}	Operating Supply Voltage		1.8 ⁽¹⁾	5.5	V
T _A	Operating temperature range		-40	125	°C

Note:

1. Operation is guaranteed down to 1.8V or V_{BOD} with BODLEVEL0, whichever is lower.

Table 4-3. Operating Voltage and Frequency

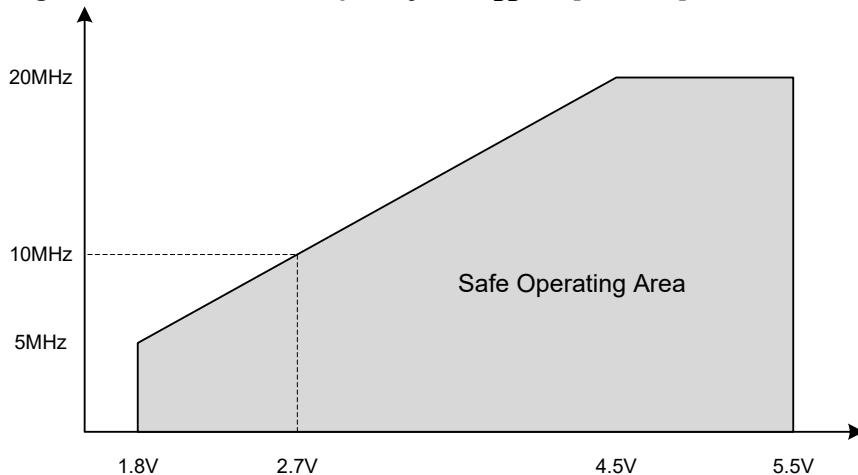
Symbol	Description	Condition	Min.	Max.	Unit
f _{CLK_CPU}	Nominal operating system clock frequency	V _{DD} =[1.8, 5.5]V T _A =[-40, 105]°C ⁽¹⁾⁽⁴⁾	0	5	MHz
		V _{DD} =[2.7, 5.5]V T _A =[-40, 105]°C ⁽²⁾⁽⁴⁾	0	10	
		V _{DD} =[4.5, 5.5]V T _A =[-40, 105]°C ⁽³⁾⁽⁴⁾	0	20	
		V _{DD} =[2.7, 5.5]V T _A =[-40, 125]°C ⁽²⁾	0	8	
		V _{DD} =[4.5, 5.5]V T _A =[-40, 125]°C ⁽²⁾	0	16	

Note:

1. Operation is guaranteed down to BOD triggering level, V_{BOD} with BODLEVEL0.
2. Operation is guaranteed down to BOD triggering level, V_{BOD} with BODLEVEL2.
3. Operation is guaranteed down to BOD triggering level, V_{BOD} with BODLEVEL7.
4. These specifications do not apply to automotive range parts (-VAO).

The maximum CPU clock frequency depends on V_{DD}. As shown in the figure below, the Maximum Frequency vs. V_{DD} is linear between 1.8V < V_{DD} < 2.7V and 2.7V < V_{DD} < 4.5V.

Figure 4-1. Maximum Frequency vs. V_{DD} for [-40, 105]°C



4.4 Power Considerations

The average die junction temperature, T_J (in °C) is given from the formula

$$T_J = T_A + P_D * R_{\theta JA}$$

where P_D is the total power dissipation.

The total thermal resistance of a package ($R_{\theta JA}$) can be separated into two components, $R_{\theta JC}$ and $R_{\theta CA}$, representing the barrier to heat flow from the semiconductor junction to the package (case) surface ($R_{\theta JC}$) and from the case to the outside ambient air ($R_{\theta CA}$). These terms are related by the equation:

$$R_{\theta JA} = R_{\theta JC} + R_{\theta CA}.$$

$R_{\theta JC}$ is device related and cannot be influenced by the user. However, $R_{\theta CA}$ is user dependent and can be minimized by thermal management techniques such as heat sinks, ambient air cooling, and thermal convection. Thus, good thermal management on the part of the user can significantly reduce $R_{\theta CA}$ so that $R_{\theta JA}$ approximately equals $R_{\theta JC}$.

The power dissipation curve is negatively sloped as ambient temperature increase. The maximum power dissipation is therefore at minimum ambient temperature while the highest junction temperature occurs at the maximum ambient temperature.

Table 4-4. Power Dissipation and Junction Temperature vs Temperature

Package	T _A Range	R _{θJA} (°C/W)	P _D (W) Typical	T _J - T _A (°C) Typical
PDIP40	-40°C to 125°C		1.0	

4.5 Power Consumption

The values are measured power consumption under the following conditions, except where noted:

- V_{DD}=3V
- T_A=25°C
- OSC20M used as system clock source, except where otherwise specified
- System power consumption measured with peripherals disabled and I/O ports driven low with inputs disabled

ATmega4809 – 40-pin Electrical Characteristics

Table 4-5. Power Consumption in Active and Idle Mode

Mode	Description	Condition	Typ.	Max.	Unit
Active	Active power consumption	$f_{CLK_CPU}=20\text{ MHz (OSC20M)}$	$V_{DD}=5\text{V}$	8.5	- mA
		$f_{CLK_CPU}=10\text{ MHz (OSC20M div2)}$	$V_{DD}=5\text{V}$	4.3	- mA
			$V_{DD}=3\text{V}$	2.3	- mA
		$f_{CLK_CPU}=5\text{ MHz (OSC20M div4)}$	$V_{DD}=5\text{V}$	2.2	- mA
			$V_{DD}=3\text{V}$	1.2	- mA
			$V_{DD}=2\text{V}$	0.75	- mA
		$f_{CLK_CPU}=32.768\text{ kHz (OSCULP32K)}$	$V_{DD}=5\text{V}$	16.4	- μA
			$V_{DD}=3\text{V}$	9.0	- μA
			$V_{DD}=2\text{V}$	6.0	- μA
Idle	Idle power consumption	$f_{CLK_CPU}=20\text{ MHz (OSC20M)}$	$V_{DD}=5\text{V}$	2.8	- mA
		$f_{CLK_CPU}=10\text{ MHz (OSC20M div2)}$	$V_{DD}=5\text{V}$	1.4	- mA
			$V_{DD}=3\text{V}$	0.8	- mA
		$f_{CLK_CPU}=5\text{ MHz (OSC20M div4)}$	$V_{DD}=5\text{V}$	0.7	- mA
			$V_{DD}=3\text{V}$	0.4	- mA
			$V_{DD}=2\text{V}$	0.25	- mA
		$f_{CLK_CPU}=32.768\text{ kHz (OSCULP32K)}$	$V_{DD}=5\text{V}$	5.6	- μA
			$V_{DD}=3\text{V}$	2.8	- μA
			$V_{DD}=2\text{V}$	1.8	- μA

Table 4-6. Power Consumption in Power-Down, Standby and Reset Mode

Mode	Description	Condition	Typ. 25°C	Max. 85°C ⁽¹⁾	Max. 125°C	Unit
Standby	Standby power consumption	RTC running at 1.024 kHz from external XOSC32K (CL=7.5 pF)	$V_{DD}=3\text{V}$	0.7	-	- μA
		RTC running at 1.024 kHz from internal OSCULP32K	$V_{DD}=3\text{V}$	0.7	6.0	16.0 μA
Power Down/ Standby	Power down/ Standby power consumption are the same when all peripherals are stopped	All peripherals stopped	$V_{DD}=3\text{V}$	0.1	5.0	15.0 μA

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Mode	Description	Condition		Typ. 25°C	Max. 85°C ⁽¹⁾	Max. 125°C	Unit
Reset	Reset power consumption	RESET line pulled low	V _{DD} =3V	100	-	-	µA

Note:

- These parameters are for design guidance only and are not tested.

4.6 Peripherals Power Consumption

The table below can be used to calculate the additional current consumption for the different I/O peripherals in the various operating modes.

Some peripherals will request the clock to be enabled when operating in STANDBY. See the peripheral chapter for further information.

Operating conditions:

- V_{DD}=3V
- T=25°C
- OSC20M at 1 MHz used as system clock source, except where otherwise specified
- In Idle Sleep mode, except where otherwise specified

Table 4-7. Peripherals Power Consumption

Peripheral	Conditions	Typ. ⁽¹⁾	Unit
BOD	Continuous	19	µA
	Sampling @ 1 kHz	1.2	
TCA	16-bit count @ 1 MHz	13.0	µA
TCB	16-bit count @ 1 MHz	7.4	µA
RTC	16-bit count @ OSCULP32K	1.2	µA
WDT (including OSCULP32K)		0.7	µA
OSC20M		130	µA
AC	Fast Mode ⁽²⁾	92	µA
	Low-Power Mode ⁽²⁾	45	
ADC ⁽³⁾	50 ksps	330	µA
	100 ksps	340	
XOSC32K	C _L =7.5 pF	0.5	µA
OSCULP32K		0.4	µA
USART	Enable @ 9600 Baud	13.0	µA
SPI (Master)	Enable @ 100 kHz	2.1	µA

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Peripheral	Conditions	Typ. ⁽¹⁾	Unit
TWI (Master)	Enable @ 100 kHz	24.0	µA
TWI (Slave)	Enable @ 100 kHz	17.0	µA
Flash programming	Erase Operation	1.5	mA
	Write Operation	3.0	

Note:

1. Current consumption of the module only. To calculate the total internal power consumption of the microcontroller, add this value to the base power consumption given in “Power Consumption” section in electrical characteristics.
2. CPU in Standby mode.
3. Average power consumption with ADC active in Free-Running mode.

4.7 BOD and POR Characteristics

Table 4-8. Power Supply Characteristics

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
SRON ⁽¹⁾	Power-on Slope		-	-	100 ⁽²⁾	V/ms

Note:

1. For design guidance only and not tested in production.
2. A slope faster than the maximum rating can trigger a reset of the device if changing the voltage level after an initial power-up.

Table 4-9. Power-on Reset (POR) Characteristics

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
V _{POR}	POR threshold voltage on V _{DD} falling	V _{DD} falls/rises at 0.5V/ms or slower	0.8 ⁽¹⁾	-	1.6 ⁽¹⁾	V
	POR threshold voltage on V _{DD} rising		1.4 ⁽¹⁾	-	1.8	

Note:

1. For design guidance only and not tested in production.

Table 4-10. Brown-out Detector (BOD) Characteristics

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
V _{BOD}	BOD detection level (falling/rising)	BODLEVEL0	1.7	1.8	2.0	V
		BODLEVEL2	2.4	2.6	2.9	
		BODLEVEL7	3.9	4.3	4.5	

.....continued

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
V_{HYS}	Hysteresis	BODLEVEL0	-	25	-	mV
		BODLEVEL2	-	40	-	
		BODLEVEL7	-	80	-	
t_{BOD}	Detection time	Continuous	-	7	-	μs
		Sampled, 1 kHz	-	1	-	ms
		Sampled, 125 Hz	-	8	-	
$t_{startup}$	Start-up time	Time from enable to ready	-	40	-	μs
V_{INT}	Interrupt level 0	Percentage above the selected BOD level	-	4	-	%
	Interrupt level 1		-	13	-	
	Interrupt level 2		-	25	-	

4.8 External Reset Characteristics

Table 4-11. External Reset Characteristics

Mode	Description	Condition	Min.	Typ.	Max.	Unit
V_{VIH_RST}	Input Voltage for $\overline{\text{RESET}}$	$0.7 \times V_{DD}$	-	$V_{DD} + 0.2$	V	
V_{VIL_RST}	Input Low Voltage for $\overline{\text{RESET}}$		-0.2			
t_{MIN_RST}	Minimum pulse width on $\overline{\text{RESET}}$ pin ⁽¹⁾	-	-	2.5	-	μs
R_{p_RST}	$\overline{\text{RESET}}$ pull-up resistor	$V_{Reset}=0V$	20	35	50	kΩ

Note:

- These parameters are for design guidance only and are not production tested.

4.9 Oscillators and Clocks

Operating conditions:

- $V_{DD}=3V$, except where specified otherwise

Table 4-12. 20 MHz Internal Oscillator (OSC20M) Characteristics

Symbol	Description	Condition		Min.	Typ.	Max.	Unit
f_{OSC20M}	Factory calibration frequency	FREQSEL=0	$T_A=25^\circ\text{C}, 3.0V$	16		20	MHz
		FREQSEL=1					
f_{CAL}	Frequency calibration range	OSC16M ⁽²⁾		14.5		17.5	MHz
		OSC20M ⁽²⁾		18.5		21.5	MHz

ATmega4809 – 40-pin Electrical Characteristics

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Symbol	Description	Condition	Min.	Typ.	Max.	Unit
E_{TOTAL}	Total error with 16 MHz and 20 MHz frequency selection	From target frequency	$T_A=25^\circ\text{C}, 3.0\text{V}$	-1.5		1.5 %
			$T_A=[0, 70]^\circ\text{C}, V_{DD}=[1.8, 3.6]\text{V}$	-2.0		2.0 %
			Full operation range	-4.0		4.0
E_{DRIFT}	Accuracy with 16 MHz and 20 MHz frequency selection relative to the factory-stored frequency value	Factory calibrated $V_{DD}=3\text{V}^{(1)}$	$T_A=[0, 70]^\circ\text{C}, V_{DD}=[1.8, 5.5]\text{V}$	-1.8		1.8 %
Δf_{OSC20M}	Calibration step size			-	0.75	- %
D_{OSC20M}	Duty cycle			-	50	- %
$t_{startup}$	Start-up time	Within 2% accuracy		-	12	- μs

Note:

1. See also the description of OSC20M on calibration.
2. Oscillator Frequencies above speed specification must be divided so the CPU clock is always within specification.

Table 4-13. 32.768 kHz Internal Oscillator (OSCULP32K) Characteristics

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
$f_{OSCULP32K}$	Factory calibration frequency	$T_A=25^\circ\text{C}, 3.0\text{V}$	32.768			kHz
	Factory calibration accuracy				3	%
E_{TOTAL}	Total error from target frequency	$T_A=[0, 70]^\circ\text{C}, V_{DD}=[1.8, 3.6]\text{V}$	-10		+10	%
		Full operation range	-20		+20	
$D_{OSCULP32K}$	Duty cycle			50		%
$t_{startup}$	Start-up time		-	250	-	μs

Table 4-14. 32.768 kHz External Crystal Oscillator (XOSC32K) Characteristics

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
f_{out}	Frequency		-	32.768	-	kHz
$t_{startup}$	Start-up time	$C_L=7.5 \text{ pF}$	-	300	-	ms
C_L	Crystal load capacitance ⁽¹⁾		7.5	-	12.5	pF
$C_{TOSC1/TOSC2}$	Parasitic pin capacitance		-	5.5	-	pF
ESR ⁽¹⁾	Equivalent Series Resistance - Safety Factor=3	$C_L=7.5 \text{ pF}$	-	-	80	$\text{k}\Omega$
		$C_L=12.5 \text{ pF}$	-	-	40	

Note:

1. This parameter is for design guidance only and not production tested.

Figure 4-2. External Clock Waveform Characteristics

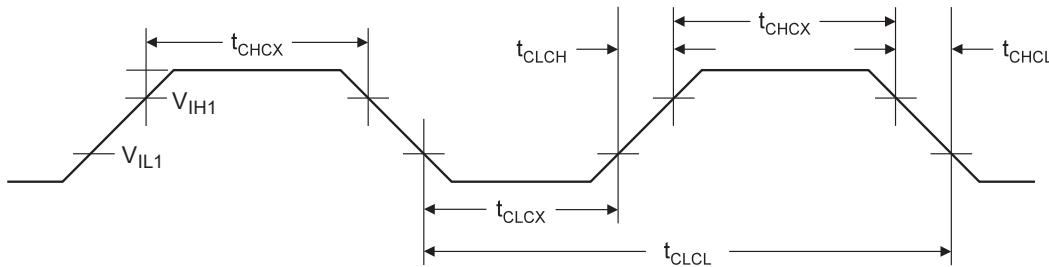


Table 4-15. External Clock Characteristics

Symbol	Description	Condition	$V_{DD}=[1.8, 5.5]V$		$V_{DD}=[2.7, 5.5]V$		$V_{DD}=[4.5, 5.5]V$		Unit
			Min.	Max.	Min.	Max.	Min.	Max.	
f_{CLCL}	Frequency		0	5.0	0.0	10.0	0.0	20.0	MHz
t_{CLCL}	Clock Period		200	-	100	-	50	-	ns
$t_{CHCX}^{(1)}$	High Time		80	-	40	-	20	-	ns
$t_{CLCX}^{(1)}$	Low Time		80	-	40	-	20	-	ns
$t_{CLCH}^{(1)}$	Rise Time (for maximum frequency)		-	40	-	20	-	10	ns
$t_{CHCL}^{(1)}$	Fall Time (for maximum frequency)		-	40	-	20	-	10	ns
$\Delta t_{CLCL}^{(1)}$	Change in period from one clock cycle to the next		-	20	-	20	-	20	%

Note:

1. This parameter is for design guidance only and not production tested.

4.10 I/O Pin Characteristics

Table 4-16. I/O Pin Characteristics ($T_A=[-40, 85]^\circ C$, $V_{DD}=[1.8, 5.5]V$ unless otherwise noted)

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
V_{IL}	Input Low Voltage		-0.2	-	$0.3 \times V_{DD}$	V
V_{IH}	Input High Voltage		$0.7 \times V_{DD}$	-	$V_{DD}+0.2V$	V
I_{IH} / I_{IL}	I/O pin Input Leakage Current	$V_{DD}=5.5V$, pin high	-	< 0.05	-	μA
		$V_{DD}=5.5V$, pin low	-	< 0.05	-	

ATmega4809 – 40-pin Electrical Characteristics

.....continued

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
V _{OL}	I/O pin drive strength	V _{DD} =1.8V, I _{OL} =1.5 mA	-	-	0.36	V
		V _{DD} =3.0V, I _{OL} =7.5 mA	-	-	0.6	
		V _{DD} =5.0V, I _{OL} =15 mA	-	-	1	
V _{OH}	I/O pin drive strength	V _{DD} =1.8V, I _{OH} =1.5 mA	1.44	-	-	V
		V _{DD} =3.0V, I _{OH} =7.5 mA	2.4	-	-	
		V _{DD} =5.0V, I _{OH} =15 mA	4	-	-	
I _{total}	Maximum combined I/O sink/source current per pin group ^(1,2)	T _A =125°C	-	-	100	mA
	Maximum combined I/O sink/source current per pin group ^(1,2)	T _A =25°C	-	-	200	
t _{RISE}	Rise time	V _{DD} =3.0V, load=20 pF	-	2.5	-	ns
		V _{DD} =5.0V, load=20 pF	-	1.5	-	
		V _{DD} =3.0V, load=20 pF, slew rate enabled	-	19	-	
		V _{DD} =5.0V, load=20 pF, slew rate enabled	-	9	-	
t _{FALL}	Fall time	V _{DD} =3.0V, load=20 pF	-	2.0	-	ns
		V _{DD} =5.0V, load=20 pF	-	1.3	-	
		V _{DD} =3.0V, load=20 pF, slew rate enabled	-	21	-	
		V _{DD} =5.0V, load=20 pF, slew rate enabled	-	11	-	
C _{pin}	I/O pin capacitance except for TOSC, VREFA, and TWI pins		-	3.5	-	pF
C _{pin}	I/O pin capacitance on TOSC pins		-	4	-	pF
C _{pin}	I/O pin capacitance on TWI pins		-	10	-	pF
C _{pin}	I/O pin capacitance on VREFA pin		-	14	-	pF
R _p	Pull-up resistor		20	35	50	kΩ

Note:

1. Pin group A (PA[7:0]), PF[6:2]), pin group B (PB[7:0], PC[7:0]), pin group C (PD:7:0, PE[3:0], PF[1:0]). For 28-pin and 32-pin devices pin group A and B should be seen as a single group. The combined continuous sink/source current for each individual group should not exceed the limits.
2. These parameters are for design guidance only and are not production tested.

4.11 USART

Figure 4-3. USART in SPI Mode - Timing Requirements in Master Mode

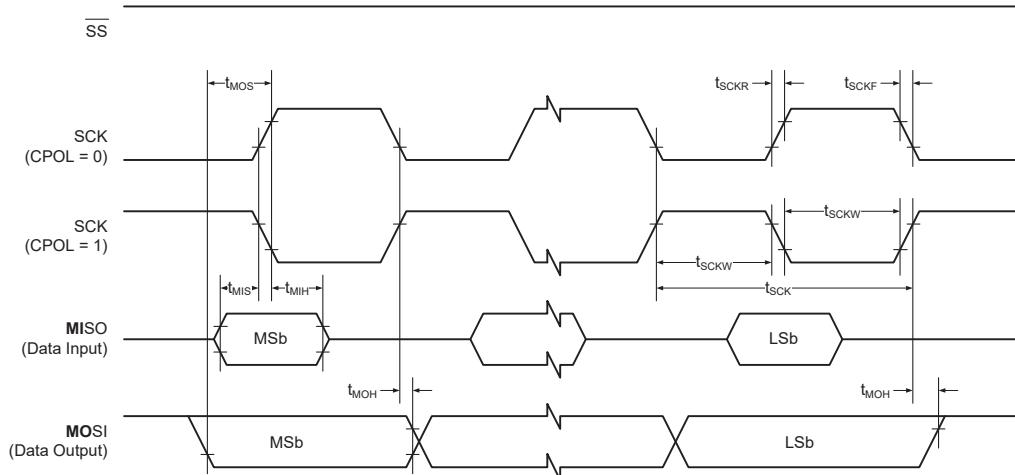


Table 4-17. USART in SPI Master Mode - Timing Characteristics

Symbol ⁽¹⁾	Description	Condition	Min.	Typ.	Max.	Unit
f _{SCK}	SCK clock frequency	Master	-	-	10	MHz
t _{SCK}	SCK period	Master	100	-	-	ns
t _{SCKW}	SCK high/low width	Master	-	0.5×t _{SCK}	-	ns
t _{SCKR}	SCK rise time	Master	-	2.7	-	ns
t _{SCKF}	SCK fall time	Master	-	2.7	-	ns
t _{MIS}	MISO setup to SCK	Master	-	10	-	ns
t _{MIH}	MISO hold after SCK	Master	-	10	-	ns
t _{MOS}	MOSI setup to SCK	Master	-	0.5×t _{SCK}	-	ns
t _{MOH}	MOSI hold after SCK	Master	-	1.0	-	ns

Note:

1. These parameters are for design guidance only and are not production tested.

4.12 SPI

Figure 4-4. SPI - Timing Requirements in Master Mode

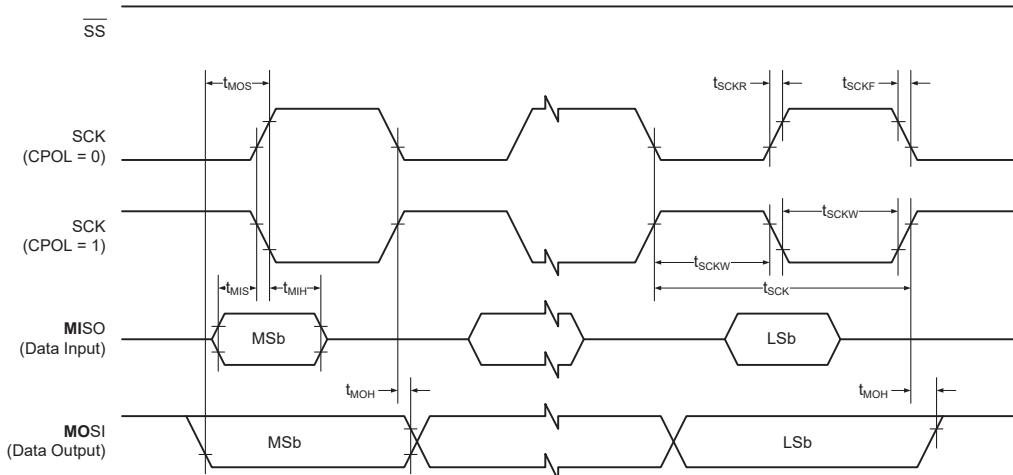


Figure 4-5. SPI - Timing Requirements in Slave Mode

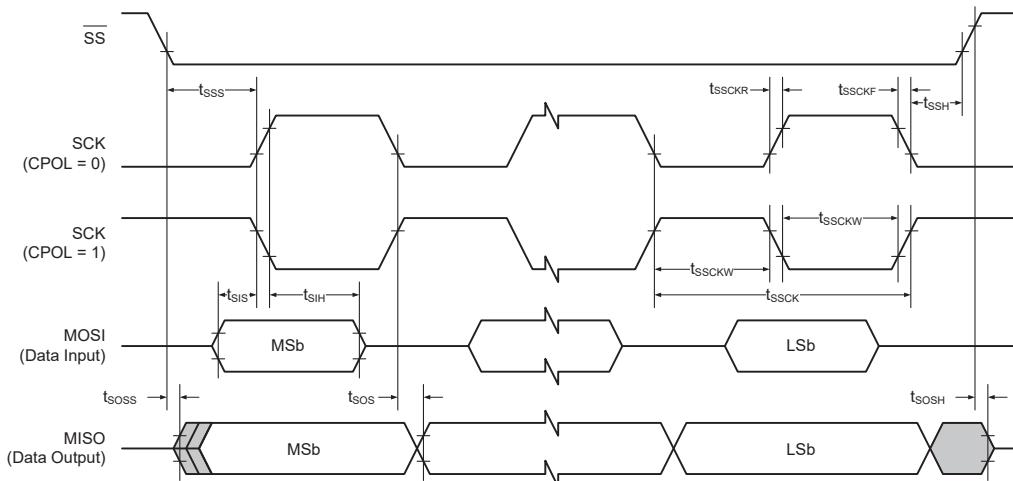


Table 4-18. SPI - Timing Characteristics

Symbol ⁽¹⁾	Description	Condition	Min.	Typ.	Max.	Unit
f_{SCK}	SCK clock frequency	Master	-	-	10	MHz
t_{SCK}	SCK period	Master	100	-	-	ns
t_{SCKW}	SCK high/low width	Master	-	0.5*SCK	-	ns
t_{SCKR}	SCK rise time	Master	-	2.7	-	ns
t_{SCKF}	SCK fall time	Master	-	2.7	-	ns
t_{MIS}	MISO setup to SCK	Master	-	10	-	ns
t_{MIH}	MISO hold after SCK	Master	-	10	-	ns
t_{MOS}	MOSI setup to SCK	Master	-	0.5*SCK	-	ns
t_{MOH}	MOSI hold after SCK	Master	-	1.0	-	ns

.....continued

Symbol ⁽¹⁾	Description	Condition	Min.	Typ.	Max.	Unit
f_{SSCK}	Slave SCK clock frequency	Slave	-	-	5	MHz
t_{SSCK}	Slave SCK period	Slave	$4*t_{Clkper}$	-	-	ns
t_{SSCKW}	SCK high/low width	Slave	$2*t_{Clkper}$	-	-	ns
t_{SSCKR}	SCK rise time	Slave	-	-	1600	ns
t_{SSCKF}	SCK fall time	Slave	-	-	1600	ns
t_{SIS}	MOSI setup to SCK	Slave	3.0	-	-	ns
t_{SIH}	MOSI hold after SCK	Slave	t_{Clkper}	-	-	ns
t_{SSS}	SS setup to SCK	Slave	21	-	-	ns
t_{SSH}	SS hold after SCK	Slave	20	-	-	ns
t_{SOS}	MISO setup to SCK	Slave	-	8.0	-	ns
t_{SOH}	MISO hold after SCK	Slave	-	13	-	ns
t_{SOSS}	MISO setup after SS low	Slave	-	11	-	ns
t_{SOSH}	MISO hold after SS low	Slave	-	8.0	-	ns

Note:

- These parameters are for design guidance only and are not production tested.

