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Help

By Yahboom

Yahboom ROS Transbot Robot with Lidar Depth camera support Python programming MoveIt 3D mapping for Raspberry Pi 4B

★★★★★ **4.85/5.0** | 13 reviews

SKU: 3000200281_4000200281

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Product description   Shipping   Warranty   Payment   Ask a question

Another version

Jetson NANO Transbot ROS Robot

Transbot is a crawler educational robot developed based on the ROS(robot operating system). It uses Python 3 as the programming language. And comes with high-performance hardware configurations such as Raspberry Pi 4B board, lidar, high-definition camera/depth camera, etc., which can realize robot motion control, remote communication, mapping navigation, following, avoiding, autopilot, robotic arm MoveIt simulation, multi-robot queue, multi-robot navigation and so on. We will provide many ROS courses and teaching video to help user get started with ROS easily.

Features:

Intimate design and service: The chassis has been assembled before shipment. The TF card comes with Transbot dedicated system files. Only need to assemble the Raspberry Pi, camera and other parts, and you can quickly enjoy it.

Professional technical support and after-sales service.

Stable hardware configuration realizes interesting functions:

Based on lidar: Obstacle avoidance, following, 2D mapping navigation, multi-robot navigation, etc.

Based on depth camera: 3D mapping, point cloud image processing, KCF target visual following, etc.

Based on a HD camera: High-brightness searchlight, 2 DOF PTZ flexible rotation.

ROS operating system: Based on the ROS robot operating system, we cleverly use Rviz, MoveIt, and Qt toolboxes to realize the joint control of the robot arm MoveIt simulation and the real machine.

Cross-platform interconnection control: It support a variety of different control methods, AI-enabled APP, FPV real-view visual handle remote control, JupyterLab online programming, and robot operating system control.

Detailed video courses: We provide 64-hours video tutorials and detailed documents. Whether you are a beginner or an experienced ROS player, you can easily use Transbot robot.

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Lidar scanning avoiding / Depth camera visual recognition / 3D mapping navigation

Massive video courses
◇ 64 original video tutorials

APP control
◇ Control APP (iOS/Android)
◇ Map Navigation APP (Android)

Top hardware configuration
◇ Raspberry Pi 4B board
◇ SLAM A1 Lidar
◇ Astra Pro depth camera

Funny function
◇ 3D/2D mapping navigation
◇ Visual SLAM image processing
◇ Path planning/APP mapping navigation

This product is the **Raspberry Pi 4B** version Transbot, if you need the **JETSON NANO** version Transbot, **please click here**

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realize robot motion control, remote control communication, mapping navigation, Follow obstacle avoidance, autonomous driving, robot MoveIt simulation and other applications. A lot of ROS courses and teaching video will be provided, which will help you easily get started with ROS.
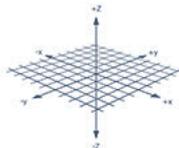
ROS operating system

Artificial intelligence

Raspberry Pi 4B

Path planning automatic navigation

Lidar scan map

3D real-world map navigation

Visual recognition target tracking
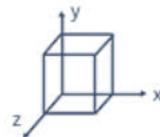
3D analysis of depth images

OpenCV image processing

Multi-color visual tracking

Mobile APP mapping navigation

Python/C++ programming

MoveIt simulation

Indoor navigation dynamic avoiding

Cross-platform interconnection control

Real person video manipulation

Built-in PID controller

Massive video tutorials

Detail tutorials

Technical support

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and learning direction. At present, Ackerman steering chassis and Mecanum wheel chassis are popular choices. Ackerman is the standard structure of modern cars, and Mecanum wheel is the standard choice of omnidirectional mobile. If you want to explore the field of automatic driving in the future, Ackerman chassis structure is recommended. All of the following models can be equipped with depth cameras and multiple lidars, all of which meet the requirements of mapping navigation, depth learning, 3D vision, robot formation and other directions. Each vehicle model provides corresponding video tutorials, which can meet the requirements of zero basic introduction and improvement.

Help

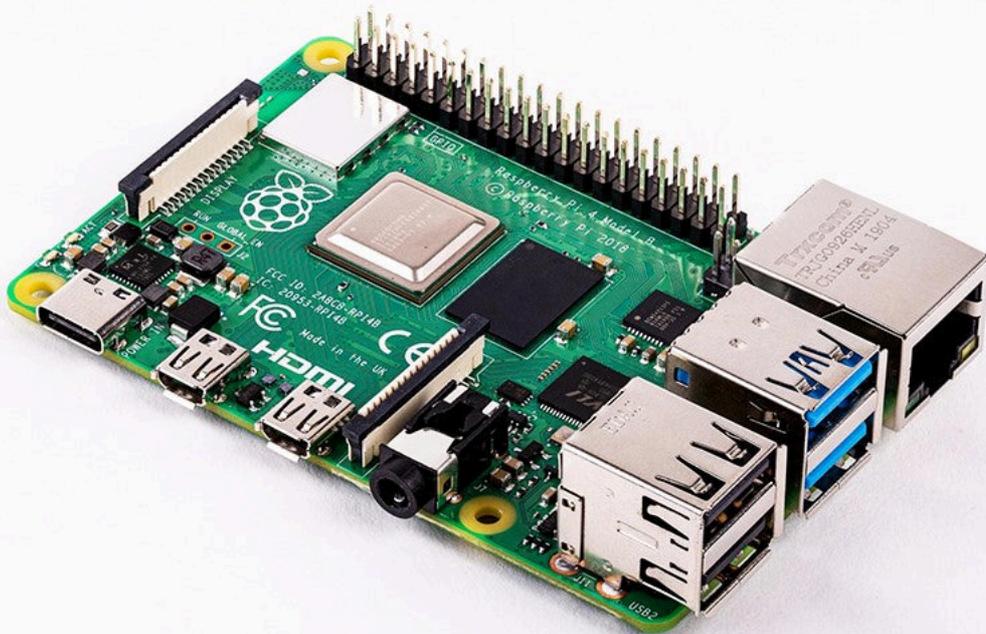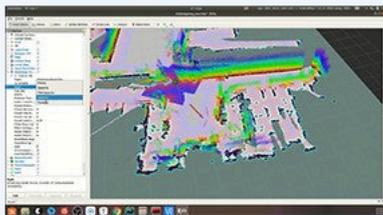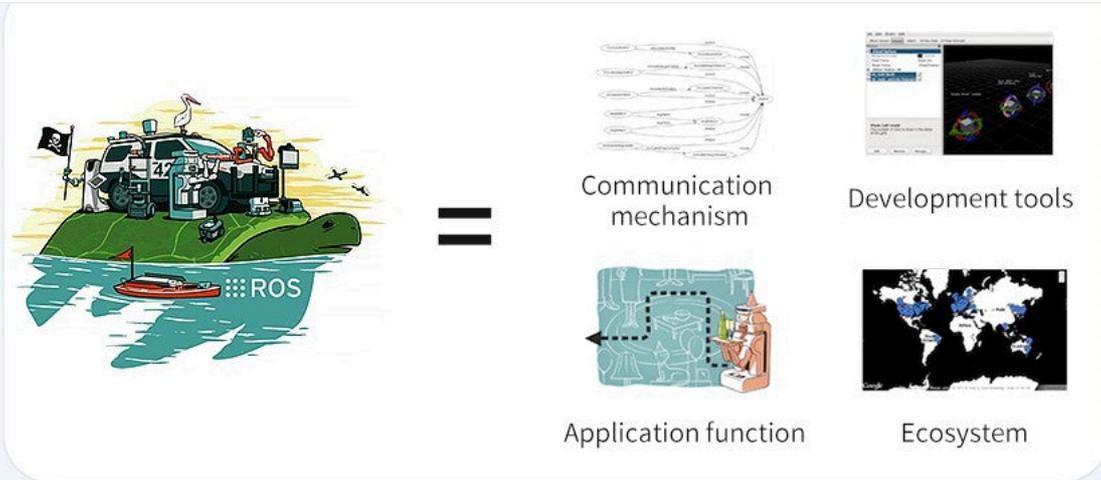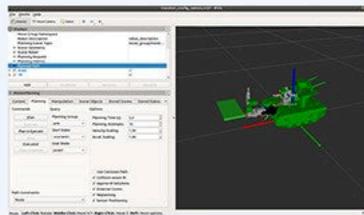|						
ROSMASTER X1 (Click to buy)	Chassis	Pendulous suspension(M)	Tire	Non-slip rubber wheel	Motor	520 Motor *4
	Motor reduction ratio	1:30	Robotic arm	No	Voice interaction	Yes
	Lidar	SLAM A1/ YDLIDAR X3	Camera	Astra Pro depth camera	Level	ROS basic learning
ROSMASTER R2 (Click to buy)	Chassis	Ackerman steering	Tire	Racing rubber wheel	Motor	520 Motor *4 Metal servo *1
	Motor reduction ratio	1:19	Robotic arm	No	Voice interaction	Yes
	Lidar	SLAM A1/ YDLIDAR 4ROS	Camera	Astra Pro depth camera	Level	Autopilot/ Competition
ROSMASTER X3 (Click to buy)	Chassis	Pendulous suspension(M)	Tire	Mecanum wheel(M)	Motor	520 Motor *4
	Motor reduction ratio	1:30	Robotic arm	No	Voice interaction	Yes
	Lidar	SLAM A1/ SLAM S2L	Camera	Astra Pro depth camera	Level	Omnidirectional movement/ROS deep development
ROSMASTER X3 PLUS (Click to buy)	Chassis	Pendulous suspension(L)	Tire	Mecanum wheel(L)	Motor	520 Motor *4
	Motor reduction ratio	1:56	Robotic arm	6DOF	Voice interaction	Yes
	Lidar	YDLIDAR 4ROS	Camera	Astra Pro depth camera	Level	University research/Mobile capture
TRANSBOT	Chassis	Crawler	Tire	Nylon track	Motor	520 Motor *2
	Motor reduction ratio	1:56	Robotic arm	3DOF	Voice interaction	No
	Lidar	SLAM A1	Camera	Astra Pro depth camera	Level	Mobile grabbing/With off-road ability

CPU
64-bit 1.5GHz Quad-core
(28nm process)

GPU
Broadcom VideoCore VI
@ 500MHz

4GB / 8GB memory versions are officially recommended, and 2GB / 1GB memory versions are not recommended.
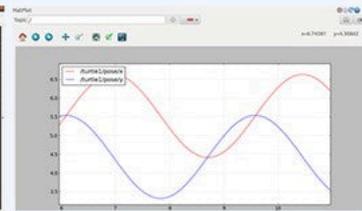

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Communication mechanism   Development tools

Application function   Ecosystem

3D visualization tool--Rviz   Robotic arm motion planning--Movelt   QtTool box--rqt_plot/ rqt_graph

Option description

HD camera

The high-definition camera platform can realize rotation of up, down, left and right, and equipped with high-power LED spotlights. color tracking and automatic driving can be realized easily.

VS

Astra Pro Plus depth camera

The depth camera platform supports left and right rotation and up and down manual adjustment, which can not only realize all the AI visual functions, but also realize advanced functions such as depth image data processing and 3D mapping navigation.