4.13 TWI

Figure 4-6. TWI - Timing Requirements

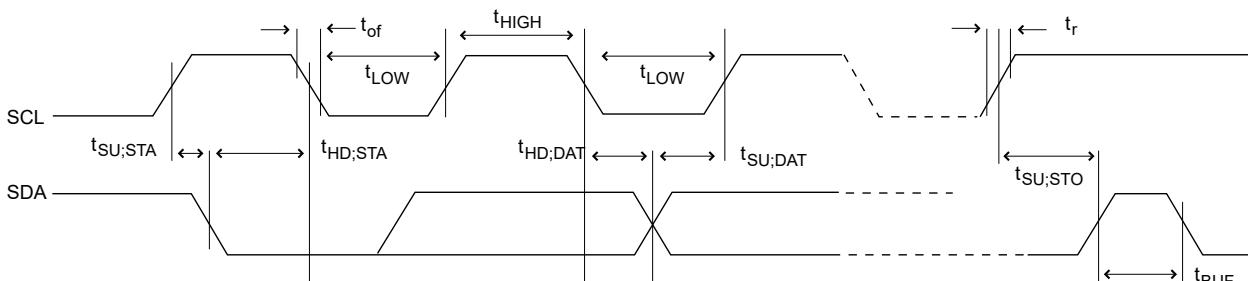


Table 4-19. TWI - Timing Characteristics

Symbol ⁽¹⁾	Description	Condition	Min.	Typ.	Max.	Unit
f_{SCL}	SCL clock frequency	Max. frequency requires system clock at 10 MHz, which, in turn, requires $V_{DD}=[2.7, 5.5]V$ and $T=[-40, 105]^{\circ}C$	0	-	1000	kHz
V_{IH}	Input high voltage		$0.7 \times V_{DD}$	-	-	V
V_{IL}	Input low voltage		-	-	$0.3 \times V_{DD}$	V

ATmega4809 – 40-pin Electrical Characteristics

.....continued

Symbol⁽¹⁾	Description	Condition		Min.	Typ.	Max.	Unit
V_{HYS}	Hysteresis of Schmitt trigger inputs			$0.1 \times V_{DD}$		$0.4 \times V_{DD}$	V
V_{OL}	Output low voltage	$I_{load}=20\text{ mA}$, Fast mode+		-	-	$0.2 \times V_{DD}$	V
		$I_{load}=3\text{ mA}$, Normal mode, $V_{DD}>2\text{ V}$		-	-	0.4V	
		$I_{load}=3\text{ mA}$, Normal mode, $V_{DD}\leq 2\text{ V}$		-	-	$0.2 \times V_{DD}$	
I_{OL}	Low-level output current	$f_{SCL}\leq 400\text{ kHz}$, $V_{OL}=0.4\text{ V}$		3	-	-	mA
		$f_{SCL}\leq 1\text{ MHz}$, $V_{OL}=0.4\text{ V}$		20	-	-	
C_B	Capacitive load for each bus line	$f_{SCL}\leq 100\text{ kHz}$		-	-	400	pF
		$f_{SCL}\leq 400\text{ kHz}$		-	-	400	
		$f_{SCL}\leq 1\text{ MHz}$		-	-	550	
t_R	Rise time for both SDA and SCL	$f_{SCL}\leq 100\text{ kHz}$		-	-	1000	ns
		$f_{SCL}\leq 400\text{ kHz}$		20	-	300	
		$f_{SCL}\leq 1\text{ MHz}$		-	-	120	
t_{OF}	Output fall time from $V_{IH\min}$ to $V_{IL\max}$	$10\text{ pF} < \text{capacitance of bus line} < 400\text{ pF}$	$f_{SCL}\leq 400\text{ kHz}$	$20+0.1 \times C_B$	-	300	ns
			$f_{SCL}\leq 1\text{ MHz}$	$20+0.1 \times C_B$	-	120	
t_{SP}	Spikes suppressed by the input filter			0	-	50	ns
I_L	Input current for each I/O pin	$0.1 \times V_{DD} < V_I < 0.9 \times V_{DD}$		-	-	1	μA
C_I	Capacitance for each I/O pin			-	-	10	pF
R_P	Value of pull-up resistor	$f_{SCL}\leq 100\text{ kHz}$		$(V_{DD}-V_{OL(\max)}) / I_{OL}$	-	$1000\text{ ns}/(0.8473 \times C_B)$	Ω
		$f_{SCL}\leq 400\text{ kHz}$		-	-	$300\text{ ns}/(0.8473 \times C_B)$	
		$f_{SCL}\leq 1\text{ MHz}$		-	-	$120\text{ ns}/(0.8473 \times C_B)$	
$t_{HD;STA}$	Hold time (repeated) Start condition	$f_{SCL}\leq 100\text{ kHz}$		4.0	-	-	μs
		$f_{SCL}\leq 400\text{ kHz}$		0.6	-	-	
		$f_{SCL}\leq 1\text{ MHz}$		0.26	-	-	

ATmega4809 – 40-pin Electrical Characteristics

.....continued

Symbol⁽¹⁾	Description	Condition	Min.	Typ.	Max.	Unit
t_{LOW}	Low period of SCL Clock	$f_{SCL} \leq 100 \text{ kHz}$	4.7	-	-	μs
		$f_{SCL} \leq 400 \text{ kHz}$	1.3	-	-	
		$f_{SCL} \leq 1 \text{ MHz}$	0.5	-	-	
t_{HIGH}	High period of SCL Clock	$f_{SCL} \leq 100 \text{ kHz}$	4.0	-	-	μs
		$f_{SCL} \leq 400 \text{ kHz}$	0.6	-	-	
		$f_{SCL} \leq 1 \text{ MHz}$	0.26	-	-	
$t_{SU;STA}$	Setup time for a repeated Start condition	$f_{SCL} \leq 100 \text{ kHz}$	4.7	-	-	μs
		$f_{SCL} \leq 400 \text{ kHz}$	0.6	-	-	
		$f_{SCL} \leq 1 \text{ MHz}$	0.26	-	-	
$t_{HD;DAT}$	Data hold time	$f_{SCL} \leq 100 \text{ kHz}$	0	-	3.45	μs
		$f_{SCL} \leq 400 \text{ kHz}$	0	-	0.9	
		$f_{SCL} \leq 1 \text{ MHz}$	0	-	0.45	
$t_{SU;DAT}$	Data setup time	$f_{SCL} \leq 100 \text{ kHz}$	250	-	-	ns
		$f_{SCL} \leq 400 \text{ kHz}$	100	-	-	
		$f_{SCL} \leq 1 \text{ MHz}$	50	-	-	
$t_{SU;STO}$	Setup time for Stop condition	$f_{SCL} \leq 100 \text{ kHz}$	4	-	-	μs
		$f_{SCL} \leq 400 \text{ kHz}$	0.6	-	-	
		$f_{SCL} \leq 1 \text{ MHz}$	0.26	-	-	
t_{BUF}	Bus free time between a Stop and Start condition	$f_{SCL} \leq 100 \text{ kHz}$	4.7	-	-	μs
		$f_{SCL} \leq 400 \text{ kHz}$	1.3	-	-	
		$f_{SCL} \leq 1 \text{ MHz}$	0.5	-	-	

Note:

- These parameters are for design guidance only and are not production tested.

4.14 VREF

Table 4-20. Internal Voltage Reference Characteristics

Symbol⁽¹⁾	Description	Min.	Typ.	Max.	Unit
t_{start}	Start-up time	-	25	-	μs

ATmega4809 – 40-pin Electrical Characteristics

.....continued

Symbol ⁽¹⁾	Description	Min.	Typ.	Max.	Unit
V _{DD}	Power supply voltage range for 0V55	1.8	-	5.5	V
	Power supply voltage range for 1V1	1.8	-	5.5	
	Power supply voltage range for 1V5	1.8	-	5.5	
	Power supply voltage range for 2V5	3.0	-	5.5	
	Power supply voltage range for 4V3	4.8	-	5.5	

Note:

- These parameters are for design guidance only and are not production tested.

Table 4-21. ADC Internal Voltage Reference Characteristics⁽¹⁾

Symbol ⁽²⁾	Description	Condition	Min.	Typ.	Max.	Unit
1V1	Internal reference voltage	V _{DD} =[1.8V, 5.5V] T=[0 - 105]°C	-2.0		2.0	%
0V55 1V5 2V5 4V3	Internal reference voltage	V _{DD} =[1.8V, 5.5V] T=[0 - 105]°C	-3.0		3.0	
0V55 1V1 1V5 2V5 4V3	Internal reference voltage	V _{DD} =[1.8V, 5.5V] T=[-40 - 125]°C	-5.0		5.0	

Note:

- These values are based on characterization and not covered by production test limits.
- The symbols xxxx refer to the respective values of the ADC0REFSEL bit field in the VREF.CTRLA register.

Table 4-22. AC Internal Voltage Reference Characteristics⁽¹⁾

Symbol ⁽²⁾	Description	Condition	Min.	Typ.	Max.	Unit
0V55 1V1 1V5 2V5	Internal reference voltage	V _{DD} =[1.8V, 5.5V] T=[0 - 105]°C	-3.0		3.0	%
0V55 1V1 1V5 2V5 4V3	Internal reference voltage	V _{DD} =[1.8V, 5.5V] T=[-40 - 125]°C	-5.0		5.0	

Note:

1. These values are based on characterization and not covered by production test limits.
2. The symbols xxxx refer to the respective values of the AC0REFSEL bit field in the VREF.CTRLA register.

4.15 ADC

4.15.1 Internal Reference Characteristics

Operating conditions:

- $V_{DD} = 1.8$ to $5.5V$
- Temperature = -40°C to 125°C
- DUTYCYC = 25%
- $\text{CLK}_{\text{ADC}} = 13 * f_{\text{ADC}}$
- SAMPCAP is 10 pF for 0.55V reference, while it is set to 5 pF for $V_{\text{REF}} \geq 1.1V$
- Applies for all allowed combinations of V_{REF} selections and Sample Rates unless otherwise noted

Table 4-23. Power Supply, Reference, and Input Range

Symbol	Description	Conditions	Min.	Typ.	Max.	Unit
V_{DD}	Supply voltage	$\text{CLK}_{\text{ADC}} \leq 1.5$ MHz	1.8	-	5.5	V
		$\text{CLK}_{\text{ADC}} > 1.5$ MHz	2.7	-	5.5	
V_{REF}	Reference voltage	REFSEL = Internal reference	0.55	-	$V_{DD}-0.5$	V
		REFSEL = External reference	1.1	-	V_{DD}	
		REFSEL = V_{DD}	1.8	-	5.5	
C_{IN}	Input capacitance	SAMPCAP=5 pF	-	5	-	pF
		SAMPCAP=10 pF	-	10	-	
V_{IN}	Input voltage range		0	-	V_{REF}	V
I_{BAND}	Input bandwidth	$1.1V \leq V_{\text{REF}}$	-	-	57.5	kHz

Table 4-24. Clock and Timing Characteristics⁽¹⁾

Symbol	Description	Conditions	Min.	Typ.	Max.	Unit
f_{ADC}	Sample rate	$1.1V \leq V_{\text{REF}}$	15	-	115	ksps
		$1.1V \leq V_{\text{REF}}$ (8-bit resolution)	15	-	150	
		$V_{\text{REF}}=0.55V$ (10 bits)	7.5	-	20	
CLK_{ADC}	Clock frequency	$V_{\text{REF}}=0.55V$ (10 bits)	100	-	260	kHz
		$1.1V \leq V_{\text{REF}}$ (10 bits)	200	-	1500	
		$1.1V \leq V_{\text{REF}}$ (8-bit resolution)	200	-	2000	
T_s	Sampling time		2	2	33	CLK_{ADC} cycles
T_{CONV}	Conversion time (latency)	Sampling time = 2 CLK_{ADC}	8.7	-	50	μs

.....continued

Symbol	Description	Conditions	Min.	Typ.	Max.	Unit
T _{START}	Start-up time	Internal V _{REF}	-	22	-	μs

Note:

- These parameters are for design guidance only and are not production tested.

Table 4-25. Accuracy Characteristics Internal Reference⁽²⁾

Symbol	Description	Conditions	Min.	Typ.	Max.	Unit
Res	Resolution		-	10	-	bit
INL	Integral Non-linearity	REFSEL = INTERNAL V _{REF} =0.55V	f _{ADC} =7.7 ksps	-	1.0	-
		REFSEL = INTERNAL or VDD	f _{ADC} =15 ksps	-	1.0	-
		REFSEL = INTERNAL or VDD 1.1V≤V _{REF}	f _{ADC} =77 ksps f _{ADC} =115 ksps	-	1.0 1.2	-
DNL ⁽¹⁾	Differential Non-linearity	REFSEL = INTERNAL V _{REF} = 0.55V	f _{ADC} =7.7 ksps	-	0.6	-
		REFSEL = INTERNAL V _{REF} = 1.1V	f _{ADC} =15 ksps	-	0.4	-
		REFSEL = INTERNAL or VDD 1.5V≤V _{REF}	f _{ADC} =15 ksps	-	0.4	-
		REFSEL = INTERNAL or VDD 1.1V≤V _{REF}	f _{ADC} =77 ksps	-	0.4	-
		REFSEL = INTERNAL 1.1V≤V _{REF}	f _{ADC} =115 ksps	-	0.5	-
		REFSEL = VDD 1.8V≤V _{REF}	f _{ADC} =115 ksps	-	0.9	-

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.....continued

Symbol	Description	Conditions		Min.	Typ.	Max.	Unit
EABS	Absolute accuracy	REFSEL = INTERNAL $V_{REF} = 1.1V$	T=[0-105]°C $V_{DD} = [1.8V-3.6V]$	-	<10	-	LSB
			$V_{DD} = [1.8V-3.6V]$	-	<15	-	
		REFSEL = V_{DD}		-	2.5	-	
		REFSEL = INTERNAL		-	<35	-	
EGAIN	Gain error	REFSEL = INTERNAL $V_{REF} = 1.1V$	T=[0-105]°C $V_{DD} = [1.8V-3.6V]$	-	±15	-	LSB
			$V_{DD} = [1.8V-3.6V]$	-	±20	-	
		REFSEL = V_{DD}		-	2	-	
		REFSEL = INTERNAL		-	±35	-	
EOFF	Offset error	REFSEL = INTERNAL $V_{REF} = 0.55V$		-	-1	-	LSB
				-	-0.5	-	
		REFSEL = INTERNAL $1.1V \leq V_{REF}$		-	-	-	

Note:

1. A DNL error of less than or equal to 1 LSB ensures a monotonic transfer function with no missing codes.
2. These parameters are for design guidance only and are not production tested.
3. Reference setting and f_{ADC} must fulfill the specification in “Clock and Timing Characteristics” and “Power supply, Reference, and Input Range” tables.

4.15.2 External Reference Characteristics

Operating conditions:

- $V_{DD} = 1.8$ to $5.5V$
- Temperature = $-40^{\circ}C$ to $125^{\circ}C$
- DUTYCYC = 25%
- $CLK_{ADC} = 13 * f_{ADC}$
- SAMPCAP is 5 pF

The accuracy characteristics numbers are based on the characterization of the following input reference levels and V_{DD} ranges:

- $V_{ref} = 1.8V$, $V_{DD} = 1.8$ to $5.5V$
- $V_{ref} = 2.6V$, $V_{DD} = 2.7$ to $5.5V$
- $V_{ref} = 4.096V$, $V_{DD} = 4.5$ to $5.5V$

- $V_{ref} = 4.3V$, $V_{DD} = 4.5$ to $5.5V$

Table 4-26. ADC Accuracy Characteristics External Reference⁽²⁾

Symbol	Description	Conditions	Min.	Typ.	Max.	Unit
Res	Resolution		-	10	-	bit
INL	Integral Non-linearity	$f_{ADC}=15$ ksps	-	0.9	-	LSB
			-	0.9	-	
			-	1.2	-	
DNL ⁽¹⁾	Differential Non-linearity	$f_{ADC}=15$ ksps	-	0.2	-	LSB
			-	0.4	-	
			-	0.8	-	
EABS	Absolute accuracy	$f_{ADC}=15$ ksps	-	2	-	LSB
			-	2	-	
			-	2	-	
EGAIN	Gain error	$f_{ADC}=15$ ksps	-	2	-	LSB
			-	2	-	
			-	2	-	
EOFF	Offset error		-	-0.5	-	LSB

Note:

1. A DNL error of less than or equal to 1 LSB ensures a monotonic transfer function with no missing codes.
2. These parameters are for design guidance only and are not production tested.

4.16 AC

Table 4-27. Analog Comparator Characteristics, Low-Power Mode Disabled

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
V_{IN}	Input voltage		-0.2	-	V_{DD}	V
C_{IN}	Input pin capacitance	PD1 to PD6	-	3.5	-	pF
		PD7	-	14	-	
V_{OFF}	Input offset voltage	$0.7V < V_{IN} < (V_{DD}-0.7V)$	-20	± 5	+20	mV
		$V_{IN}=[-0.2V, V_{DD}]$	-40	± 20	+40	
I_L	Input leakage current		-	5	-	nA
T_{START}	Start-up time		-	1.3	-	μs

.....continued

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
V_{HYS}	Hysteresis	HYSMODE=0x0	-	0	-	mV
		HYSMODE=0x1	-	10	-	
		HYSMODE=0x2	-	25	-	
		HYSMODE=0x3	-	50	-	
t_{PD}	Propagation delay	25 mV Overdrive, $V_{DD} \geq 2.7V$	-	50	-	ns

Table 4-28. Analog Comparator Characteristics, Low-Power Mode Enabled

Symbol	Description	Condition	Min.	Typ.	Max.	Unit
V_{IN}	Input voltage		-0.2	-	V_{DD}	V
C_{IN}	Input pin capacitance	PD1 to PD6	-	3.5	-	pF
		PD7	-	14	-	
V_{OFF}	Input offset voltage	$0.7V < V_{IN} < (V_{DD} - 0.7V)$	-30	± 10	+30	mV
		$V_{IN} = [0V, V_{DD}]$	-50	± 30	+50	
I_L	Input leakage current		-	5	-	nA
T_{START}	Start-up time		-	1.3	-	μs
V_{HYS}	Hysteresis	HYSMODE=0x0	-	0	-	mV
		HYSMODE=0x1	-	10	-	
		HYSMODE=0x2	-	25	-	
		HYSMODE=0x3	-	50	-	
t_{PD}	Propagation delay	25 mV overdrive, $V_{DD} \geq 2.7V$	-	150	-	ns

4.17 UPDI Timing

UPDI Enable Sequence ⁽¹⁾

Symbol	Description	Min.	Max.	Unit
T_{RES}	Duration of Handshake/Break on RESET	10	200	μs
T_{UPDI}	Duration of UPDI.txd=0	10	200	μs
T_{Deb0}	Duration of Debugger.txd=0	0.2	1	μs
T_{DebZ}	Duration of Debugger.txd=z	200	14000	μs

Note:

- These parameters are for design guidance only and are not production tested.

4.18 Programming Time

See the table below for typical programming times for Flash and EEPROM.