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6. AR tag pose estimation
7. AR special effects visualization◆
8. Color tracking◆
9. Object following◆
10. QR code creation
11. QR code recognition◆
12. Visual tracking autopilot◆
13. Bone detection*
14. Finger follow*
15. Camera calibration*

PS: "*" means exclusive function of Depth Camera

6. RRT exploration and mapping
7. Lidar fixed-point navigation★
8. Lidar multi-point navigation
9. TEB and DWA path planning
10. Lidar obstacle avoidance◆
11. Lidar guards◆
12. Lidar follow◆
13. Robot patrol and avoid obstacles◆
14. ROS APP navigation★
15. ROS APP mapping★   NEW
16. Multi smart robot car navigation

1. VNC remote control
2. Data type conversion
3. APP gravity sensor control◆
4. ROS image transmission and control
5. IMU and mileage data release
6. OpenCV application and tutorial
7. Handle control
8. Set static IP/open hotspot mode
9. Multi-machine communication configuration
10. SSH remote control
11. Keyboard node control
12. rqt real-time control PID
13. Linear velocity and angular velocity calibration
14. Robot ROS serial communication
15. jupyter lab remote control
16. Multi smart robot car synchronous control   NEW
17. Many smart robot car lined up to perform   NEW

1. Read the angle status of the robotic arm◆
2. Robotic arm gripping and transport◆
3. APP/handle control robotic arm◆
4. MoveIt robotic arm simulation
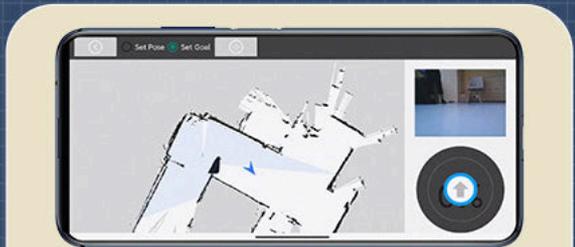PS: The above functions need to be equipped with a robotic arm

1. One-click download by serial port
2. Motor over-current protection
3. Six-axis attitude sensor
4. Battery voltage detection
5. Voltage alarm

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Transbot

遥控   炫彩车灯   图像美化   激기

The above functions with "◆" can be remotely controlled in YahboomRobot APP

Set Pose   Set Goal

The above functions with "★" can be remotely controlled in the ROS Robot APP

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01

Transbot

CONTROL   COLOURFUL LIGHT   IMAGE BEAUTIFY   LASER RADAR

YahboomRobot Control APP (iOS+Android)

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ROS Robot Mapping
Navigation APP (Android)

Handle control
(standard configuration for any version)

04

05
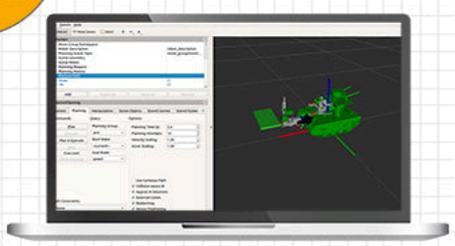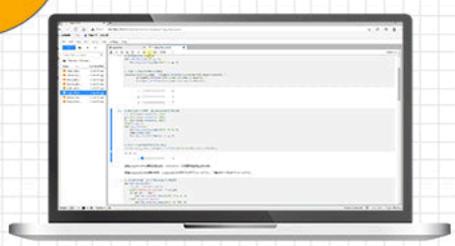
Jupyter Lab webpage
online programming control

ROS system control

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YahboomRobot APP

Built-in AI gameplay, quickly experience the funny of
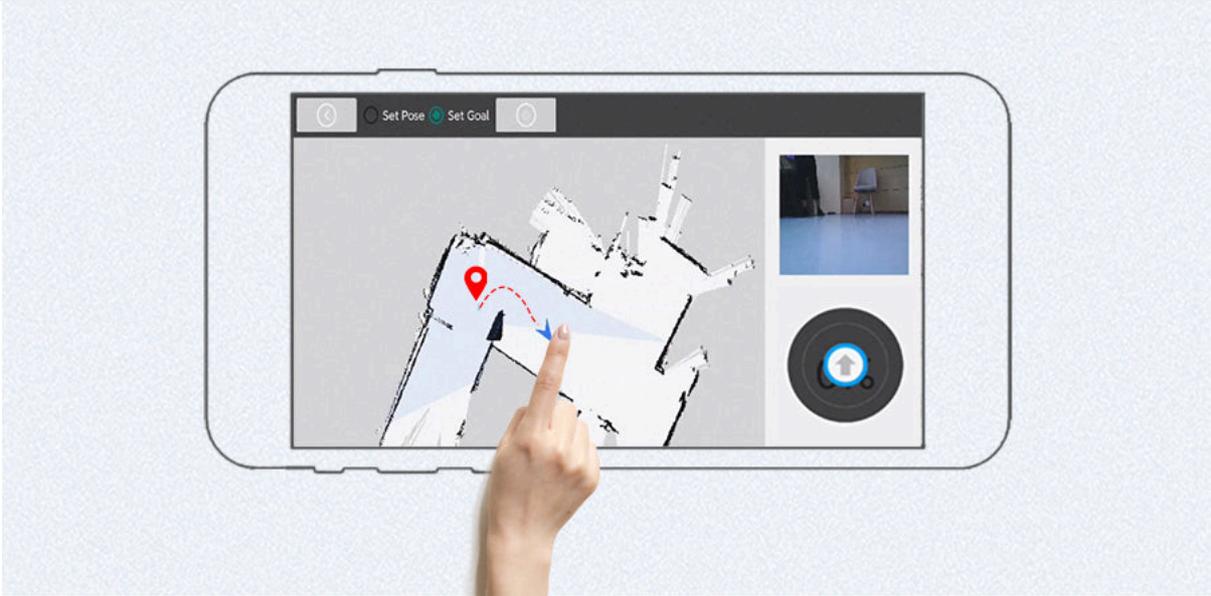Transbot remote control.

APP control interface

Autopilot interface

Lidar interface

**AR reality augmented interface**

Intelligent patrol interface

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Support 3D mapping navigation technology (rtab) containing pure vision and visual radar fusion. Transbot robot can navigate and avoid obstacles in the 3D map, and supports global relocation.
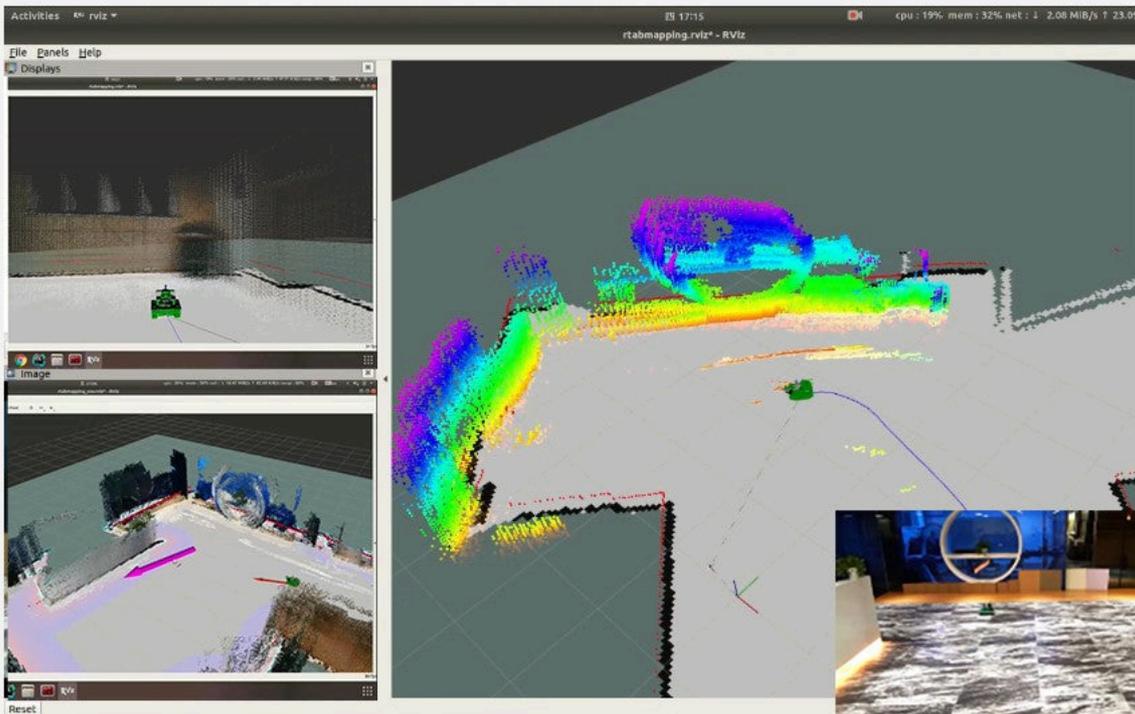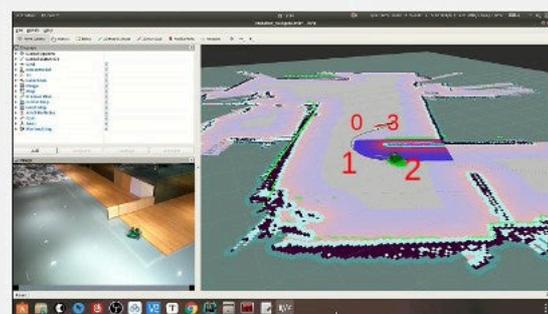

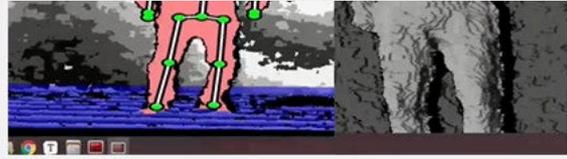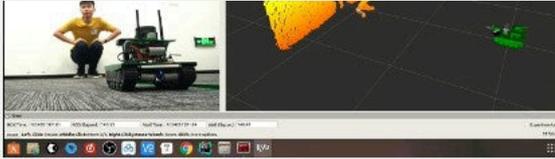## P2 Lidar mapping and navigation

Support gmapping, hector, karto, cartographer and other algorithms to create maps. Support path planning, single-point and multi-point autonomous navigation.
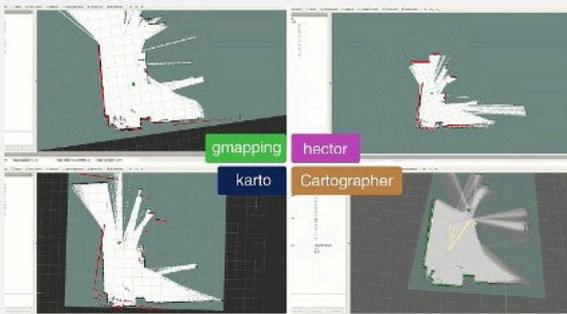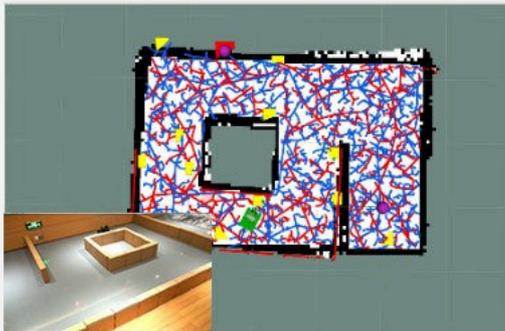

Four algorithms for mapping

Autonomous navigation for path planning

P4 RRT autonomous exploration and mapping

No need to control the robot manually, and the RRT algorithm is used to autonomously complete the exploration and construction of maps, save the map, and return to the starting point.