Table 4-29. Programming Times

Symbol	Typical Programming Time
Page Buffer Clear	7 CLK_CPU cycles
Page Write	2 ms
Page Erase	2 ms
Page Erase-Write	4 ms
Chip Erase	4 ms
EEPROM Erase	4 ms

5. Typical Characteristics

5.1 Power Consumption

5.1.1 Supply Currents in Active Mode

Figure 5-1. Active Supply Current vs. Frequency (1-20 MHz) at T=25°C

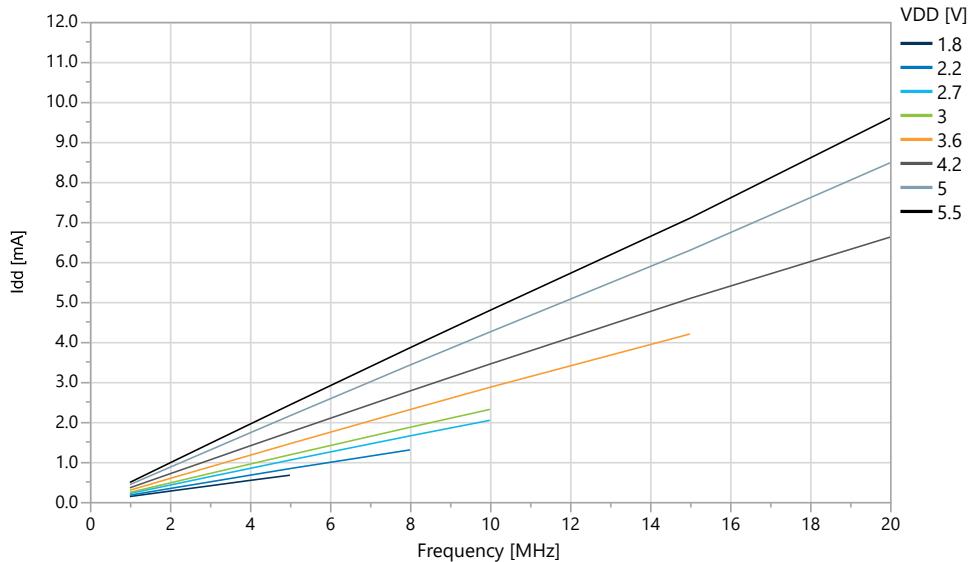
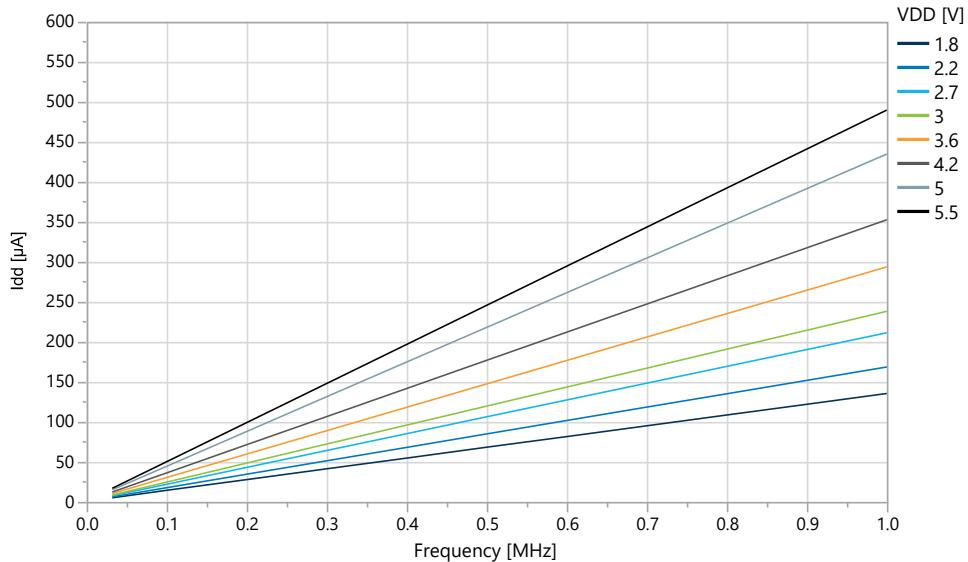


Figure 5-2. Active Supply Current vs. Frequency [0.1, 1.0] MHz at T=25°C



ATmega4809 – 40-pin Typical Characteristics

Figure 5-3. Active Supply Current vs. Temperature ($f=20$ MHz OSC20M)

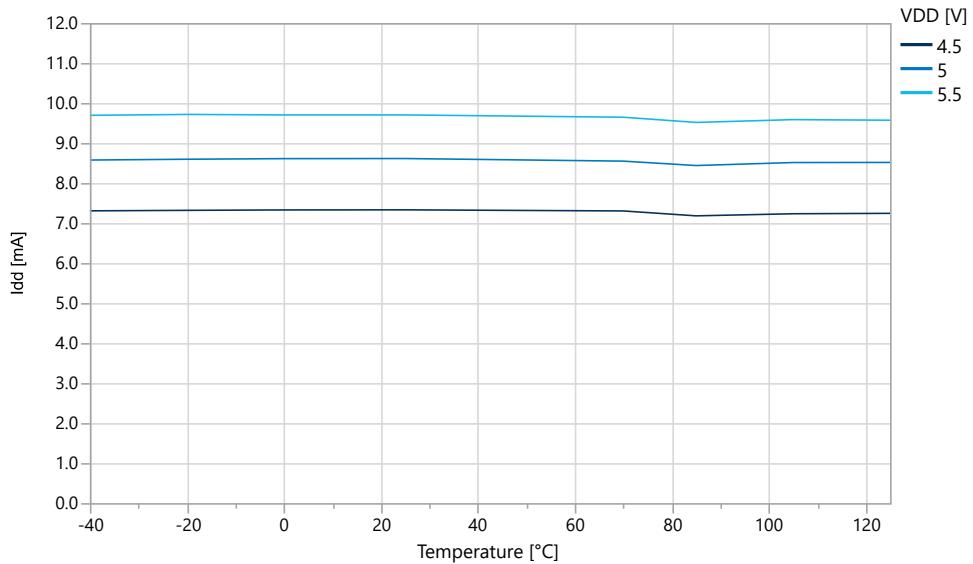


Figure 5-4. Active Supply Current vs. V_{DD} ($f=[1.25, 20]$ MHz OSC20M) at $T=25^\circ C$

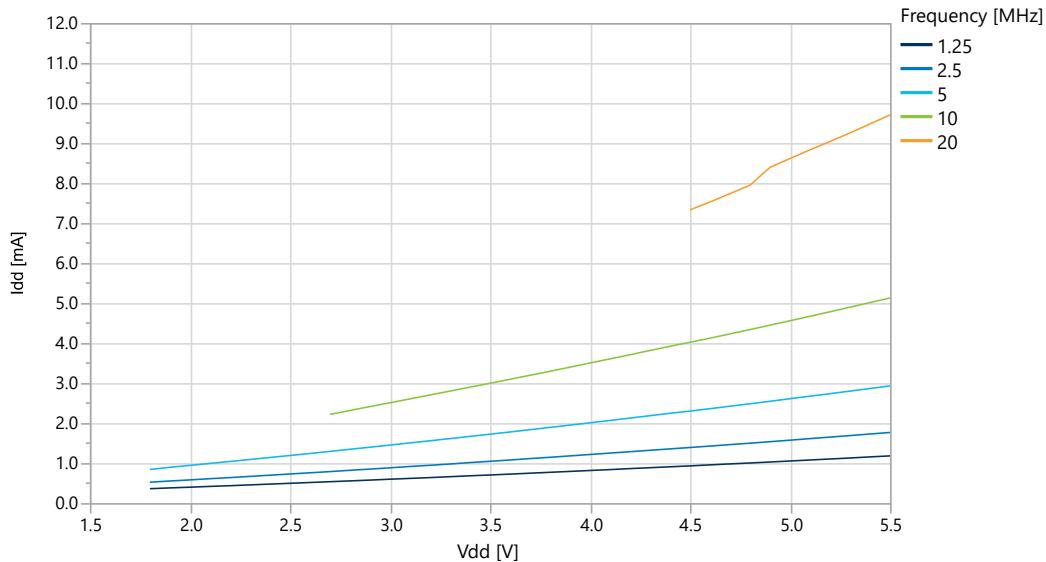
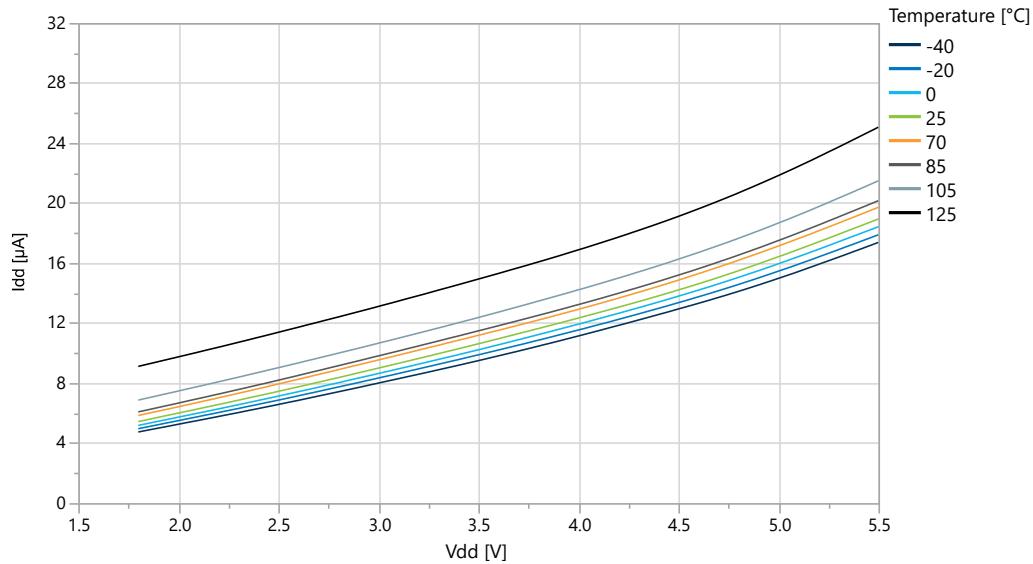
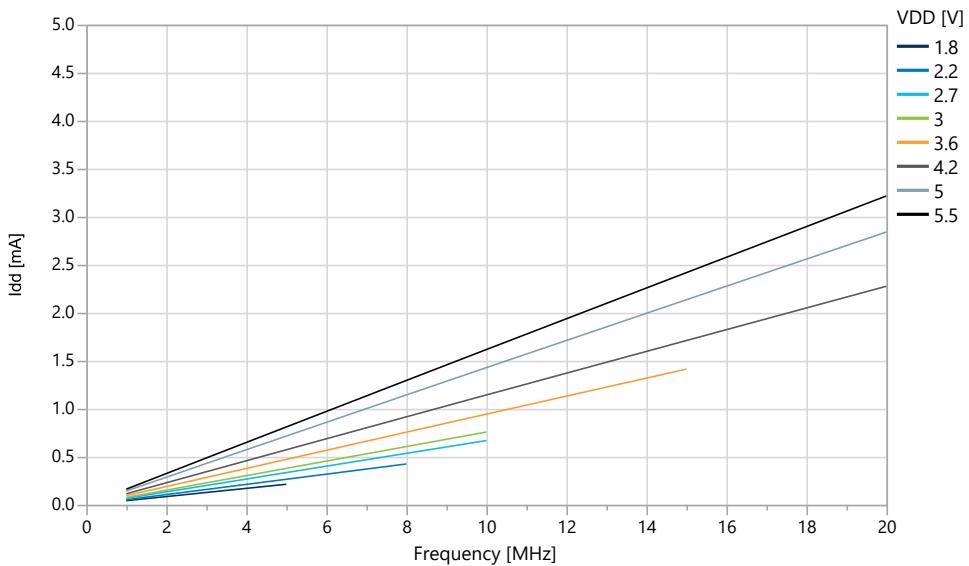


Figure 5-5. Active Supply Current vs. V_{DD} ($f=32.768$ kHz OSCULP32K)



5.1.2 Supply Currents in Idle Mode

Figure 5-6. Idle Supply Current vs. Frequency (1-20 MHz) at $T=25^\circ\text{C}$



ATmega4809 – 40-pin Typical Characteristics

Figure 5-7. Idle Supply Current vs. Low Frequency (0.1-1.0 MHz) at T=25°C

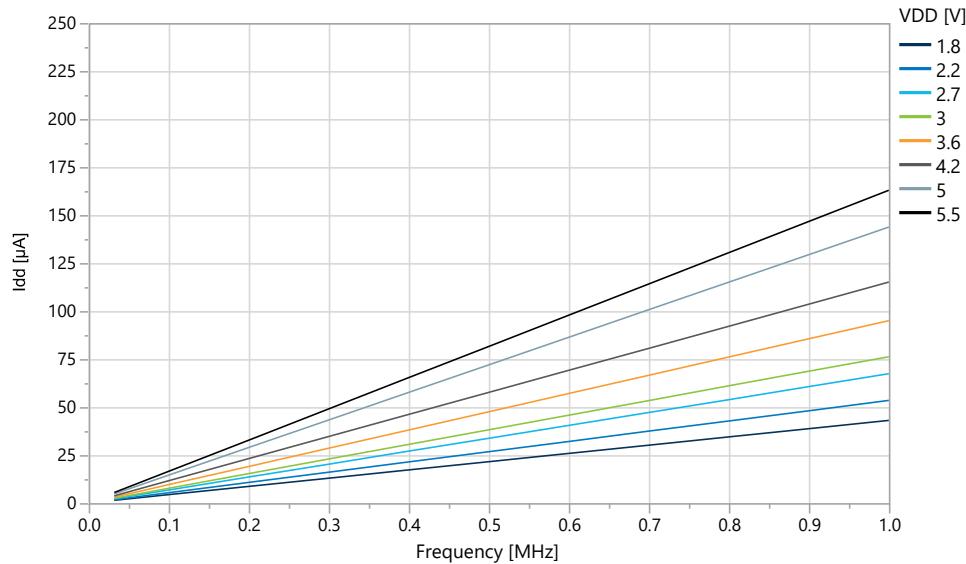


Figure 5-8. Idle Supply Current vs. Temperature (f=20 MHz OSC20M)

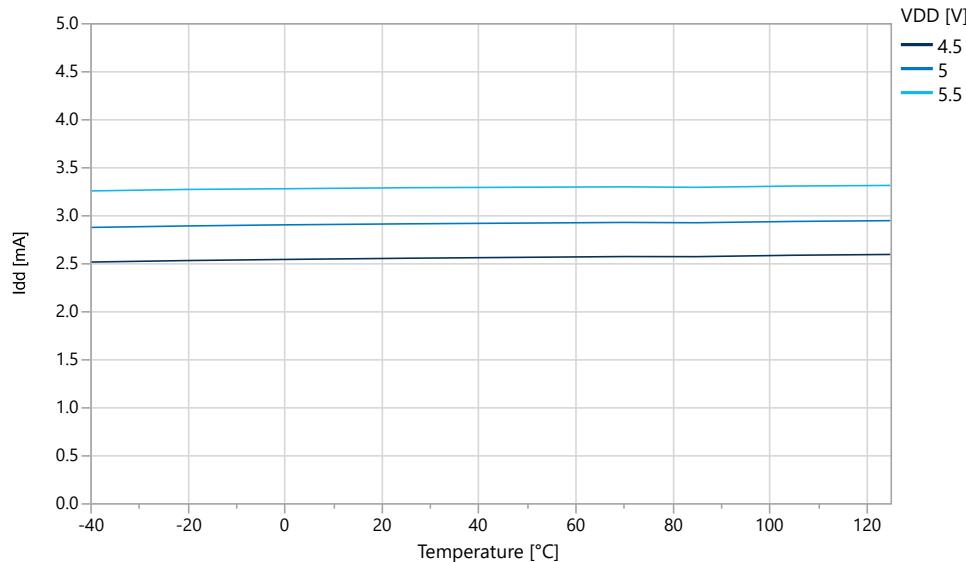
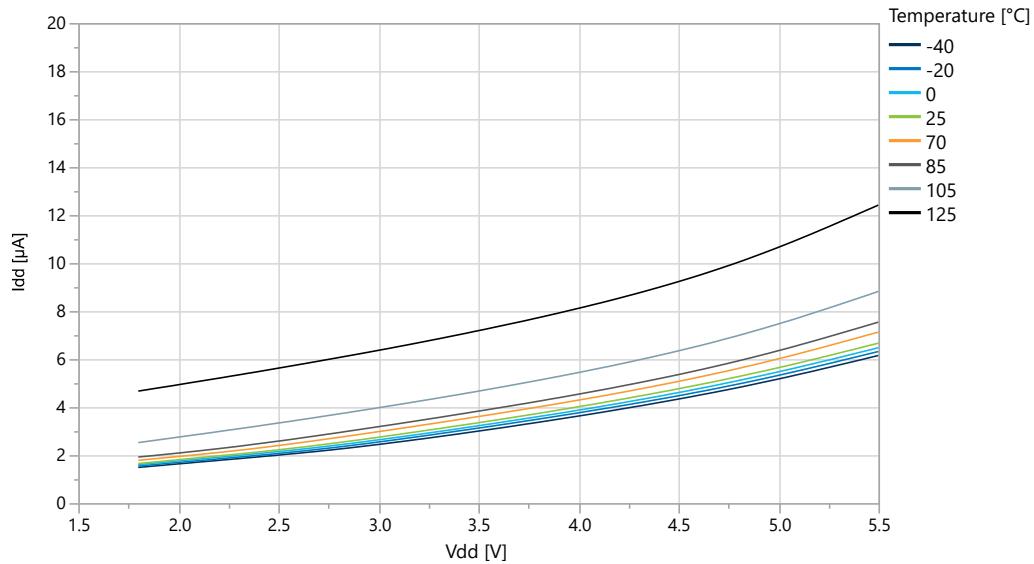


Figure 5-9. Idle Supply Current vs. V_{DD} ($f=32.768$ kHz OSCULP32K)



5.1.3 Supply Currents in Power-Down Mode

Figure 5-10. Power-Down Mode Supply Current vs. Temperature (all functions disabled)

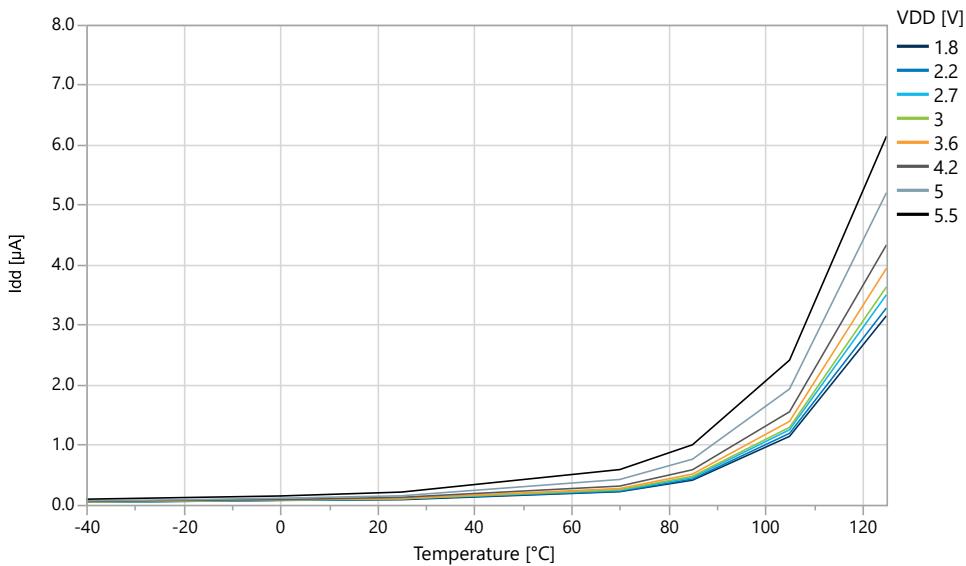


Figure 5-11. Power-Down Mode Supply Current vs. V_{DD} (all functions disabled)

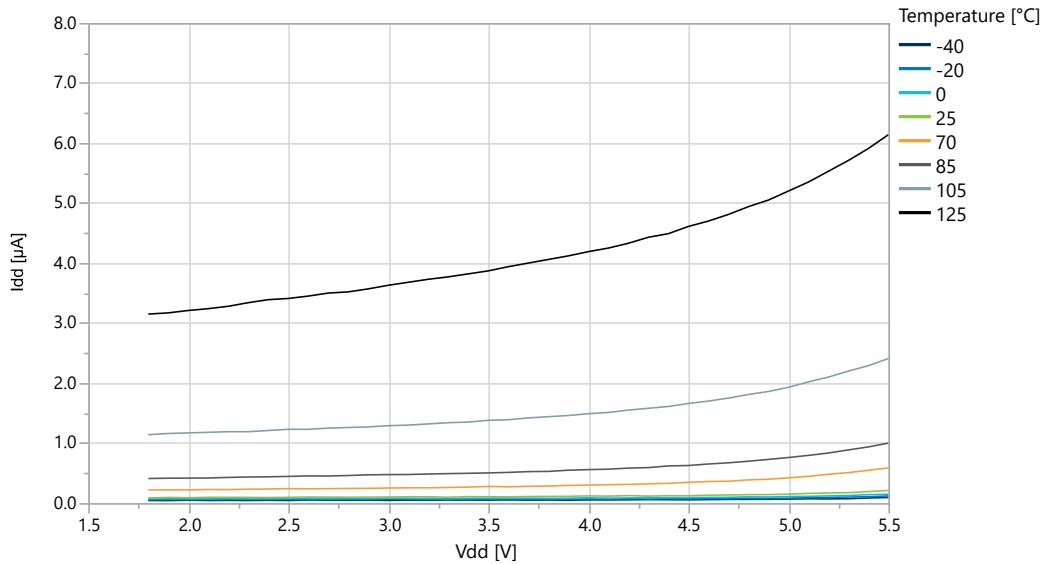
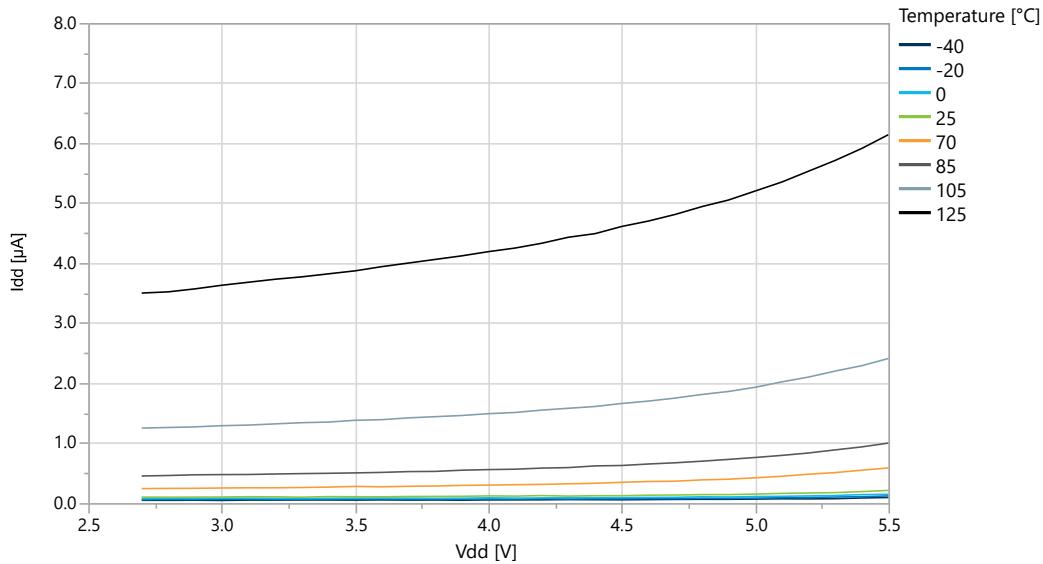


Figure 5-12. Power-Down Mode Supply Current vs. V_{DD} (all functions disabled)



5.1.4 Supply Currents in Standby Mode

Figure 5-13. Standby Mode Supply Current vs. V_{DD} (RTC running with internal OSCULP32K)

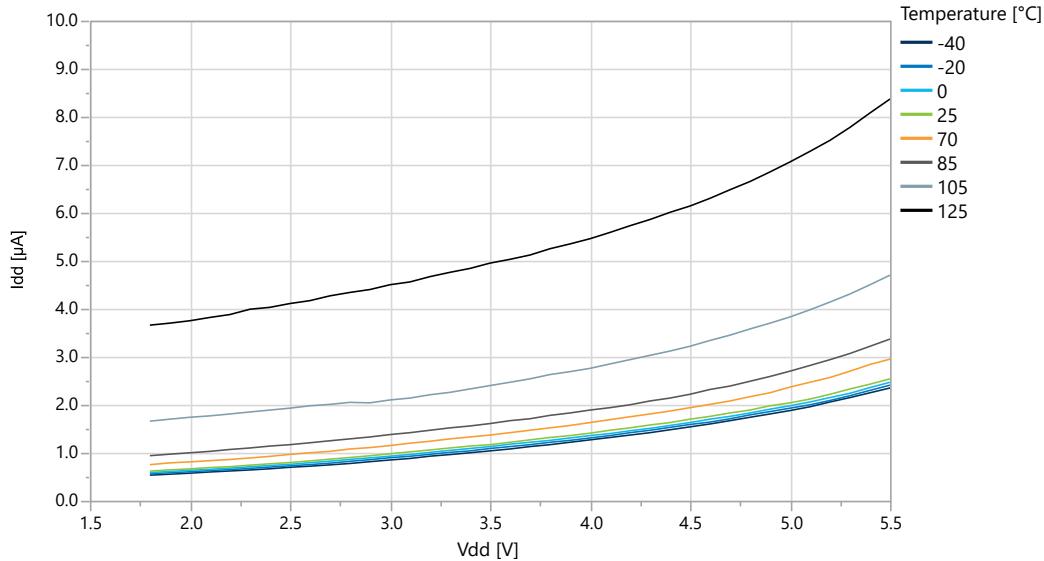


Figure 5-14. Standby Mode Supply Current vs. V_{DD} (Sampled BOD running at 125 Hz)

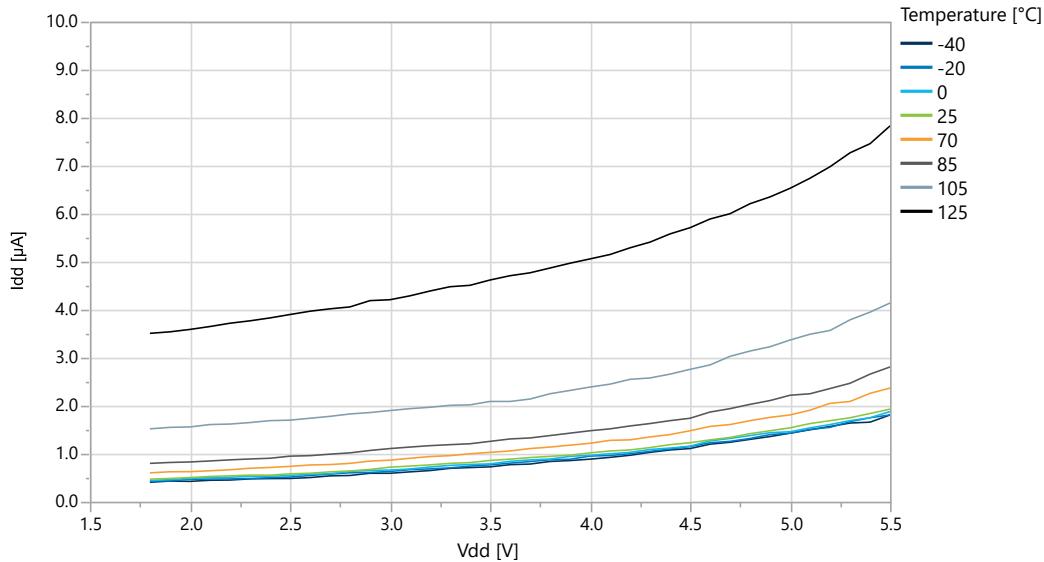
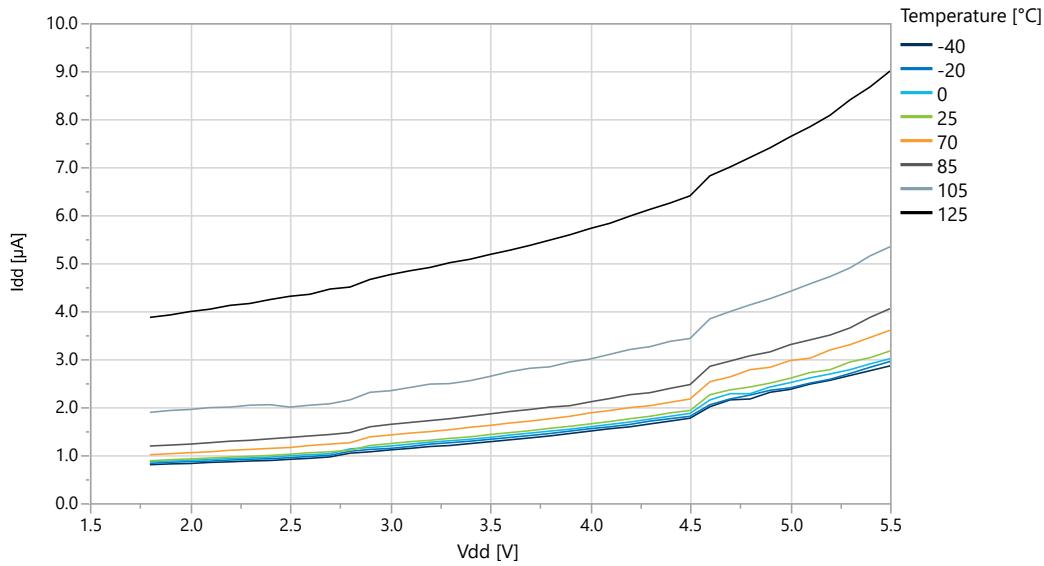
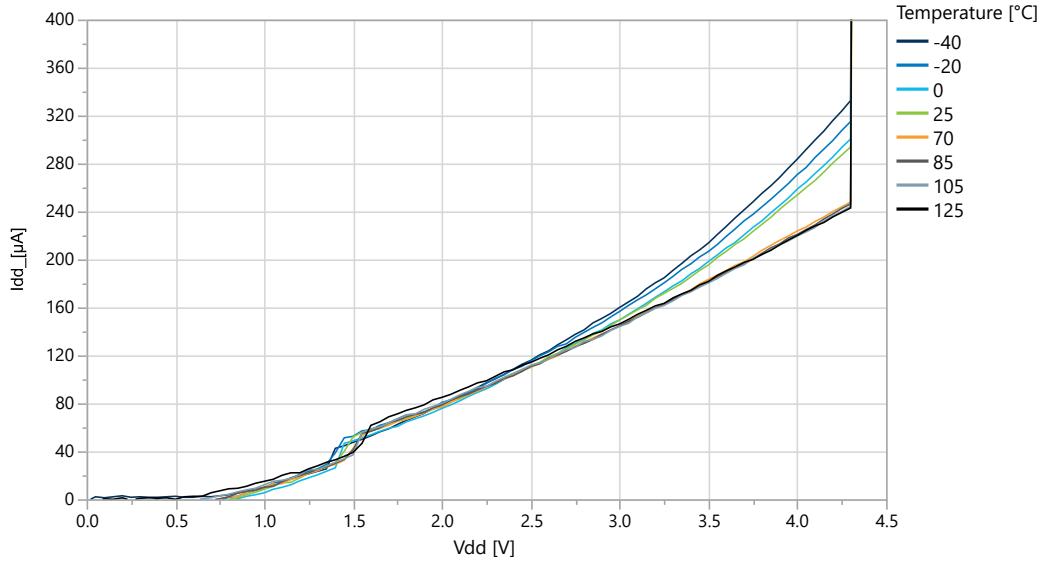


Figure 5-15. Standby Mode Supply Current vs. V_{DD} (Sampled BOD running at 1 kHz)



5.1.5 Power-on Supply Currents

Figure 5-16. Power-on Supply Current vs. V_{DD} (BOD enabled at 4.3V level)



5.2 GPIO

GPIO Input Characteristics

Figure 5-17. I/O Pin Input Hysteresis vs. V_{DD}

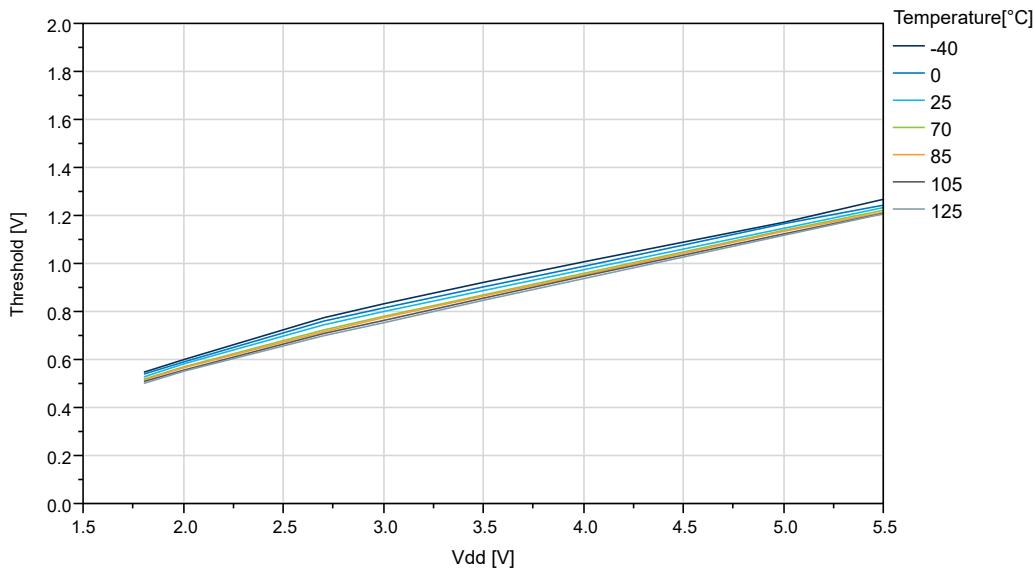


Figure 5-18. I/O Pin Input Threshold Voltage vs. V_{DD} ($T=25^{\circ}\text{C}$)

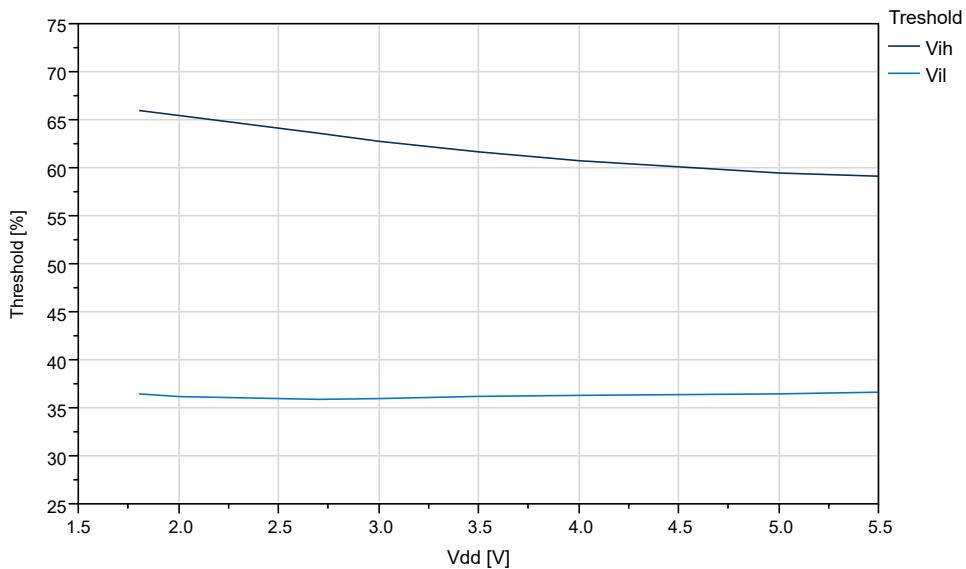


Figure 5-19. I/O Pin Input Threshold Voltage vs. V_{DD} (V_{IH})

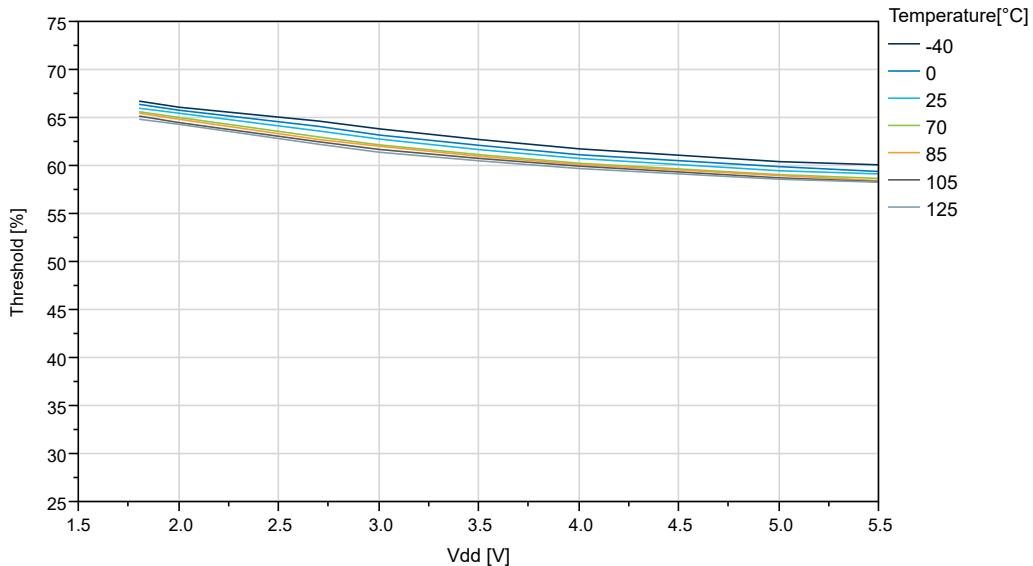
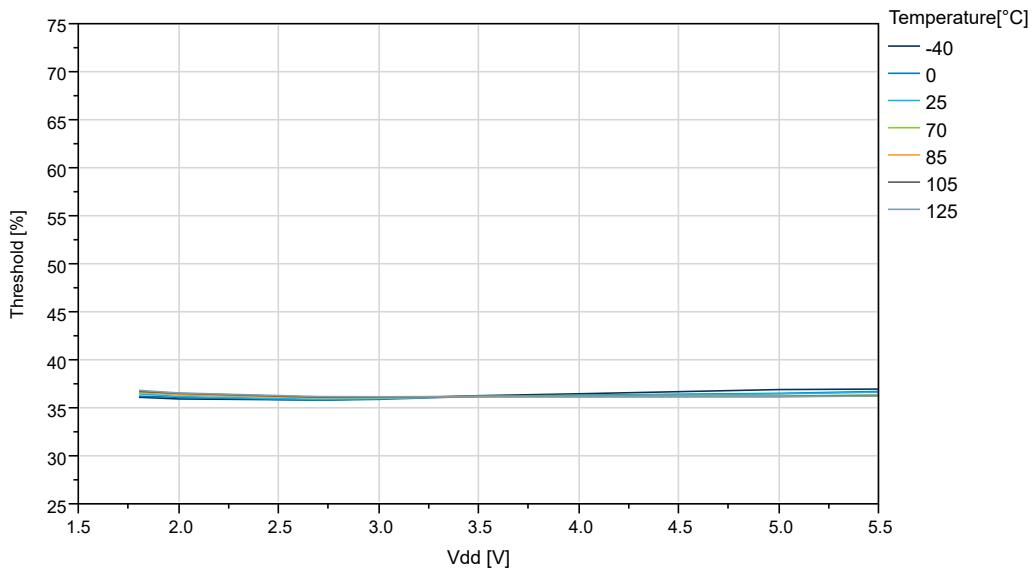


Figure 5-20. I/O Pin Input Threshold Voltage vs. V_{DD} (V_{IL})



GPIO Output Characteristics

Figure 5-21. I/O Pin Output Voltage vs. Sink Current ($V_{DD}=1.8V$)

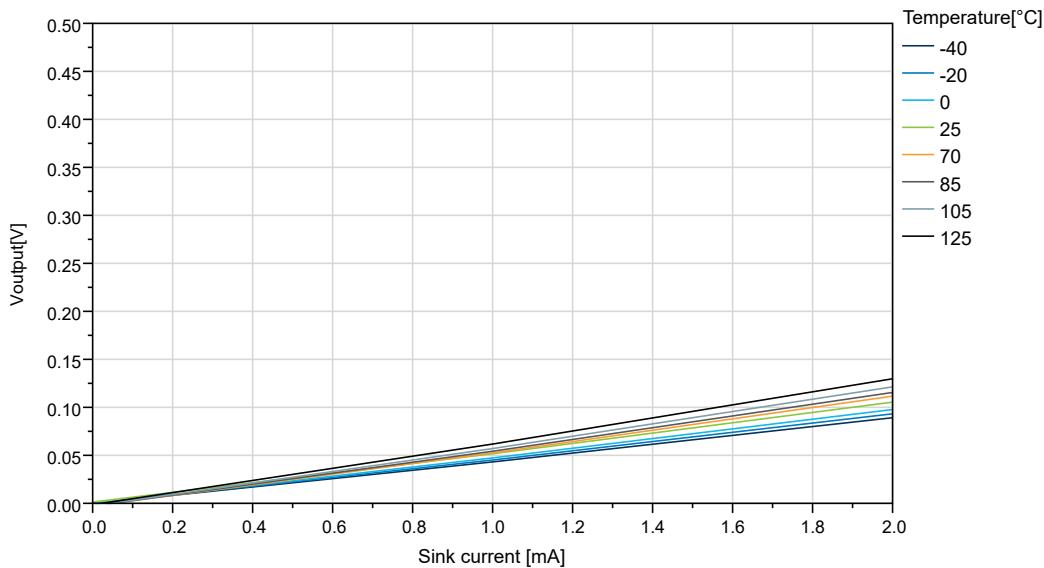
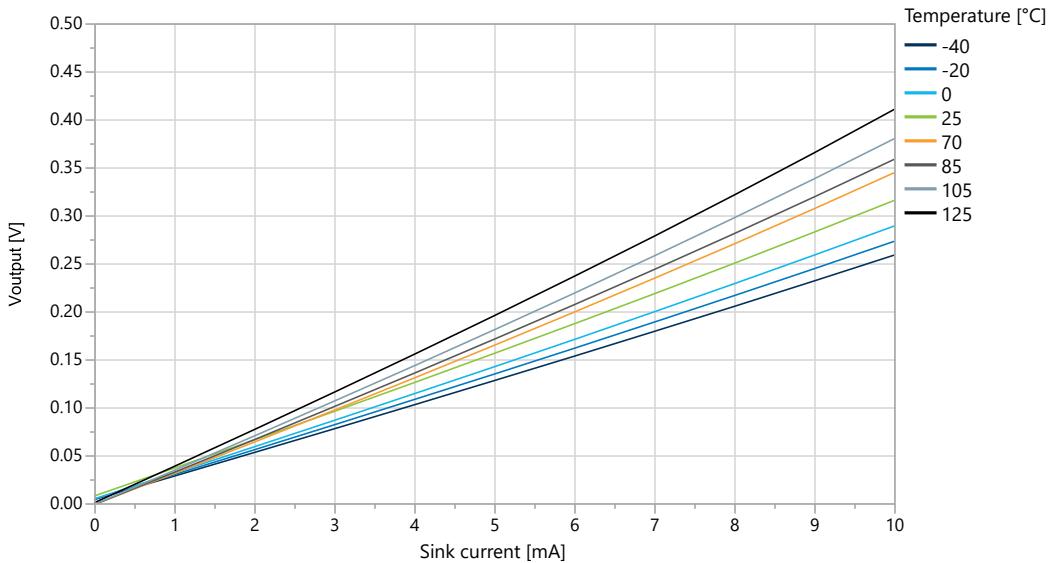


Figure 5-22. I/O Pin Output Voltage vs. Sink Current ($V_{DD}=3.0V$)



ATmega4809 – 40-pin Typical Characteristics

Figure 5-23. I/O Pin Output Voltage vs. Sink Current ($V_{DD}=5.0V$)

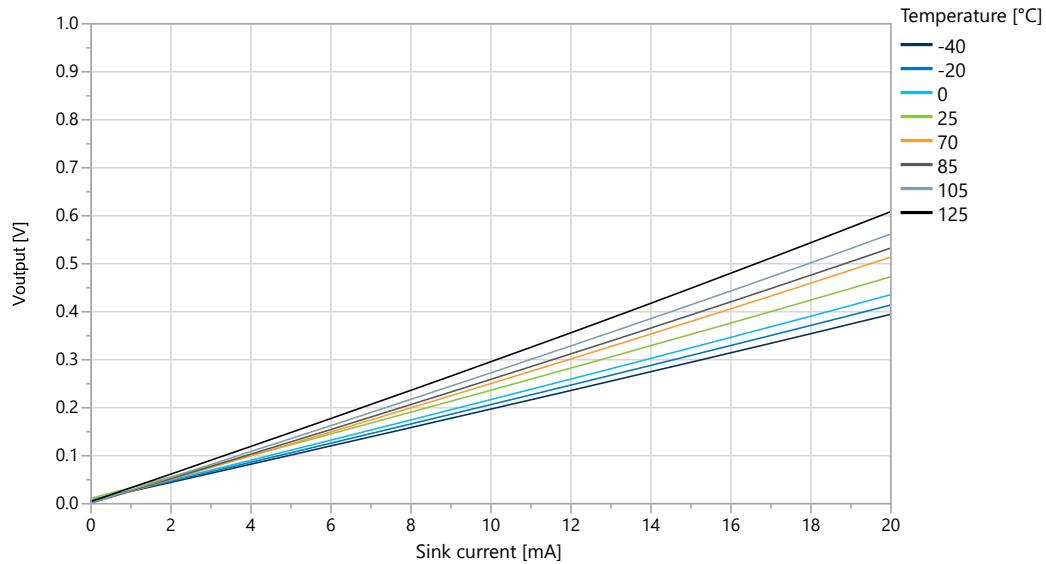
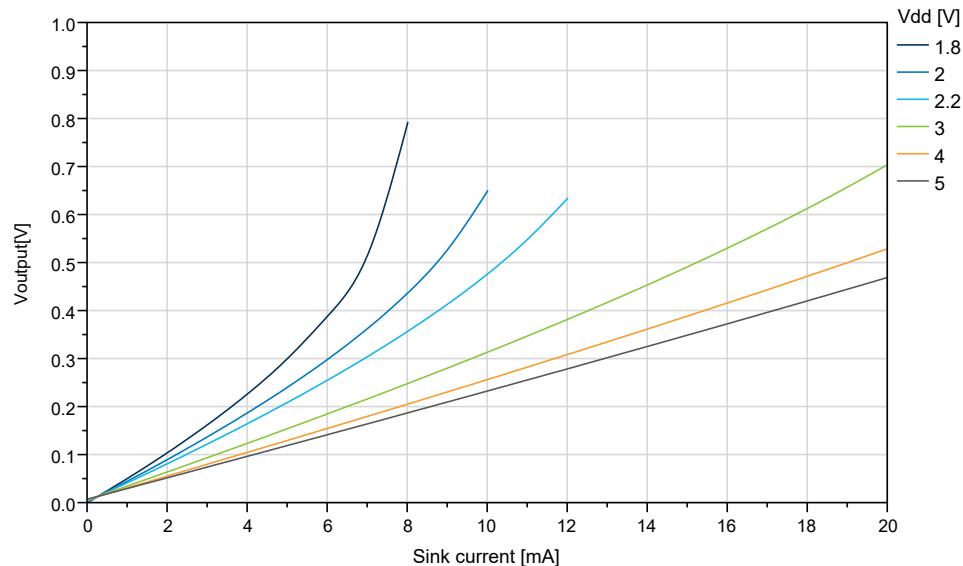


Figure 5-24. I/O Pin Output Voltage vs. Sink Current ($T=25^{\circ}C$)



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Figure 5-25. I/O Pin Output Voltage vs. Source Current ($V_{DD}=1.8V$)

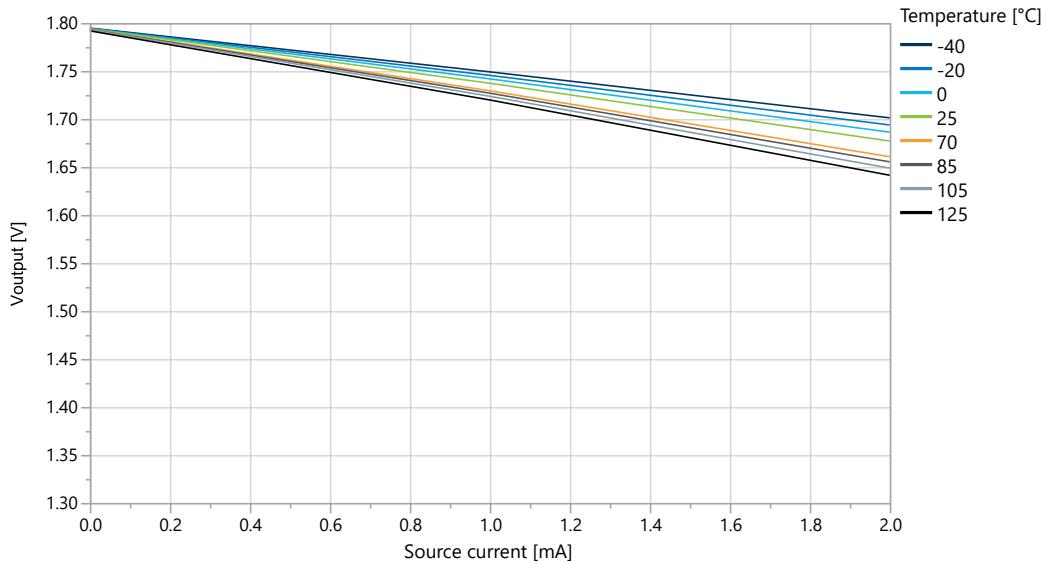


Figure 5-26. I/O Pin Output Voltage vs. Source Current ($V_{DD}=3.0V$)

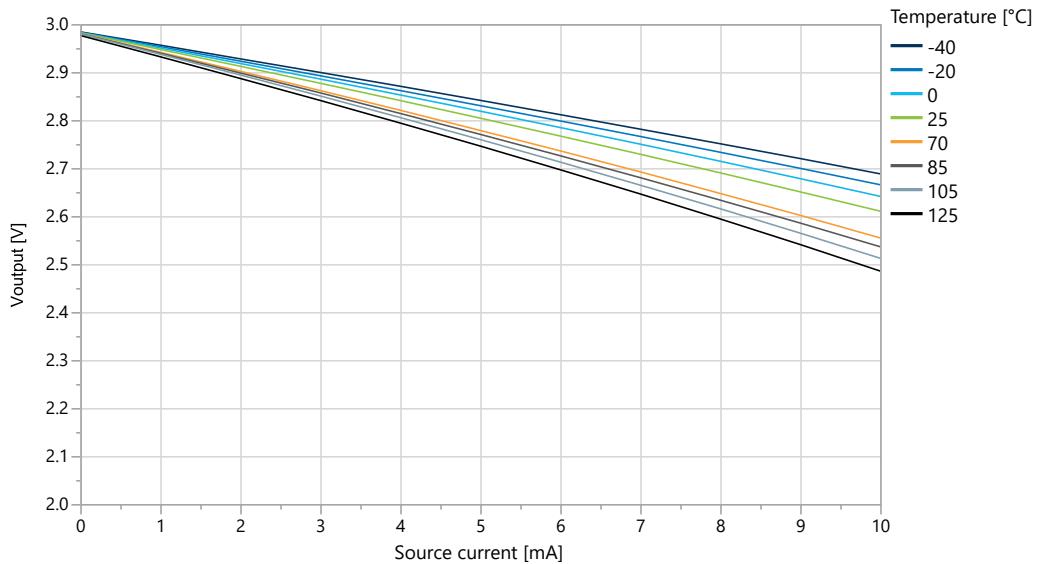


Figure 5-27. I/O Pin Output Voltage vs. Source Current ($V_{DD}=5.0V$)