P5 KCF goal follow

Depth camera exclusive function

Based on the image related KCF filter algorithm, any follow target in the image can be selected.


P6 Autopilot

Support custom color selection, the robot can automatically recognize the color and drive forward.

P7 Color recognition/tracking

Select the color through the screen and let robot track the target color.

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P8 AR tag recognition

Support 2D code label dynamic tracking detection, 2D code posture position coordinate acquisition, support multiple 2D code recognition at the same time.
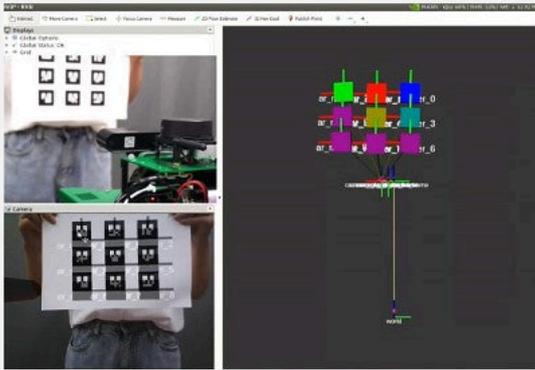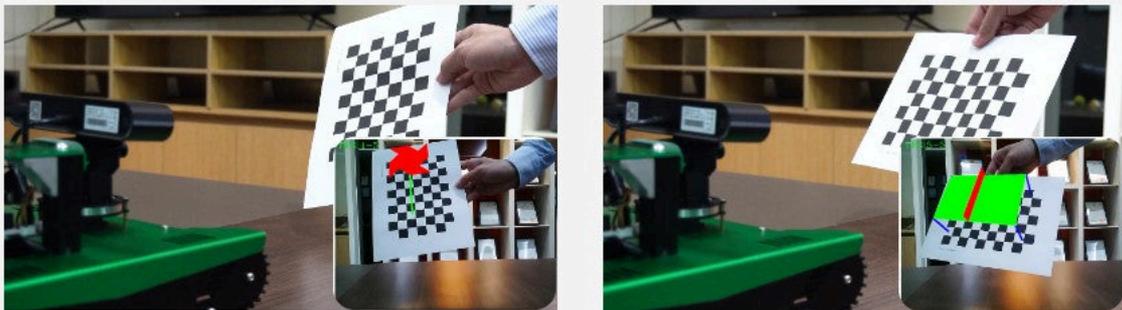
P9 Visual image beautification

Through OpenCV, the video image is converted to achieve the effect of image beautification.

P10 AR reality augmentation

Select the corresponding graphics through the APP, and let the graphics appear on the checkerboard paper through AR enhancement technology.

Help
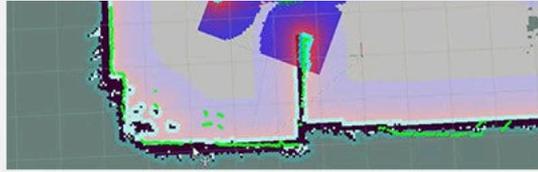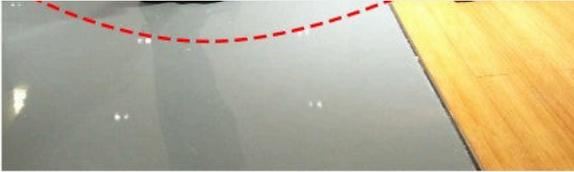
P12 Lidar tracking

Lidar scans and detects the environment, and selects targets that are close to follow to move.

P13 Lidar guard

Targets that are closer to the radar will be locked, and the front of the robot car will always face this target.

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Different configuration   Select on demand.

P16   3 DOF robotic arm

robotic arm exclusive function

3 DOF robotic arm allows the car to realize grasp objects.
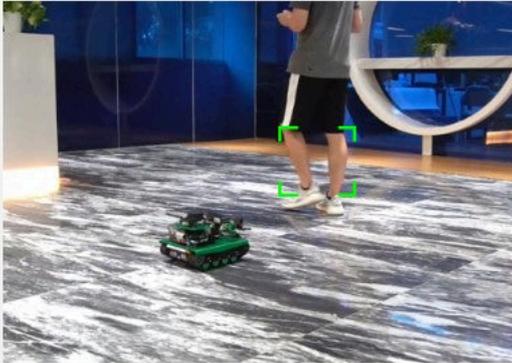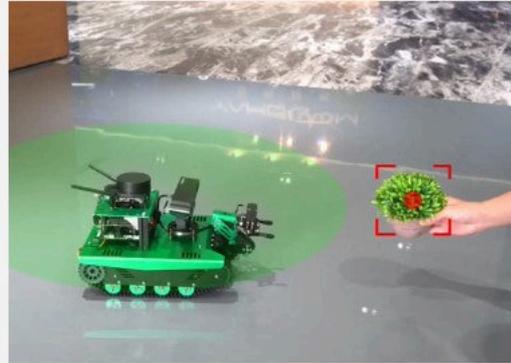
P17   Electric rotating platform