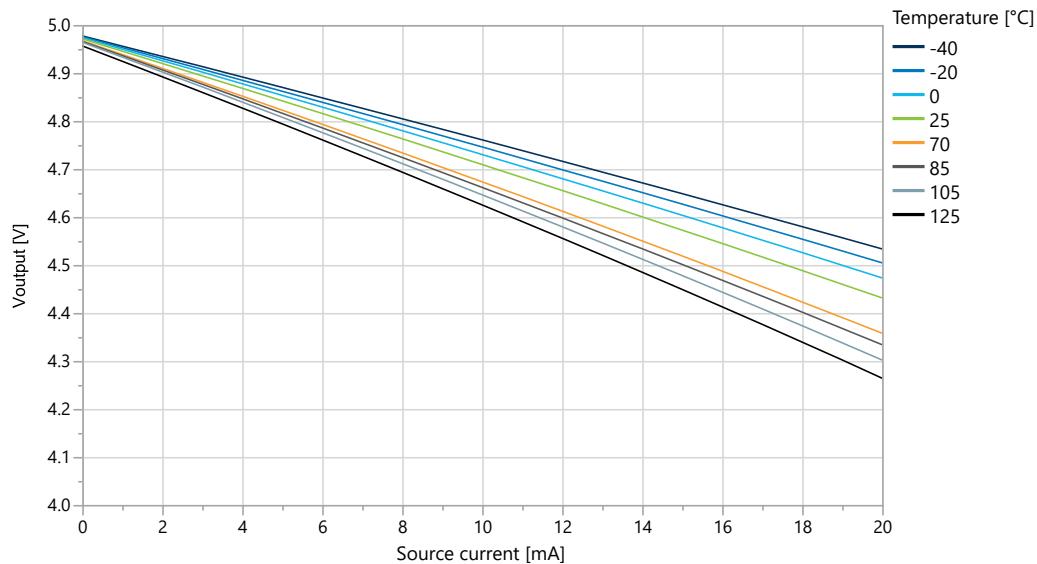
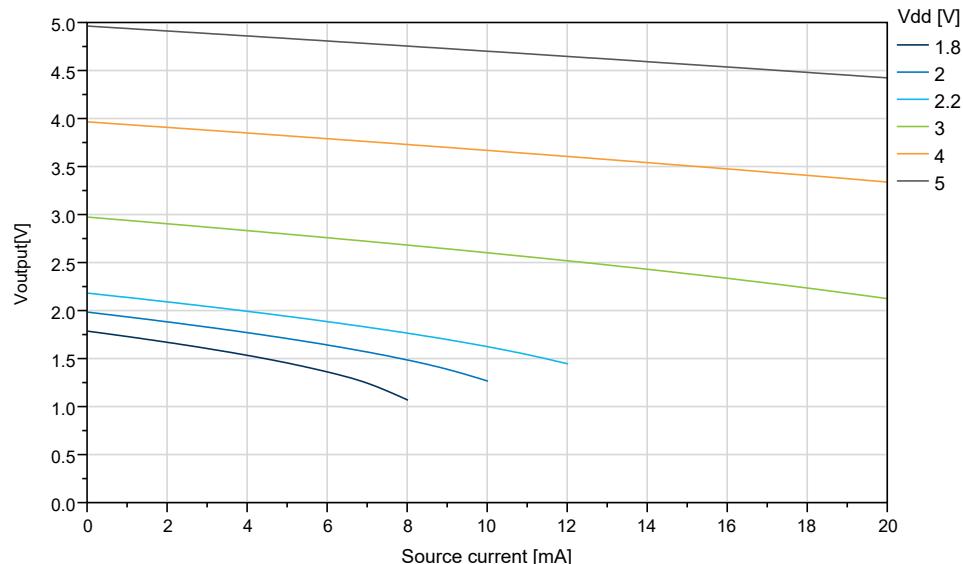


Figure 5-28. I/O Pin Output Voltage vs. Source Current (T=25°C)



GPIO Pull-Up Characteristics

Figure 5-29. I/O Pin Pull-Up Resistor Current vs. Input Voltage ($V_{DD}=1.8V$)

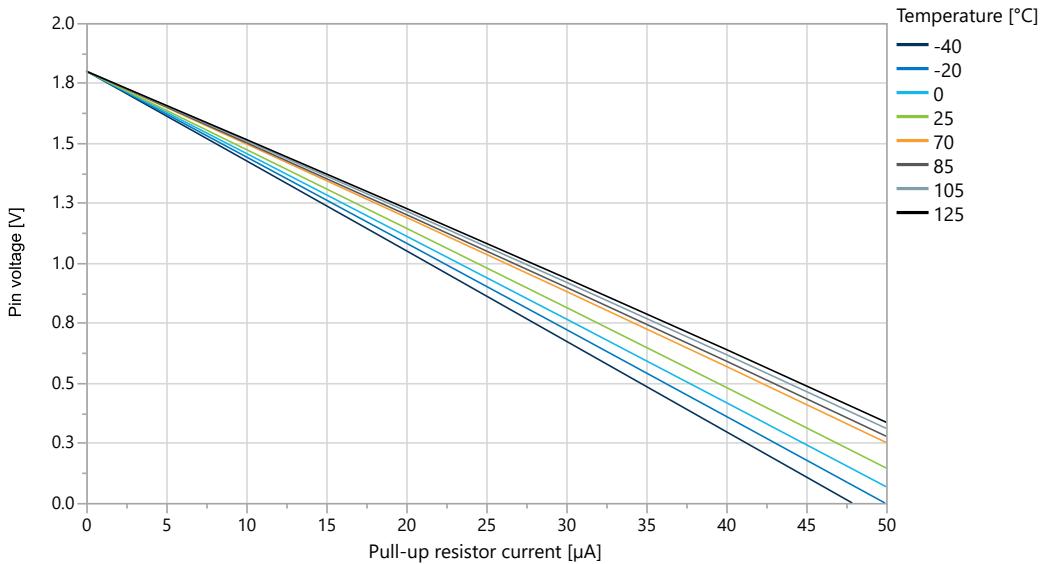


Figure 5-30. I/O Pin Pull-Up Resistor Current vs. Input Voltage ($V_{DD}=3.0V$)

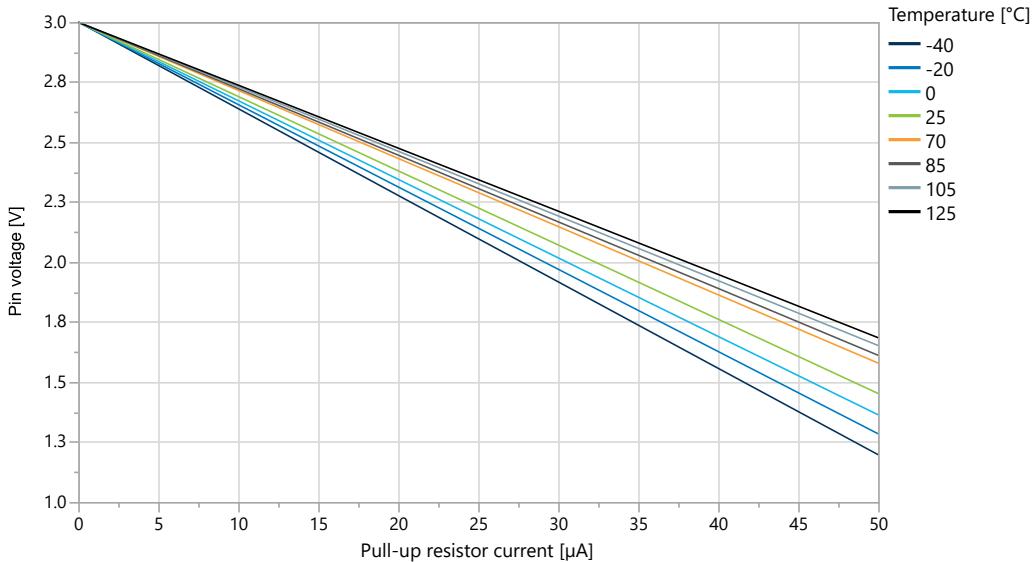
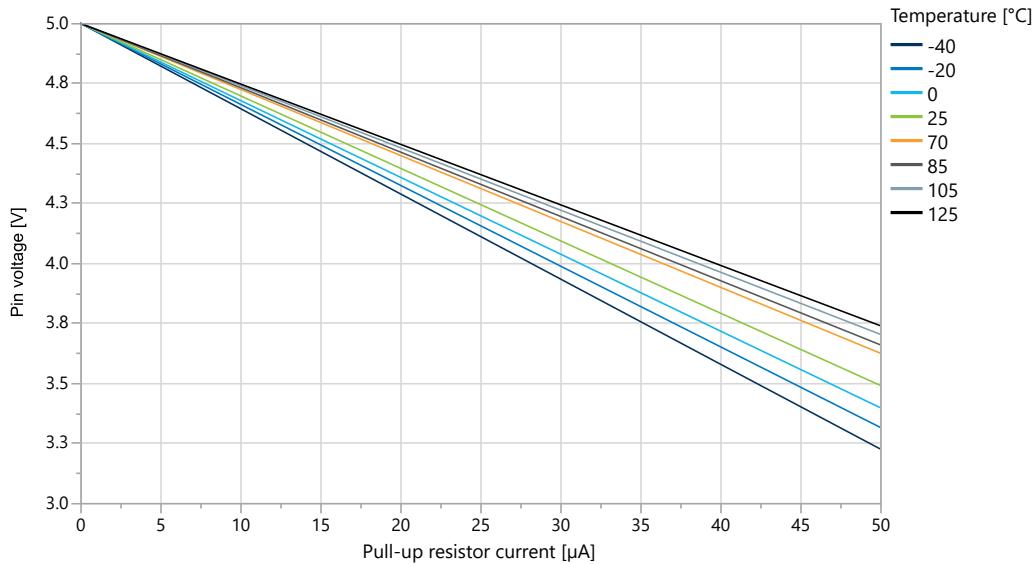


Figure 5-31. I/O Pin Pull-Up Resistor Current vs. Input Voltage ($V_{DD}=5.0V$)



5.3 VREF Characteristics

Figure 5-32. Internal 0.55V Reference vs. Temperature

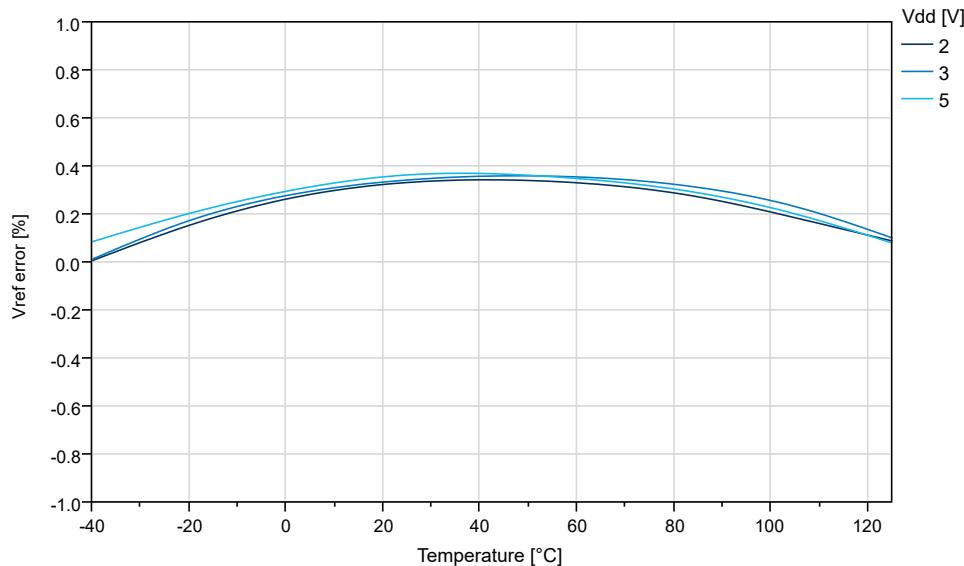


Figure 5-33. Internal 1.1V Reference vs. Temperature

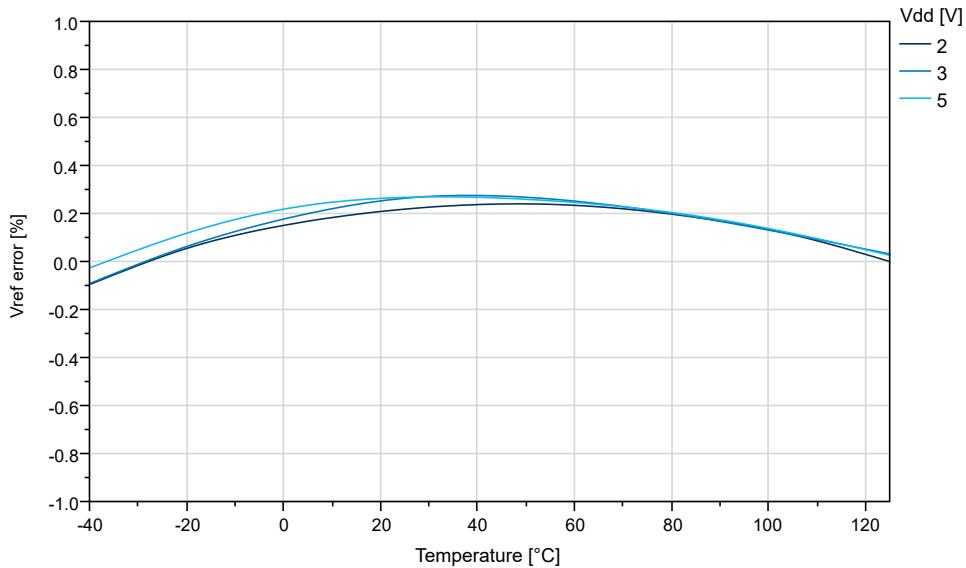


Figure 5-34. Internal 2.5V Reference vs. Temperature

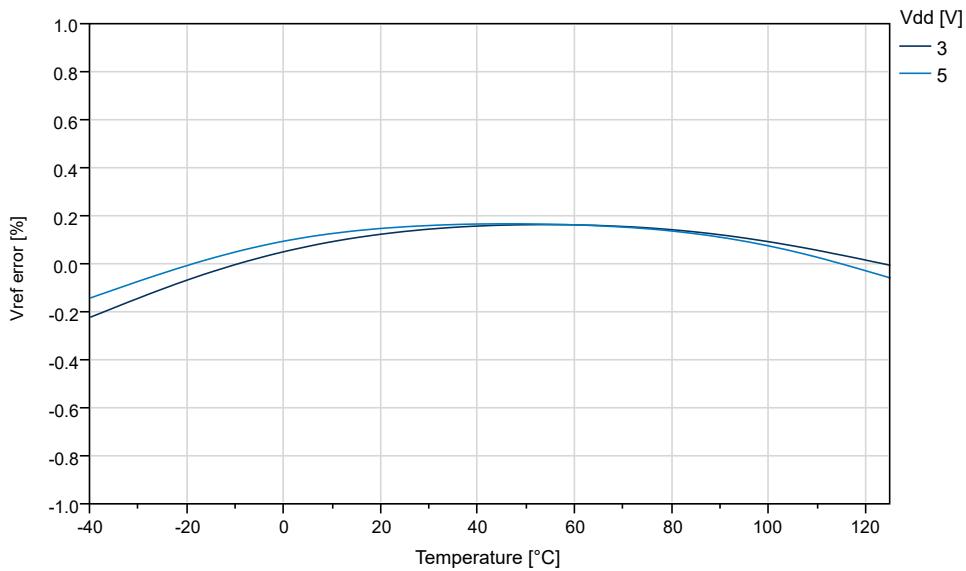
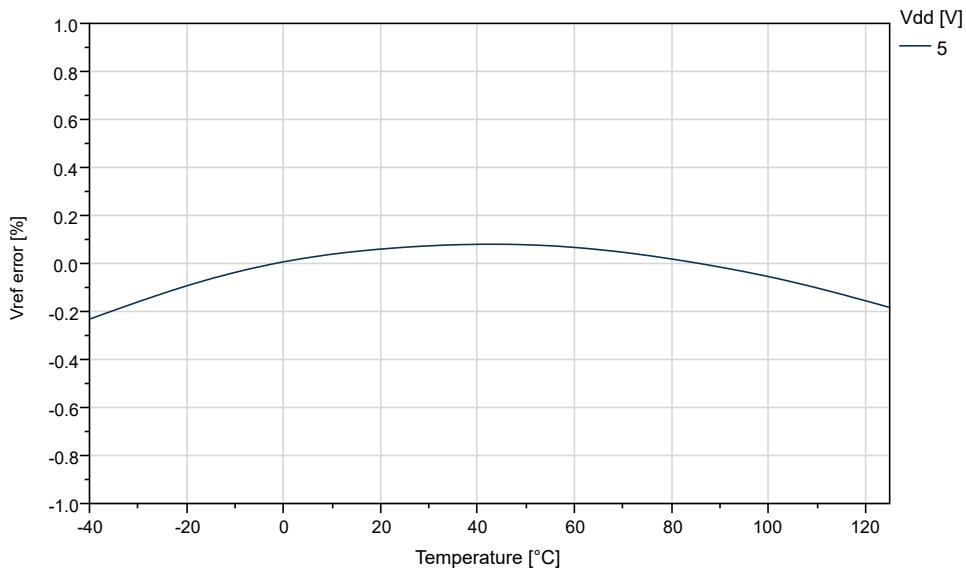


Figure 5-35. Internal 4.3V Reference vs. Temperature



5.4 BOD Characteristics

BOD Current vs. V_{DD}

Figure 5-36. BOD Current vs. V_{DD} (Continuous Mode Enabled)

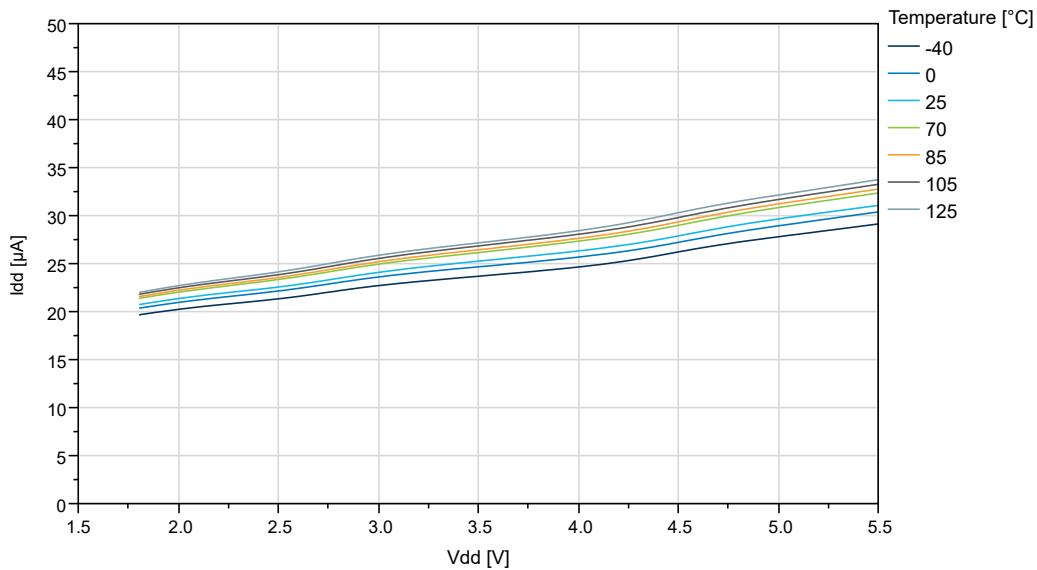


Figure 5-37. BOD Current vs. V_{DD} (Sampled BOD at 125 Hz)

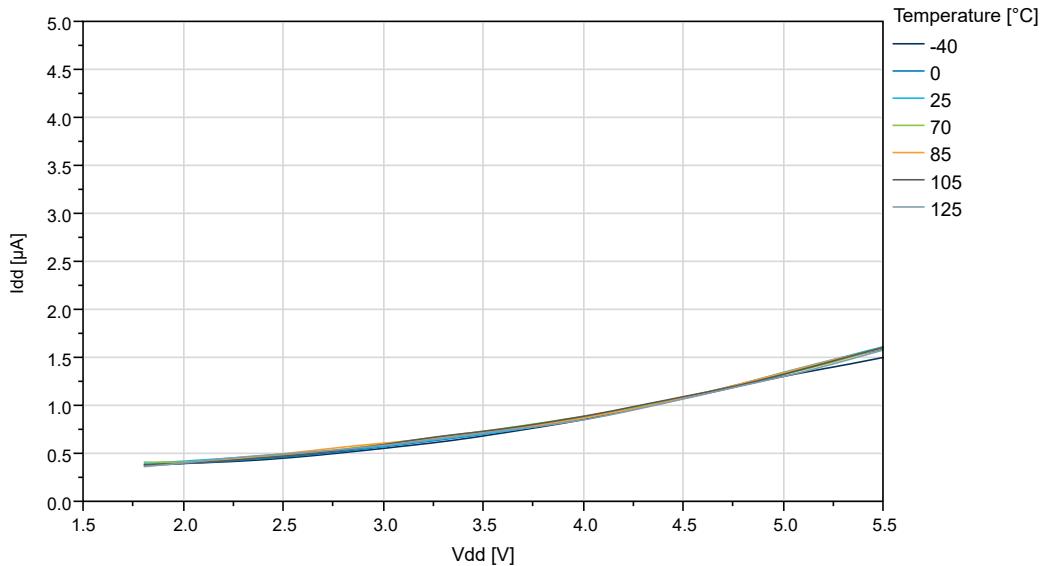
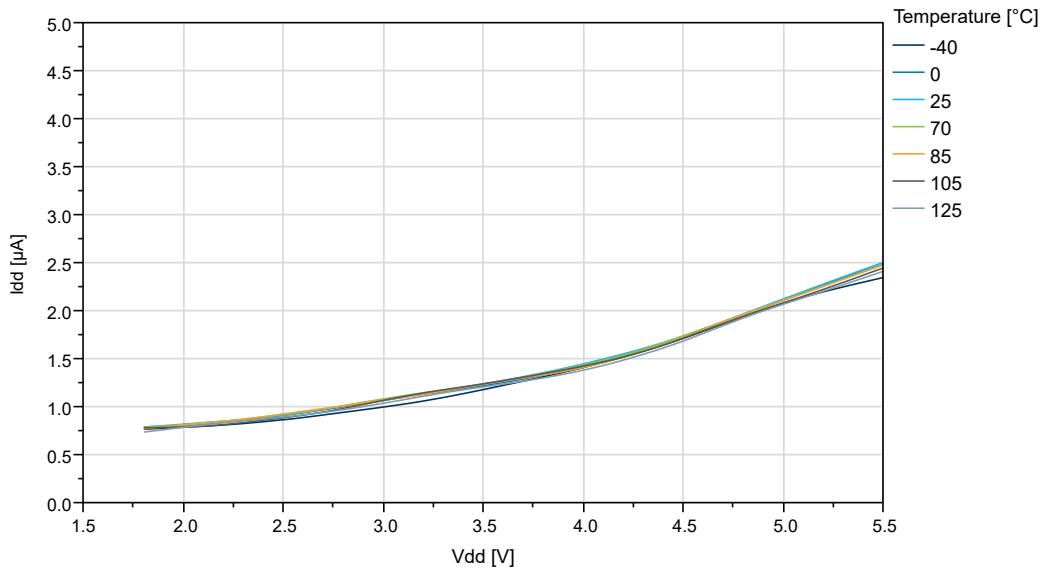


Figure 5-38. BOD Current vs. V_{DD} (Sampled BOD at 1 kHz)



BOD Threshold vs. Temperature

Figure 5-39. BOD Threshold vs. Temperature (Level 1.8V)

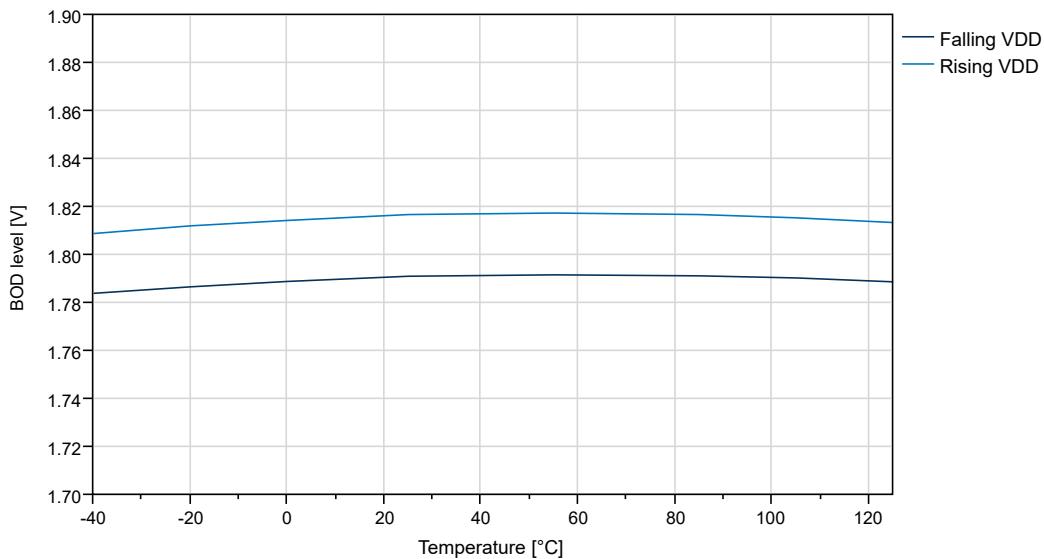


Figure 5-40. BOD Threshold vs. Temperature (Level 2.6V)

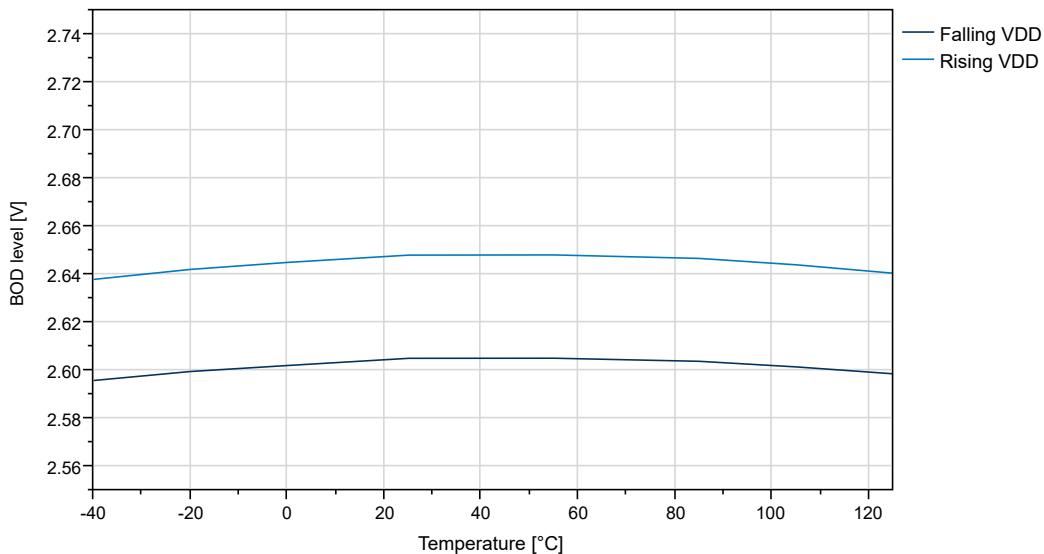
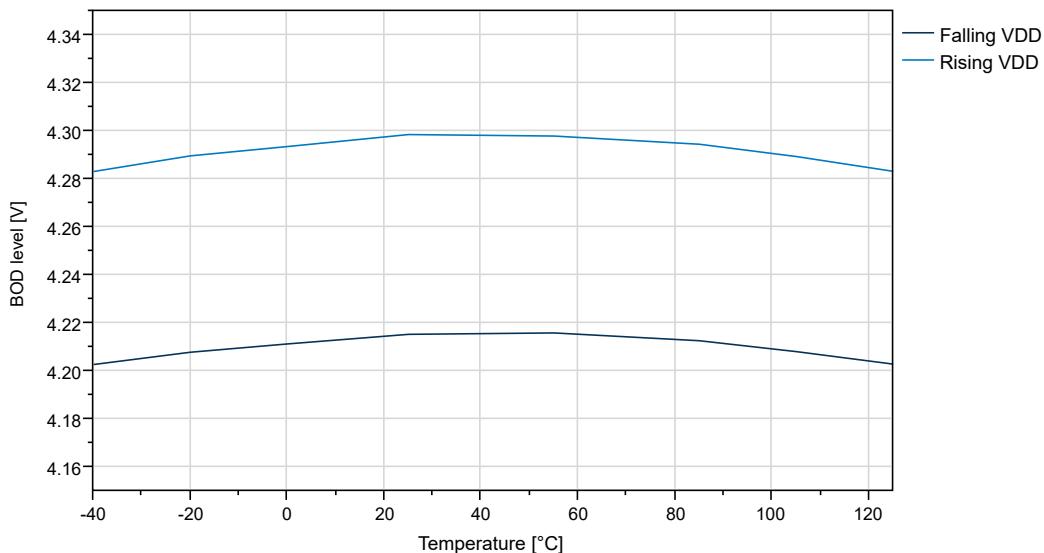
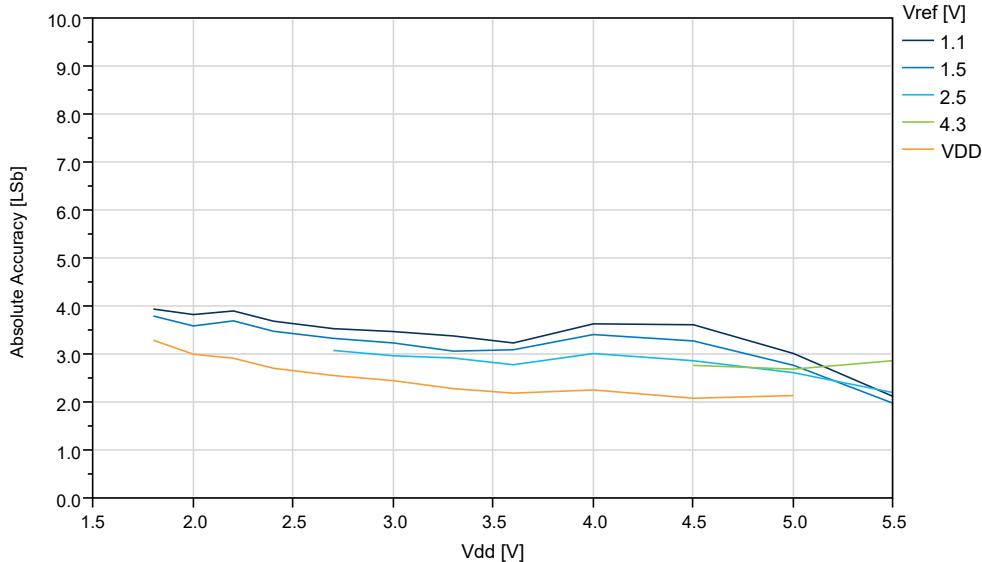


Figure 5-41. BOD Threshold vs. Temperature (Level 4.3V)



5.5 ADC Characteristics

Figure 5-42. Absolute Accuracy vs. V_{DD} ($f_{ADC}=115$ kspS) at $T=25^{\circ}\text{C}$, REFSEL = Internal Reference



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Figure 5-43. Absolute Accuracy vs. V_{ref} ($V_{DD}=5.0V$, $f_{ADC}=115$ ksps), REFSEL = Internal Reference

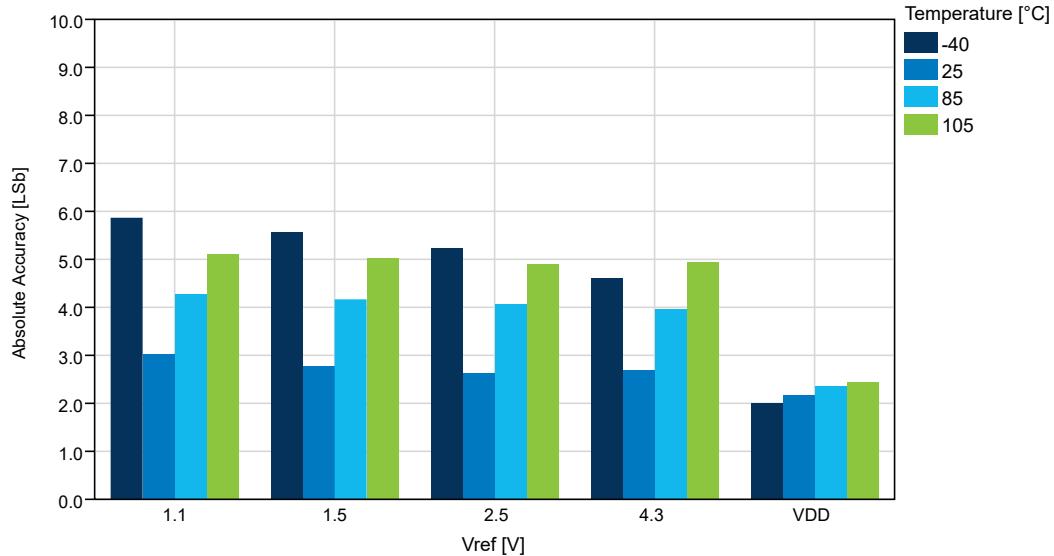
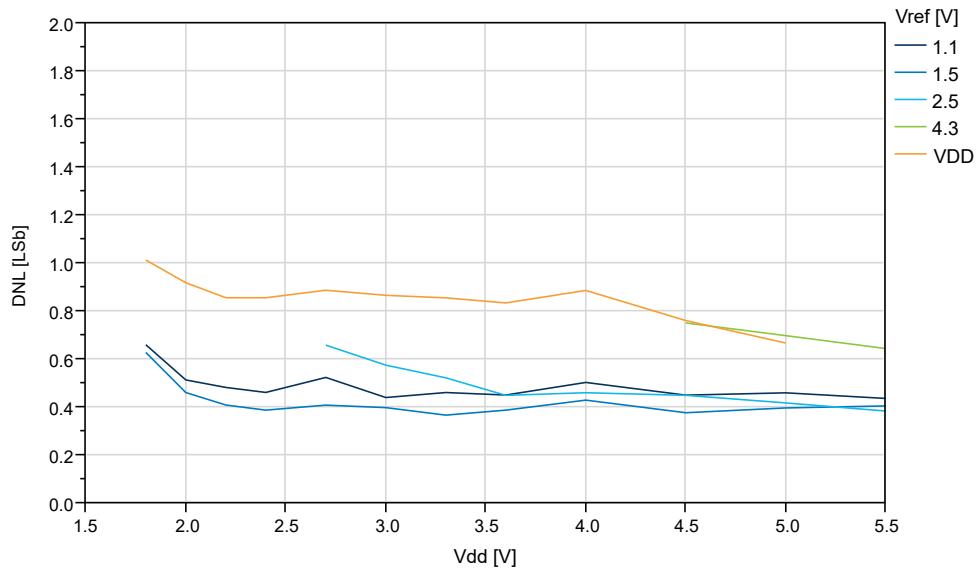


Figure 5-44. DNL Error vs. V_{DD} ($f_{ADC}=115$ ksps) at $T=25^{\circ}C$, REFSEL = Internal Reference



ATmega4809 – 40-pin Typical Characteristics

Figure 5-45. DNL vs. V_{ref} ($V_{DD}=5.0V$, $f_{ADC}=115$ ksps), REFSEL = Internal Reference

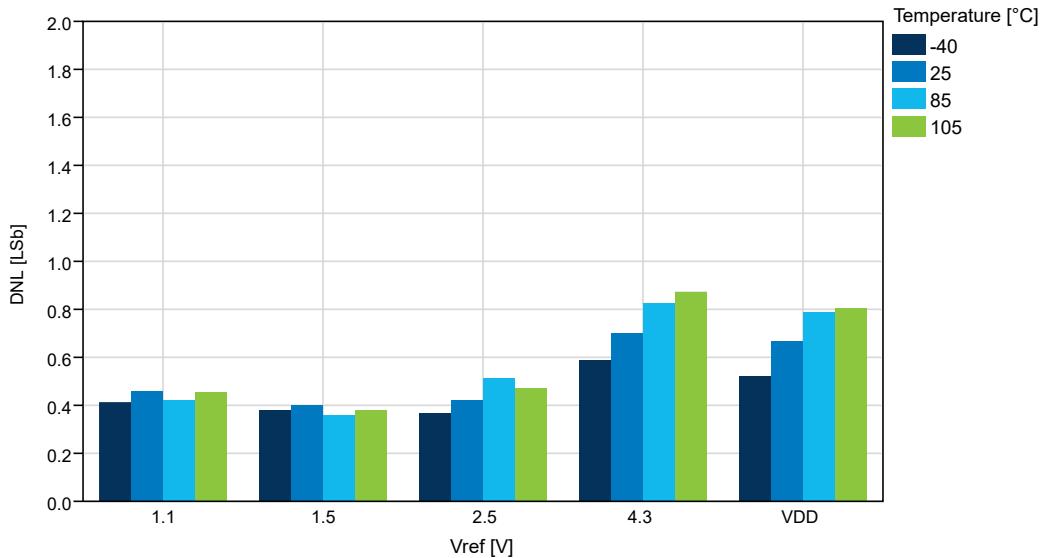
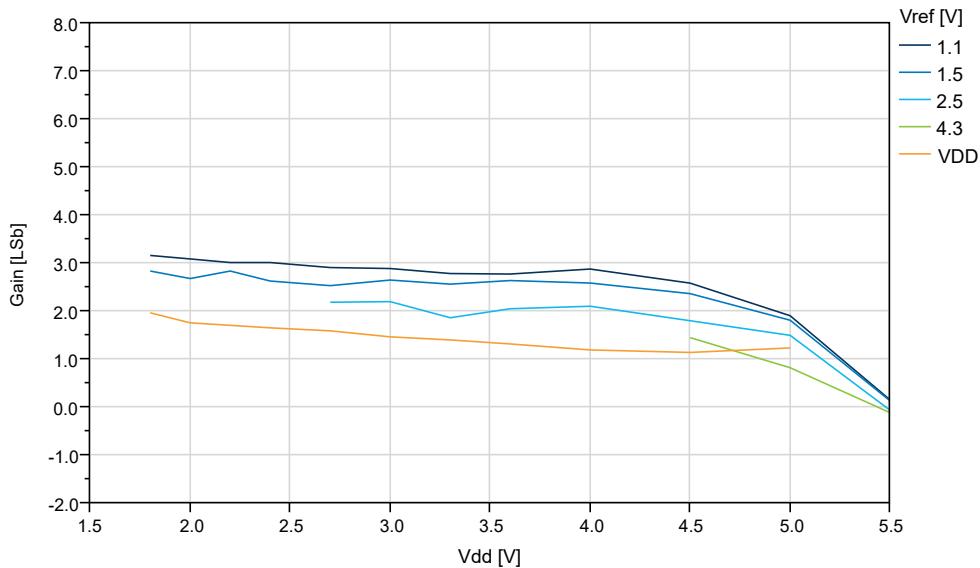


Figure 5-46. Gain Error vs. V_{DD} ($f_{ADC}=115$ ksps) at $T=25^{\circ}\text{C}$, REFSEL = Internal Reference



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Figure 5-47. Gain Error vs. V_{ref} ($V_{DD}=5.0V$, $f_{ADC}=115$ kspS), REFSEL = Internal Reference

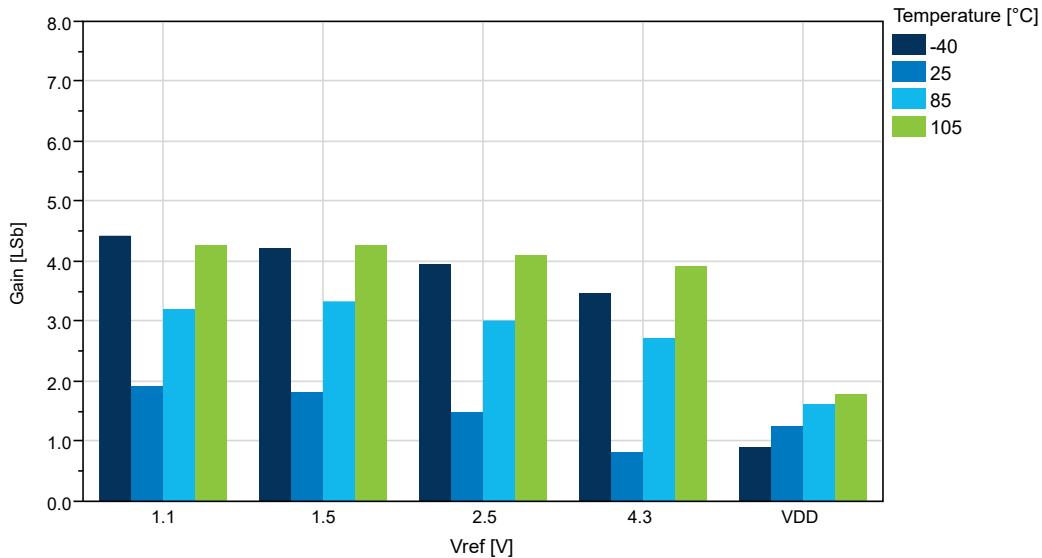


Figure 5-48. INL vs. V_{DD} ($f_{ADC}=115$ kspS) at $T=25^{\circ}C$, REFSEL = Internal Reference

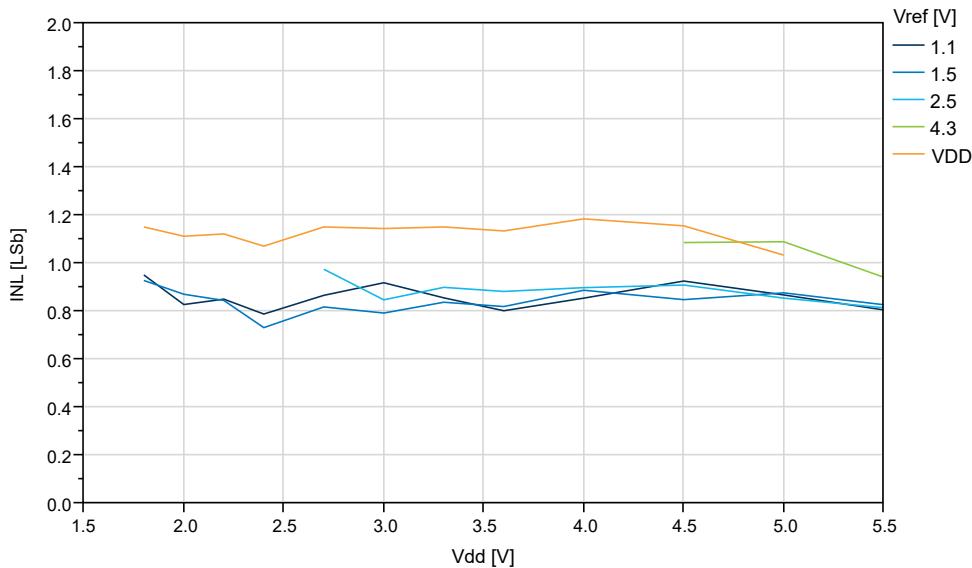


Figure 5-49. INL vs. V_{ref} ($V_{DD}=5.0V$, $f_{ADC}=115$ ksps), REFSEL = Internal Reference

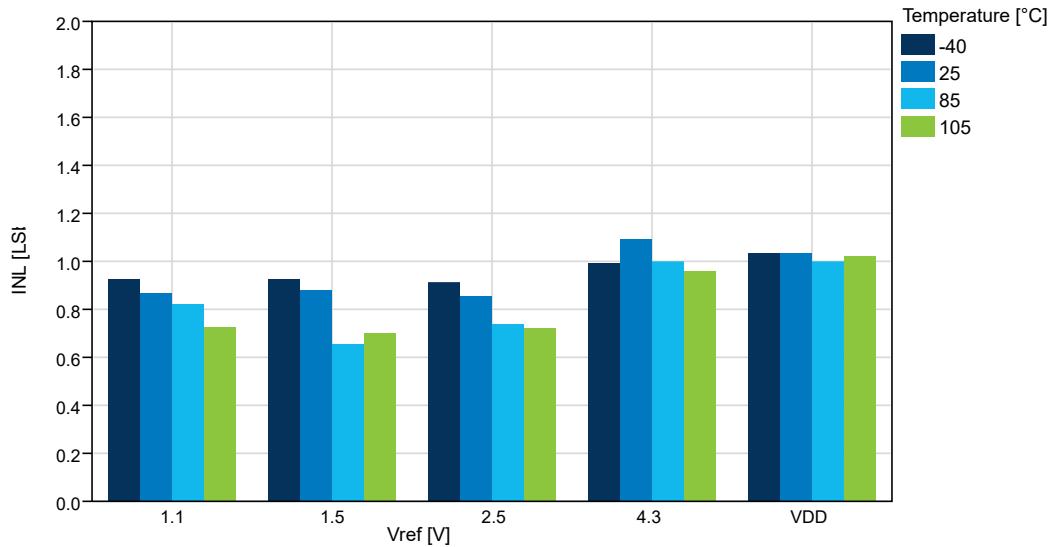
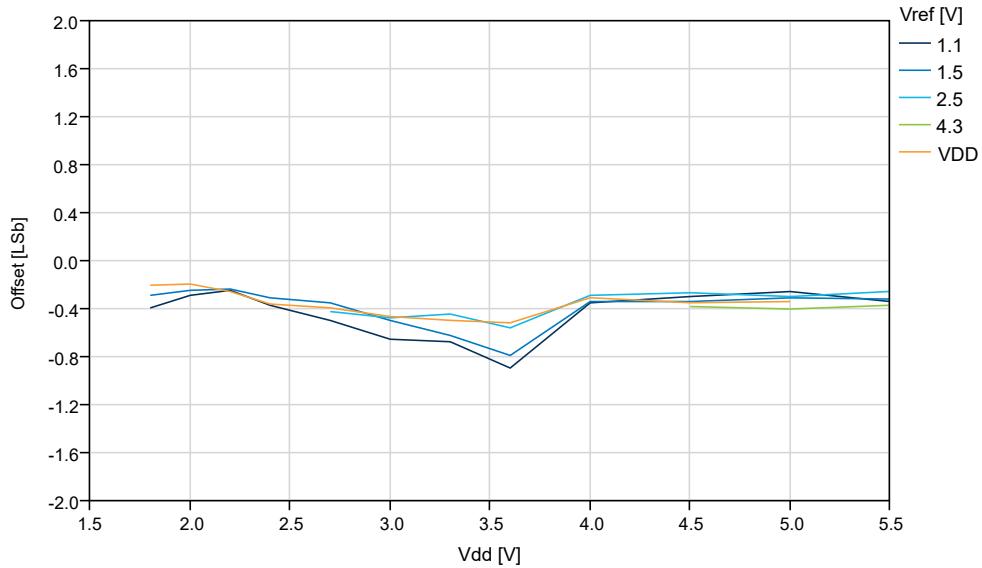


Figure 5-50. Offset Error vs. V_{DD} ($f_{ADC}=115$ ksps) at $T=25^{\circ}\text{C}$, REFSEL = Internal Reference



ATmega4809 – 40-pin Typical Characteristics

Figure 5-51. Offset Error vs. V_{ref} ($V_{DD}=5.0V$, $f_{ADC}=115$ kspS), REFSEL = Internal Reference