The depth camera supports electric left and right rotation and manual adjust up and down. The HD camera supports electric rotation up, down, left and right.
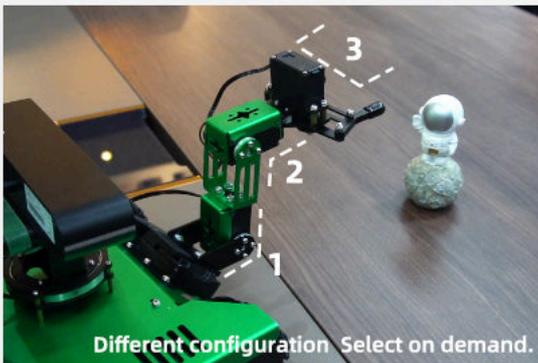
Different configuration   Select on demand.
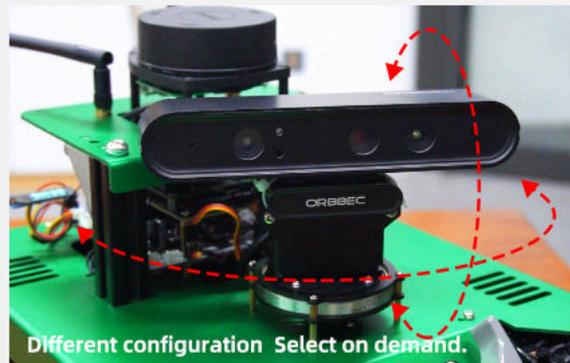
Different configuration   Select on demand.

P18   Intelligent patrol

Select the route through the mobile APP, and the car will patrol according to the route.

P19   Strong obstacle crossing ability

The large-size tracked chassis allows Transbot to have better obstacle clearance capabilities.
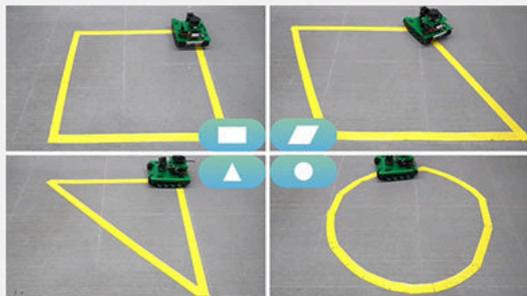
P20   MoveIt robotic arm simulation control

Robotic arm exclusive function

After Transbot is equipped with a robotic arm, the MoveIt provided by the ROS system can be used for motion simulation control. MoveIt is a ROS software package specially developed for mobile operating platforms, inheriting achievements in the fields of motion planning, three-dimensional perception, kinematics, motion control and navigation.

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P21 Lidar multi robotic cars navigation

It can control more than two robotic cars to navigate and locate in the same map. In the process of navigation, if there are obstacles within the detection range, the robot can replan the route for obstacle avoidance.
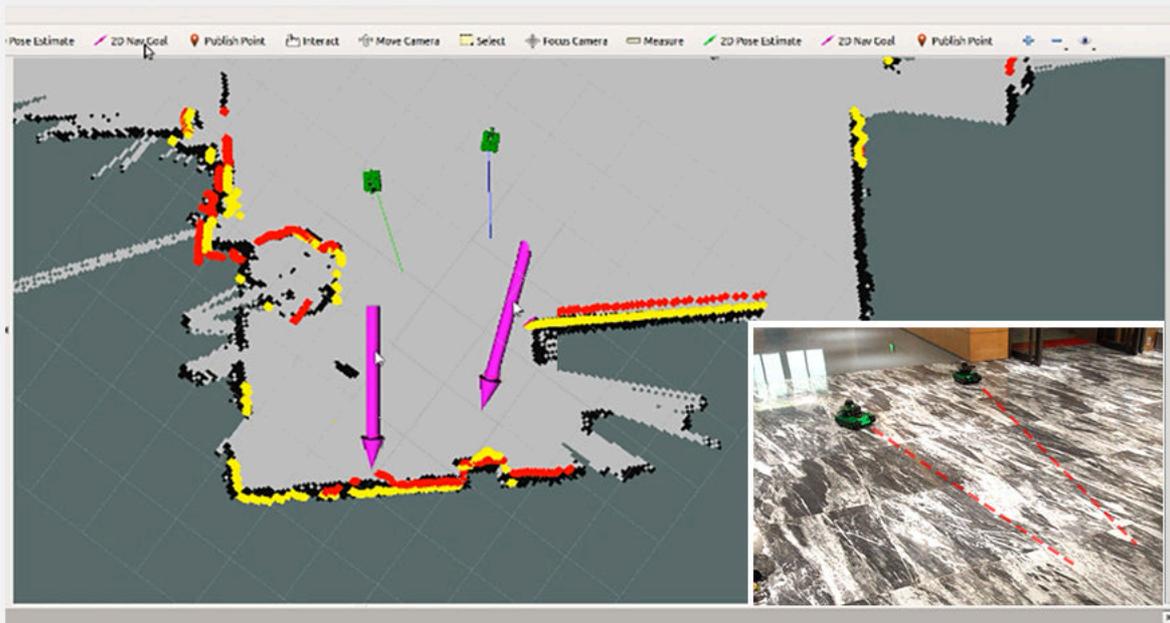
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P22 Multi robot car synchronous control

The mode key of the handle can be used to select the vehicle to control separately or control multiple robot car to complete the action synchronously.

P23 Multi robot car queue performance

Use the handle to control the robot movement, record the movement route, and then drive synchronously according to the recorded route to complete the multi vehicle queue performance.

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ROS robot operating system

RTAB 3D mapping navigation

PCL 3D point cloud

SLAM mapping navigation

Machine vision applications

Python programming

Open Source CV

MoveIt

Help

Massive learning materials

Tutorial link: http://www.yahboom.net/study/Transbot-Pi

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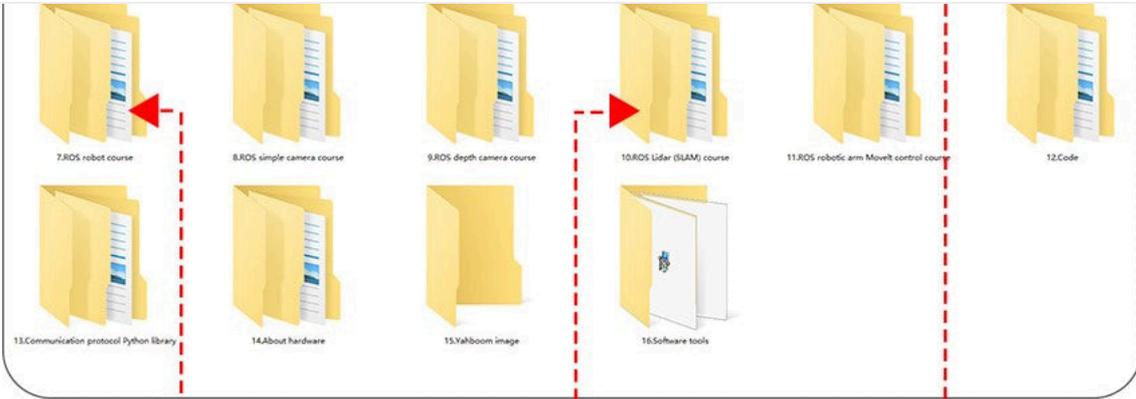
7.ROS robot course

8.ROS simple camera course

9.ROS depth camera course

10.ROS Lidar (SLAM) course

11.ROS robotic arm Movelt control course

12.Code

13.Communication protocol Python library

14.About hardware

15.Yahboom image

16.Software tools

1.Opencv application

2.Augmented Reality

3.ARTag

4.ROS+Opencv basic course

5.ROS+OpenCV application

6.Data conversion and point cloud
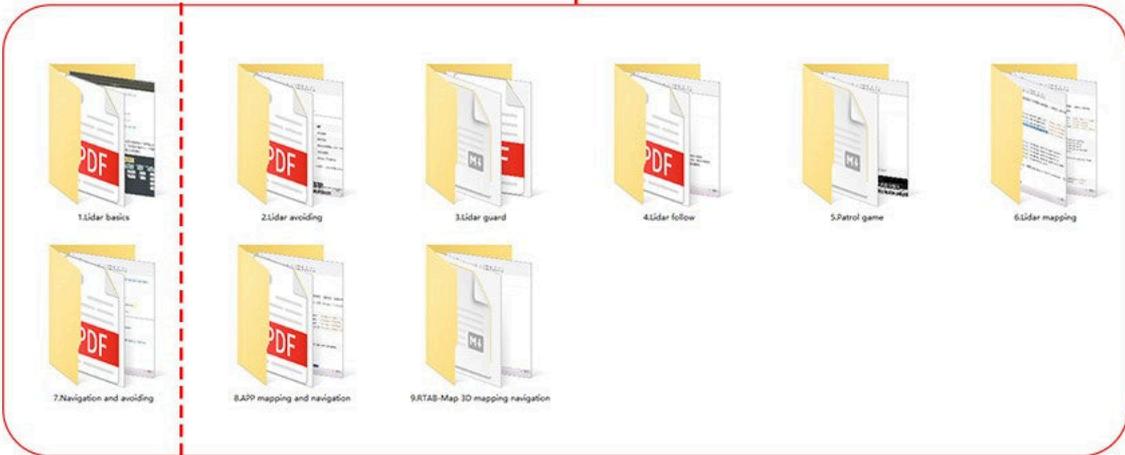
1.Lidar basics

2.Lidar avoiding

3.Lidar guard

4.Lidar follow

5.Patrol game

6.Lidar mapping

7.Navigation and avoiding

8.APP mapping and navigation

9.RTAB-Map 3D mapping navigation
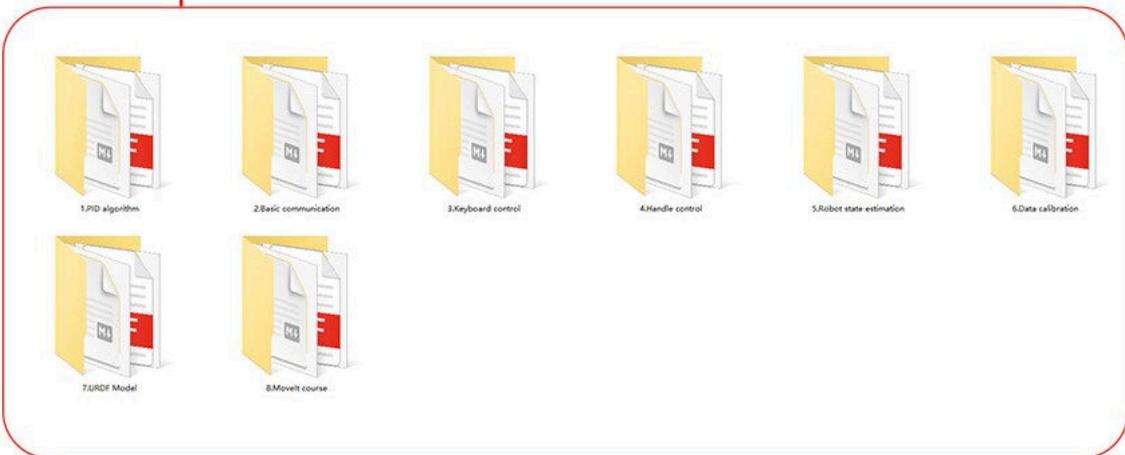
1.PID algorithm