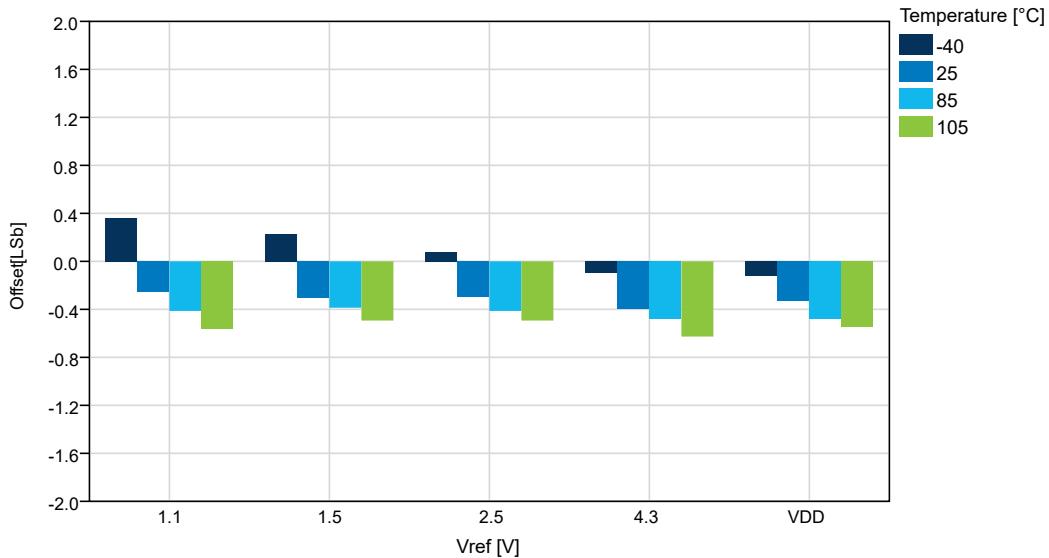


Figure 5-52. Absolute Accuracy vs. V_{DD} ($f_{ADC}=115$ kspS, $T=25^{\circ}C$), REFSEL = External Reference

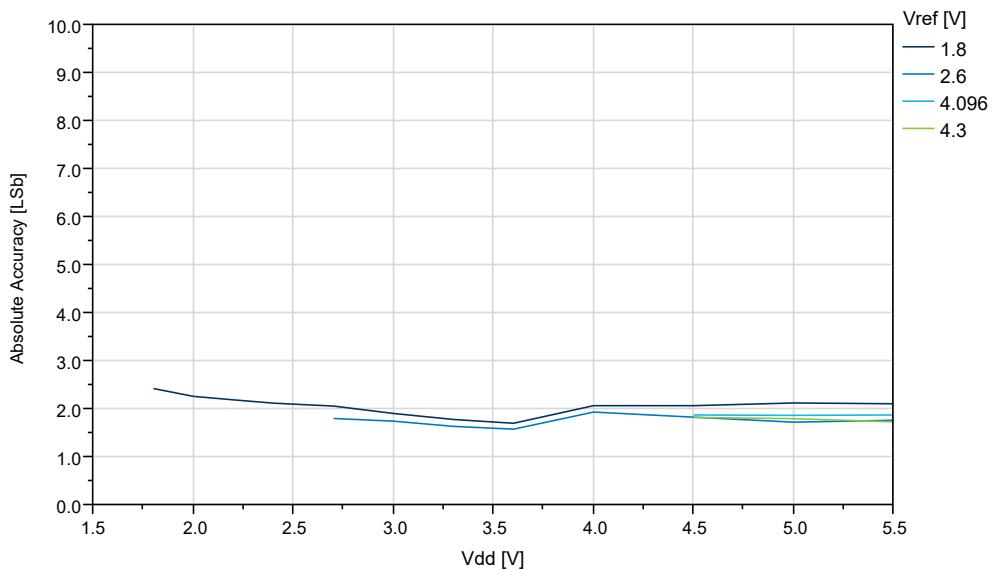


Figure 5-53. Absolute Accuracy vs. V_{REF} ($V_{DD}=5.0V$, $f_{ADC}=115$ ksps, REFSEL = External Reference)

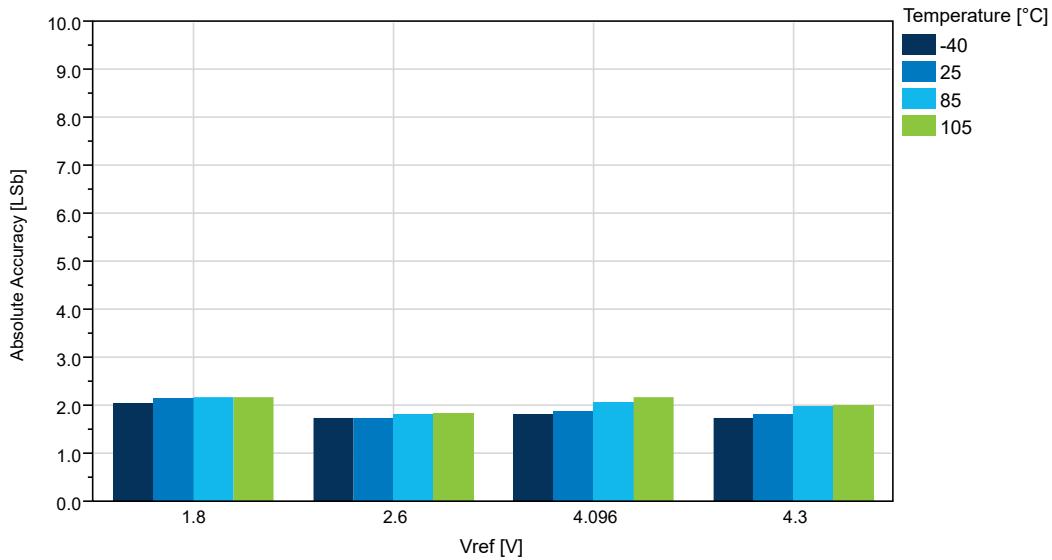
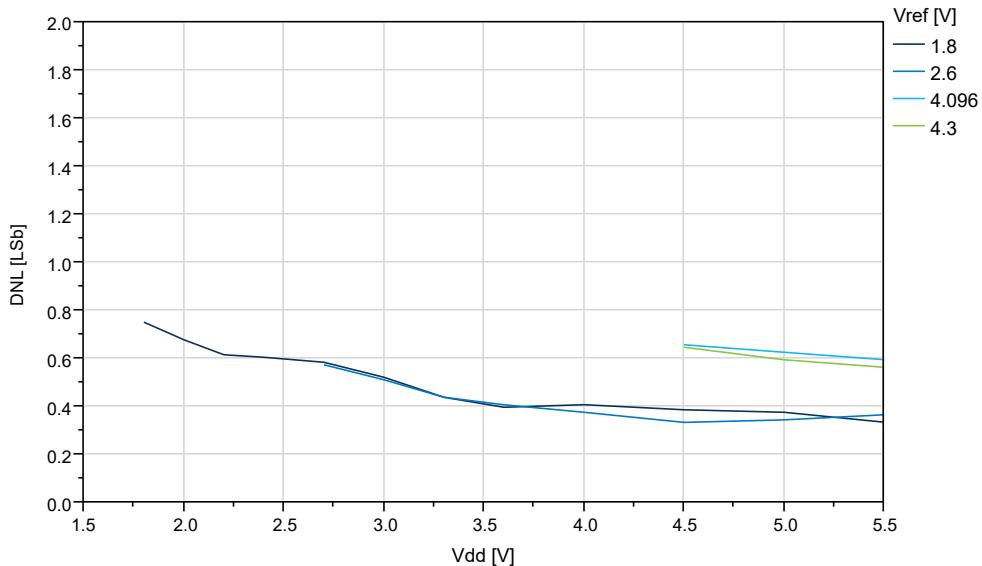


Figure 5-54. DNL vs. V_{DD} ($f_{ADC}=115$ ksps, $T=25^{\circ}\text{C}$, REFSEL = External Reference)



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Figure 5-55. DNL vs. V_{REF} ($V_{DD}=5.0V$, $f_{ADC}=115$ ksps, REFSEL = External Reference)

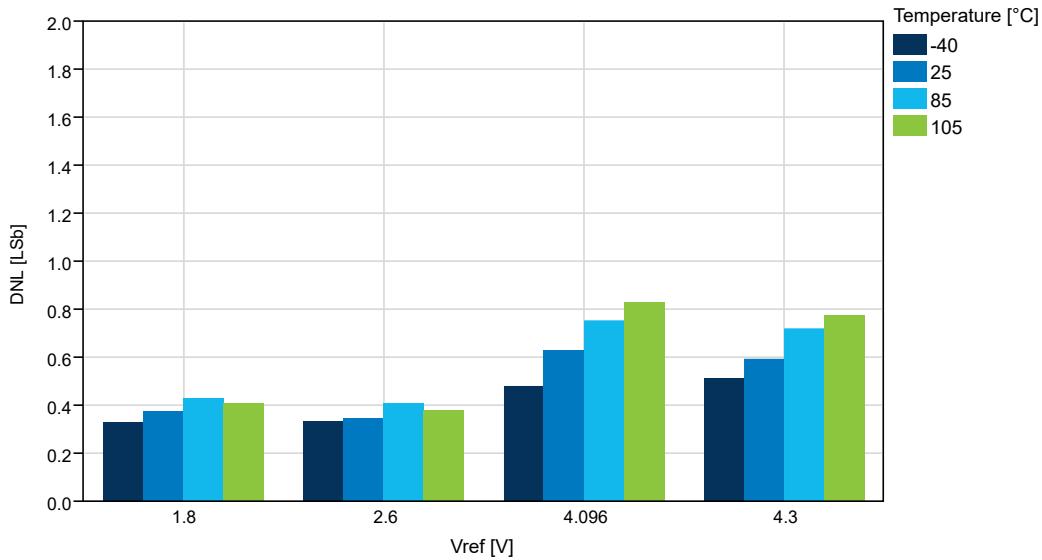


Figure 5-56. Gain vs. V_{DD} ($f_{ADC}=115$ ksps, $T=25^{\circ}\text{C}$, REFSEL = External Reference)

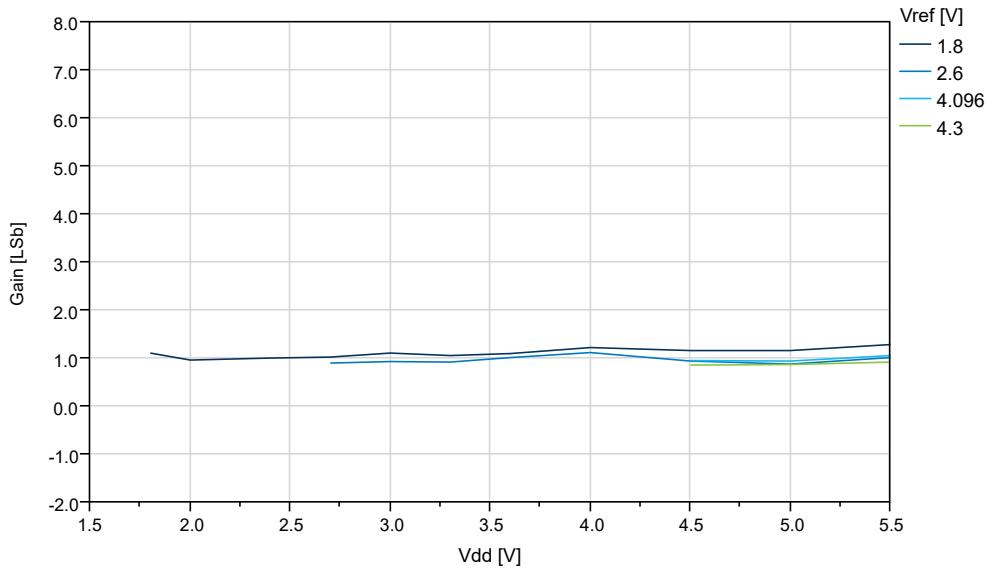


Figure 5-57. Gain vs. V_{REF} (V_{DD}=5.0V, f_{ADC}=115 kspS, REFSEL = External Reference)

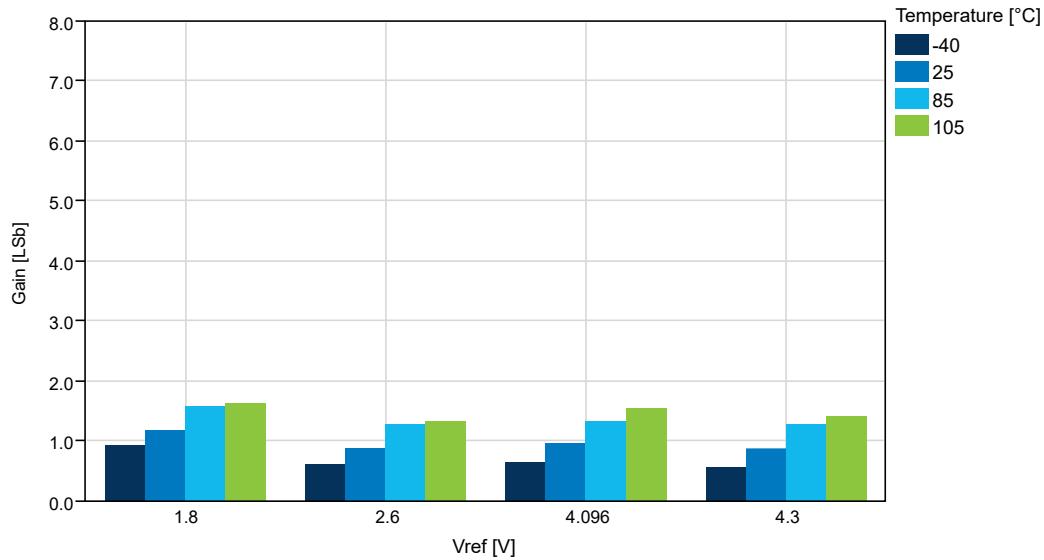


Figure 5-58. INL vs. V_{DD} (f_{ADC}=115 kspS, T=25°C, REFSEL = External Reference)

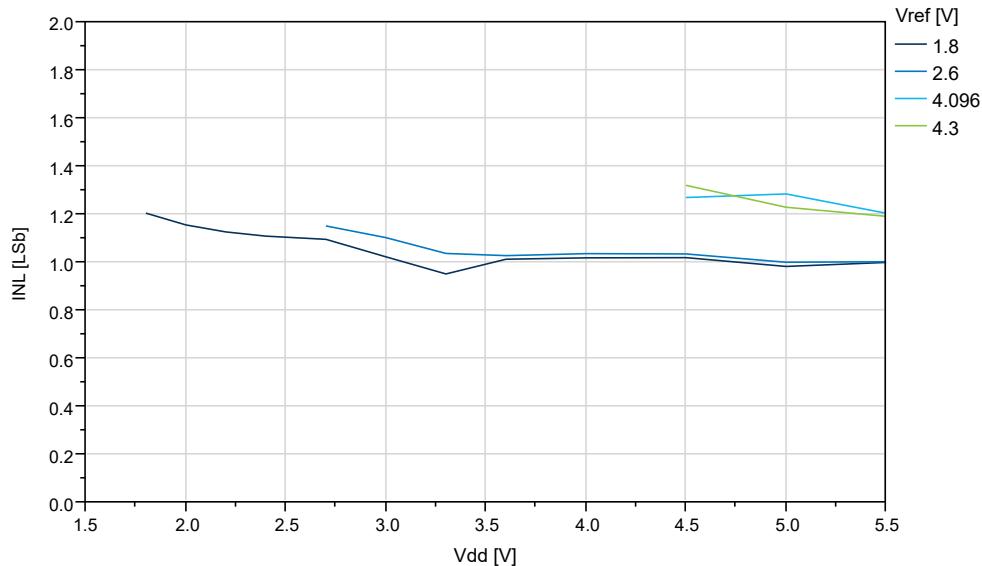


Figure 5-59. INL vs. V_{REF} ($V_{DD}=5.0V$, $f_{ADC}=115$ kspS, REFSEL = External Reference)

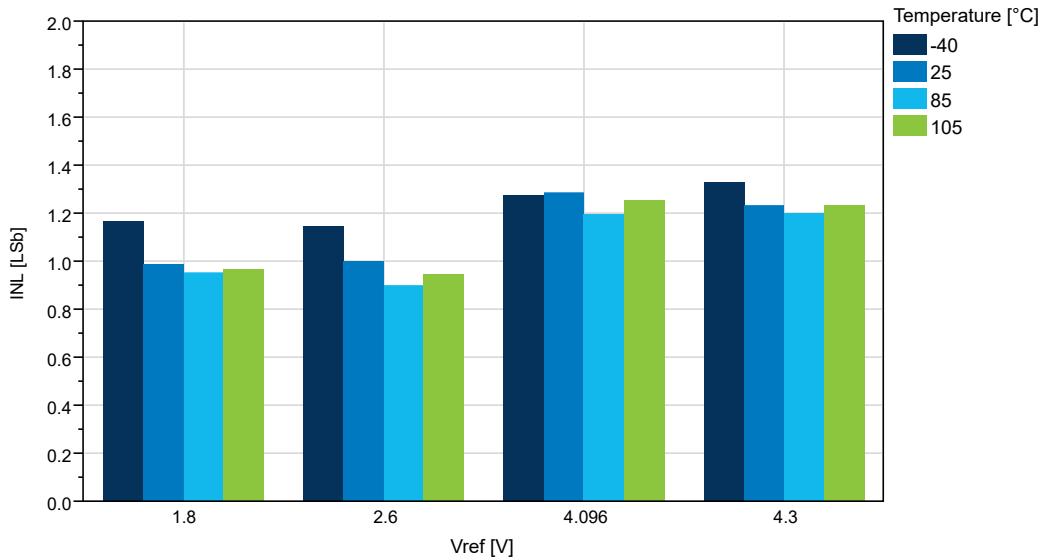


Figure 5-60. Offset vs. V_{DD} ($f_{ADC}=115$ kspS, $T=25^{\circ}\text{C}$, REFSEL = External Reference)

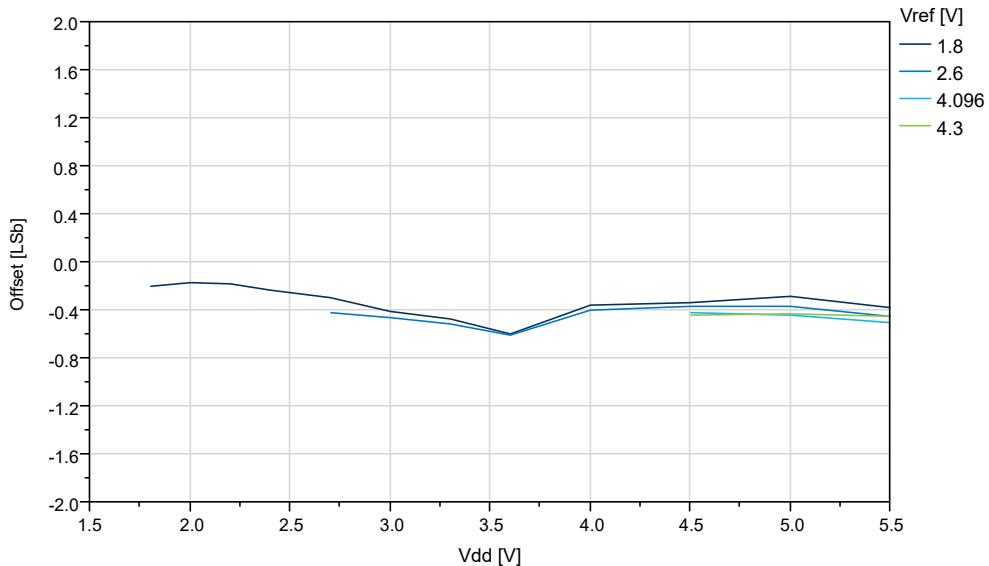
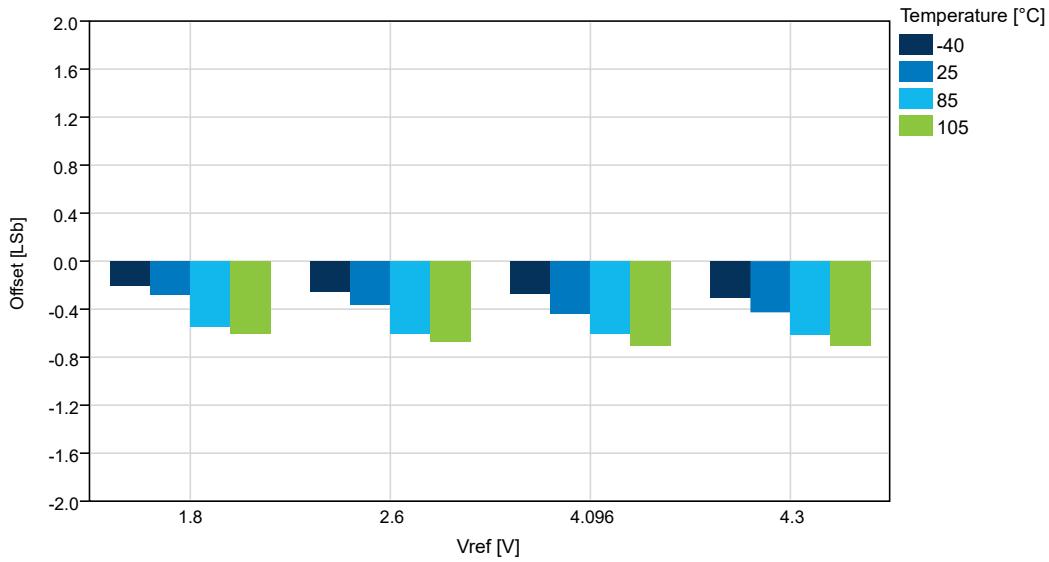


Figure 5-61. Offset vs. V_{REF} ($V_{DD}=5.0V$, $f_{ADC}=115\text{ kspS}$, REFSEL = External Reference)



5.6 AC Characteristics

Figure 5-62. Hysteresis vs. V_{CM} - 10 mV ($V_{DD}=5V$)

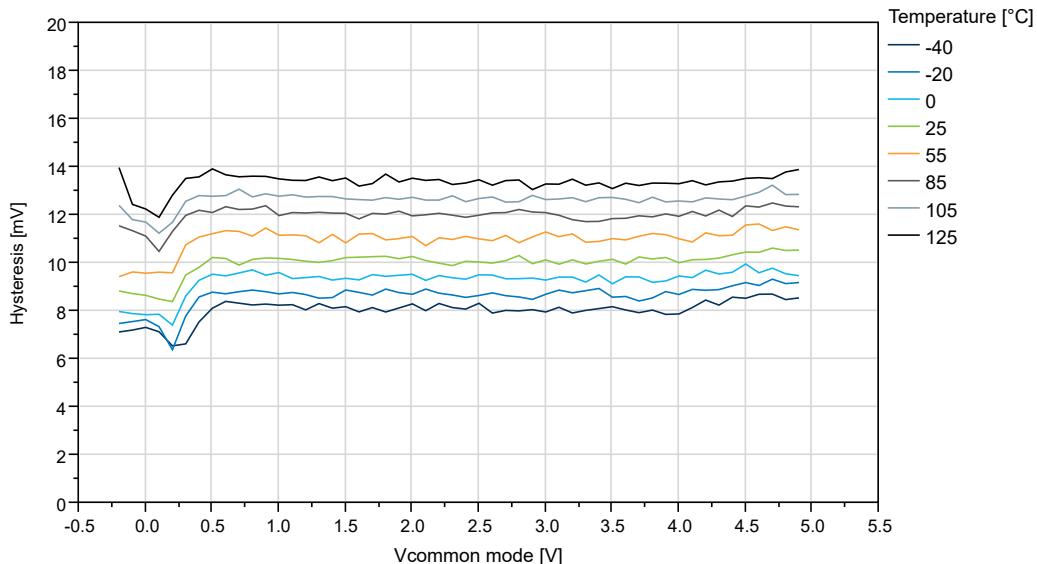


Figure 5-63. Hysteresis vs. V_{CM} - 10 mV to 50 mV ($V_{DD}=5V$, $T=25^{\circ}C$)

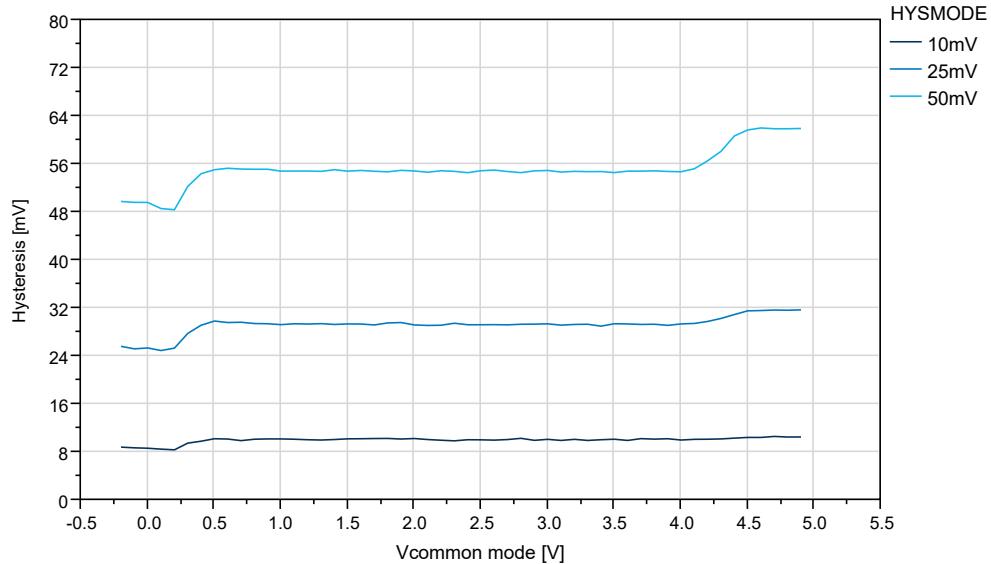


Figure 5-64. Offset vs. V_{CM} - 10 mV ($V_{DD}=5V$)

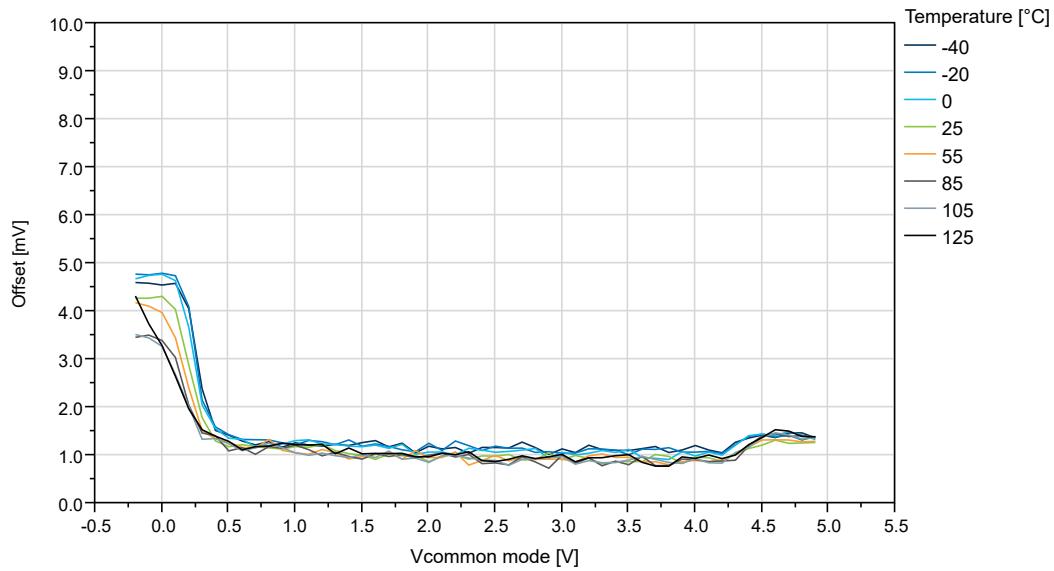
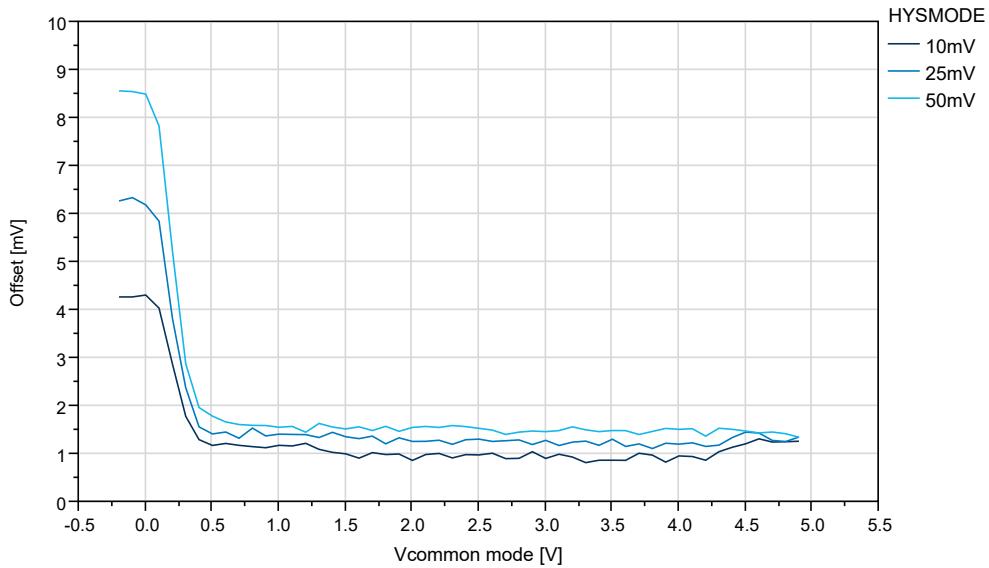


Figure 5-65. Offset vs. V_{CM} - 10 mV to 50 mV ($V_{DD}=5V$, $T=25^{\circ}C$)



5.7 OSC20M Characteristics

Figure 5-66. OSC20M Internal Oscillator: Calibration Stepsize vs. Calibration Value ($V_{DD}=3V$)

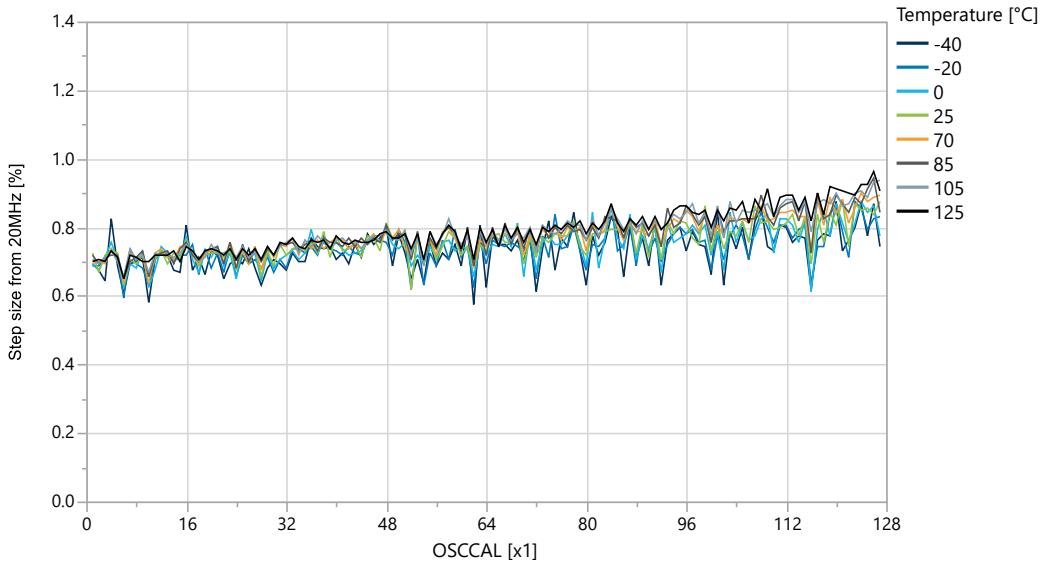


Figure 5-67. OSC20M Internal Oscillator: Frequency vs. Calibration Value ($V_{DD}=3V$)

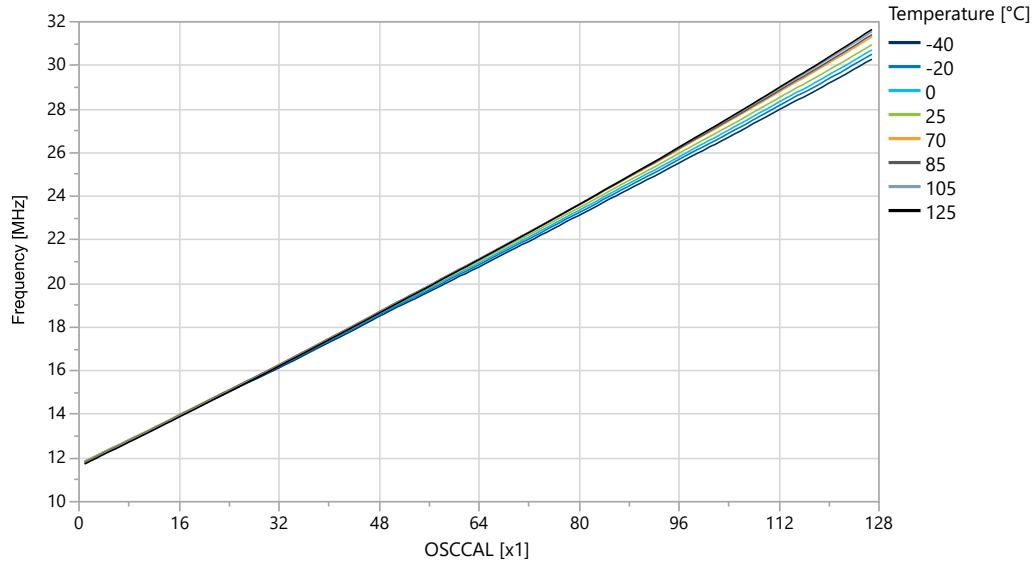


Figure 5-68. OSC20M Internal Oscillator: Frequency vs. Temperature

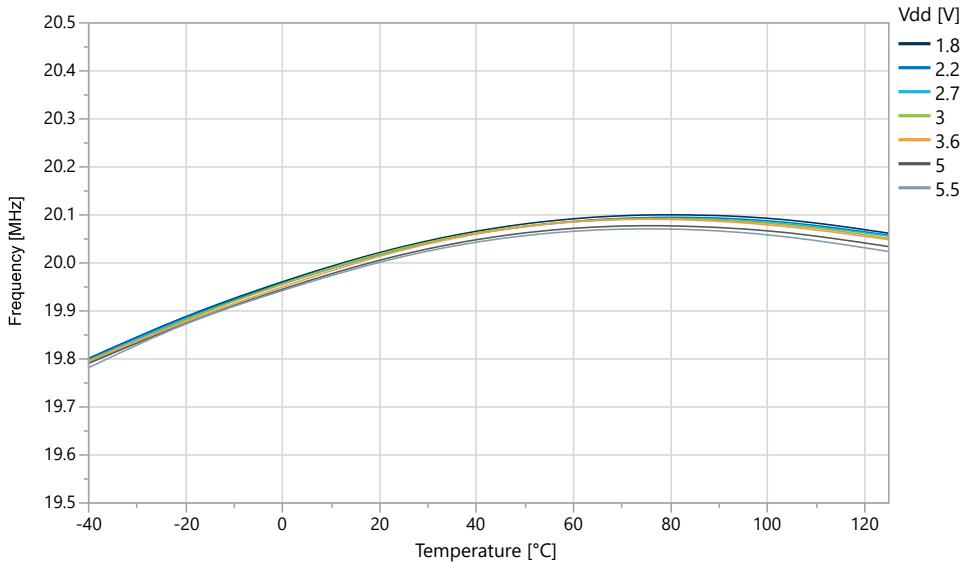
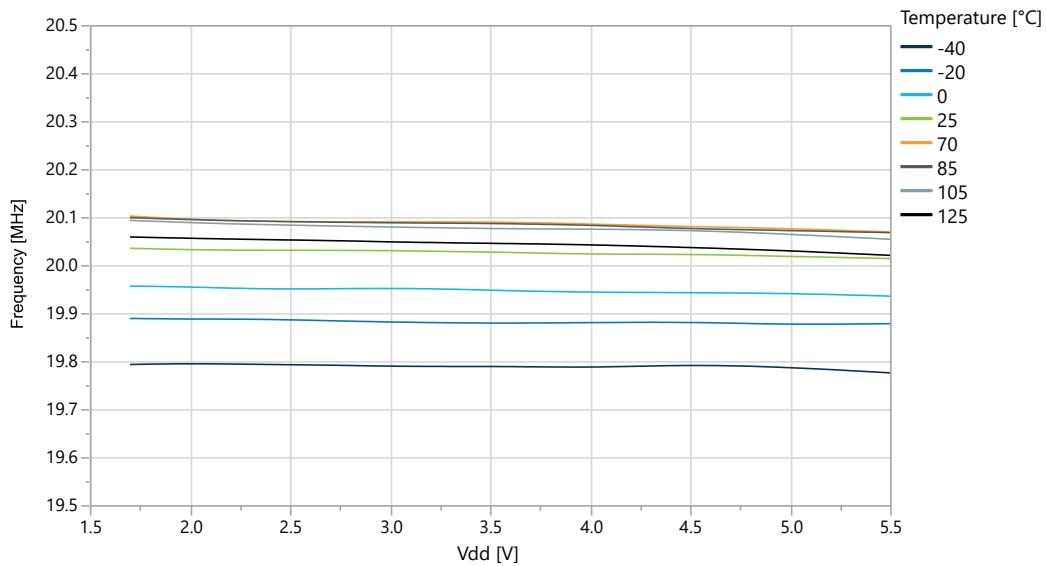
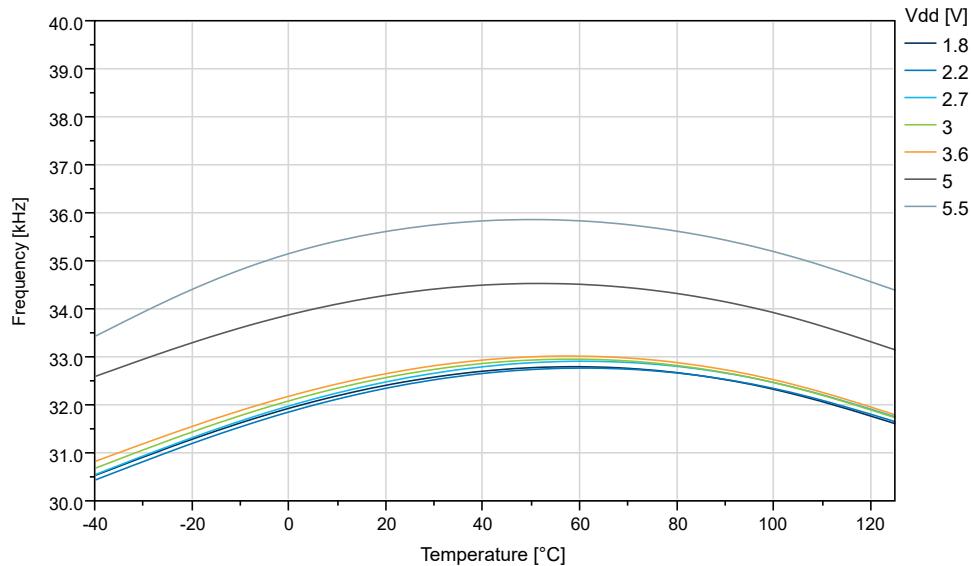


Figure 5-69. OSC20M Internal Oscillator: Frequency vs. V_{DD}



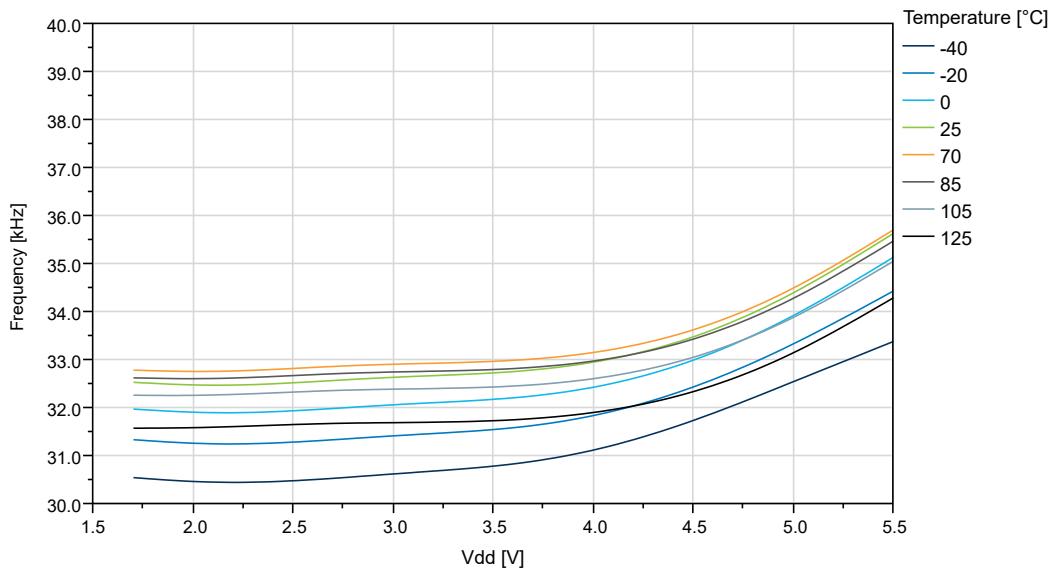
5.8 OSCULP32K Characteristics

Figure 5-70. OSCULP32K Internal Oscillator Frequency vs. Temperature



ATmega4809 – 40-pin Typical Characteristics

Figure 5-71. OSCULP32K Internal Oscillator Frequency vs. V_{DD}

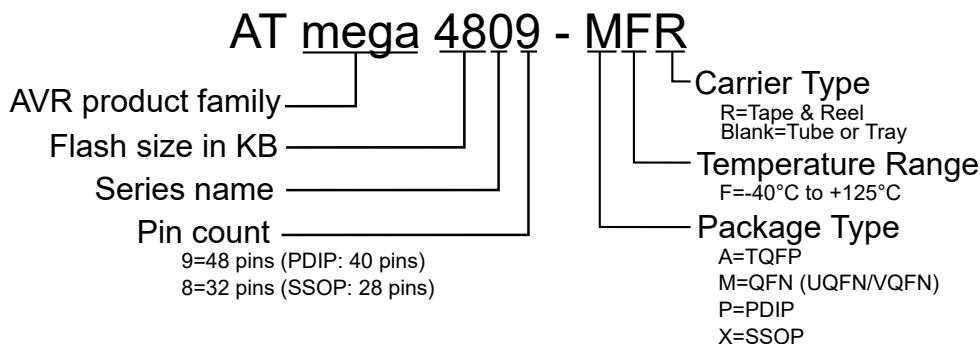


6. Ordering Information

- Available ordering options can be found by:
 - Clicking on one of the following product page links:
 - [ATmega4809 Product Page](#)
 - Searching by product name at [microchipdirect.com](#)
 - Contacting your local sales representative

Figure 6-1. Product Identification System

To order or obtain information, for example on pricing or delivery, refer to the factory or the listed sales office.



Note: Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes. Check with your Microchip Sales Office for package availability with the Tape and Reel option.

7. Online Package Drawings

For the most recent package drawings:

1. Go to <http://www.microchip.com/packaging>.
2. Go to the package type specific page, for example VQFN.
3. Search for either Drawing Number or Style to find the most recent package drawings.

Table 7-1. Drawing Numbers

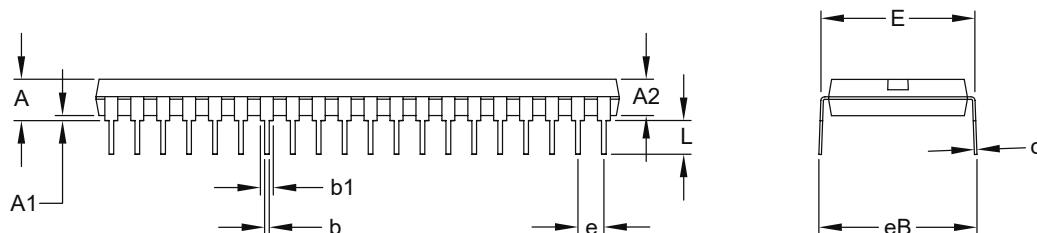
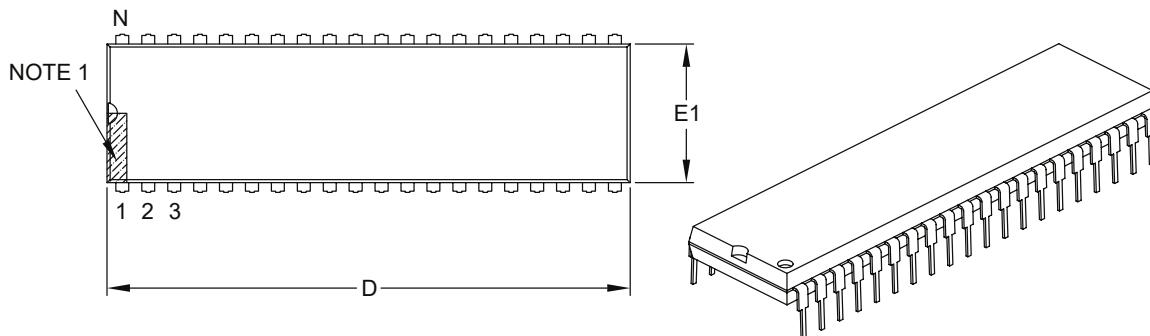
Package Type	Drawing Number	Style
PDIP40	C04-016	P

8. Package Drawings

8.1 40-Pin PDIP

40-Lead Plastic Dual In-Line (P) – 600 mil Body [PDIP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



		Units	INCHES		
		Dimension Limits	MIN	NOM	MAX
Number of Pins	N		40		
Pitch	e		.100 BSC		
Top to Seating Plane	A	—	—	.250	
Molded Package Thickness	A2	.125	—	.195	
Base to Seating Plane	A1	.015	—	—	
Shoulder to Shoulder Width	E	.590	—	.625	
Molded Package Width	E1	.485	—	.580	
Overall Length	D	1.980	—	2.095	
Tip to Seating Plane	L	.115	—	.200	
Lead Thickness	c	.008	—	.015	
Upper Lead Width	b1	.030	—	.070	
Lower Lead Width	b	.014	—	.023	
Overall Row Spacing §	eB	—	—	.700	

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic.
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-016B

ATmega4809 – 40-pin Package Drawings

Table 8-1. Device and Package Maximum Weight

6500	mg
------	----

Table 8-2. Package Characteristics

Moisture Sensitivity Level	N/A
----------------------------	-----

Table 8-3. Package Reference

JEDEC Drawing Reference	N/A
J-STD-609 Material Code	e3

Table 8-4. Package Code

S2X

9. Conventions

9.1 Memory Size and Type

Table 9-1. Memory Size and Bit Rate

Symbol	Description
KB	kilobyte ($2^{10} = 1024$)
MB	megabyte ($2^{20} = 1024 * 1024$)
GB	gigabyte ($2^{30} = 1024 * 1024 * 1024$)
b	bit (binary '0' or '1')
B	byte (8 bits)
1 kbit/s	1,000 bit/s rate (not 1,024 bit/s)
1 Mbit/s	1,000,000 bit/s rate
1 Gbit/s	1,000,000,000 bit/s rate
word	16-bit

9.2 Frequency and Time

Table 9-2. Frequency and Time

Symbol	Description
kHz	$1 \text{ kHz} = 10^3 \text{ Hz} = 1,000 \text{ Hz}$
KHz	$1 \text{ KHz} = 1,024 \text{ Hz}$, $32 \text{ KHz} = 32,768 \text{ Hz}$
MHz	$1 \text{ MHz} = 10^6 \text{ Hz} = 1,000,000 \text{ Hz}$
GHz	$1 \text{ GHz} = 10^9 \text{ Hz} = 1,000,000,000 \text{ Hz}$
ms	$1 \text{ ms} = 10^{-3}\text{s} = 0.001\text{s}$
μs	$1 \text{ } \mu\text{s} = 10^{-6}\text{s} = 0.000001\text{s}$
ns	$1 \text{ ns} = 10^{-9}\text{s} = 0.000000001\text{s}$

10. Data Sheet Revision History

Note: The data sheet revision is independent of the die revision and the device variant (last letter of the ordering number).

10.1 Rev. A - 03/2019

Initial release.

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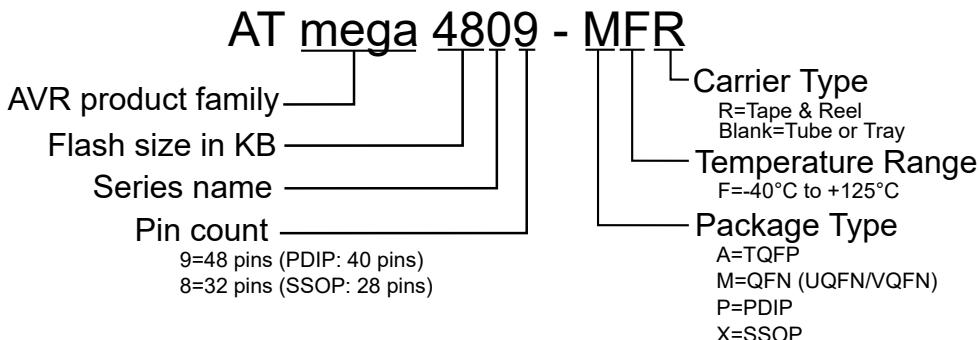
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- Local Sales Office
- Field Application Engineer (FAE)
- Technical Support

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