2.Basic communication

3.Keyboard control

4.Handle control

5.Robot state estimation

6.Data calibration

7.URDF Model

8.Movelt course

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Introduction of Transbot	Introduction	
	2.Transbot manual	
Assembly and precautions	1.Precautions for use and battery safety	
	2.Assembly precautions	
	3.Assembly steps	
First Trial	1.Camera WiFi network configuration	
	2.APP remote control tutorial	
	3.USB wireless handle control	
	4.USB handle + APP control	

Transbot tutorials

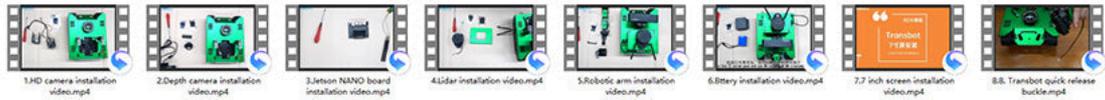|	
Hardware control course	1.About expansion board
	2.Close APP control process
	3.Install Transbot driver library
	4.Control buzzer and button
	5.Adjust LED brightness
	6.Control PWM servo
	7.Control bus servo
	8.RGB bar control
	9.Control motor
	10.Control robot movement
ROS Basic course	1.Introduction of ROS
	2.Introduction of project files
	3.Commands and tools
	4.Multi-machine communication
	5.Static IP and WiFi hotspot
ROS+OpenCV visual course	1.Opencv application
	2.Augmented Reality
	3.ARTag
	4.ROS+Opencv basic course
	5.ROS+OpenCV application
	6.Data conversion and point cloud
ROS robot course	1.PID algorithm control
	2.Basic communication
	3.Keyboard control
	4.Handle remote control

ROS Lidar (SLAM) course	3.Radar guard
	4.Radar follow
	5.Patrol game
	6.Radar mapping
	7.Navigation and avoiding
	8.APP mapping and navigation
	9.RTAB-Map 3D mapping navigation
ROS robotic arm Movelt control course	1.Robotic arm control
	2.Random move
	3.Robotic arm avoiding
Multi ROS robot car controller NEW	1.Multi robot car synchronous control
	2.Multi robot car navigation
	3.Multi robot car queue performance

Transbot annex

1.QR code recognition file
2.Checkerboard calibration file

System image and firmware

1.On board MCU firmware
2.Yahbom image file

Software development tools

1.Writing tutorial
2.Secondary writing tutorial

ROS function package and source code

1.ROS function package and source code

Communication protocol and Python driver library

1.Python driver library
2.Protocol file

Others

1.40Pin cable pin distribution diagram
2.LED module information
3.OLED display information
4.On-board MCU information

Subtotal
$0.00
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Raspberry Pi ⌄   Micro bit ⌄   RDK ⌄

Embedded Series ⌄   Accessories ⌄   Tutorials

ROS depth camera course	2.Astra color tracking	
	3.Astra object tracking	
	4.Astra autopilot	

Help

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ttes, wmcii is convenient for all users to quickly learn ROS robot.

1.Assembly steps

1.HD camera installation video.mp4   2.Depth camera installation installation video.mp4   3.Jetson NANO board installation video.mp4   4.Lidar installation video.mp4   5.Robotic arm installation video.mp4   6.Bttery installation video.mp4   7.7 inch screen installation video.mp4   8.8. Transbot quick release buckle.mp4

2.First Trial

APP control Transbot.mp4   Camera WiFi network configuration.mp4   Handle control Transbot.mp4   Handle video control Transbot.mp4

3.Hardware control course

1.About expansion board .mp4   2.Close APP control process.mp4   3.Install Transbot driver library.mp4   4.Control buzzer and button .mp4   5.Adjust LED brightness.mp4

6.Control PWM servo .mp4   7.Control bus servo .mp4   8.RGB bar control.mp4   9.Control motor .mp4   10.Control robot movement.mp4

4.ROS Basic course

1.Introduction of ROS.mp4   2.Introduction of project files.mp4   3.Commands and tools.mp4   4.Multi-machine communication.mp4   5.Static IP and WiFi hotspot .mp4

5.ROS+OpenCV visual course

1.Opencv application.mp4   2.Augmented Reality.mp4   3.ARTag.mp4   4.ROS+Opencv basic course.mp4   5.ROS+OpenCV application.mp4   6.Data conversion and point cloud.mp4

6.ROS robot control course

Help

1.Camera calibration.mp4   2.Color tracking.mp4   3.Object tracking.mp4   4.Autopilot.mp4

8.ROS depth camera course

1.ROS depth camera course.mp4   2.Astra camera calibration.mp4   3.Astra color tracking.mp4   4.Astra object tracking.mp4   5.Astra autopilot.mp4

9.ROS Lidar (SLAM) course

1.Lidar basics.mp4   2.Lidar avoiding.mp4   3.Lidar guard.mp4   4.Lidar follow.mp4   5.Patrol game.mp4

6-1.Lidar mapping.mp4   6-2.Lidar mapping.mp4   6-3.Lidar mapping.mp4   6-4.Lidar mapping.mp4   6-5.Lidar mapping.mp4

7.Navigation and avoiding.mp4   8.APP mapping and navigation.mp4   9.RTAB-Map 3D mapping navigation.mp4

10.ROS robotic arm MoveIt control course

1.Robotic arm control.mp4   2.Random move.mp4   3.Robotic arm avoiding.mp4

If you want to watch the video tutorial, you can
search for "Yahboom" on Youtube.

Help

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Help

7-inch HD touch screen (optional)

SLAM A1 Lidar

Astra Pro Plus Depth Camera & HD Camera

HQ aluminum alloy frame

Rotating electric platform

Through-type taillights

HQ anti-carton bearings

Quick release robotic arm (optional)
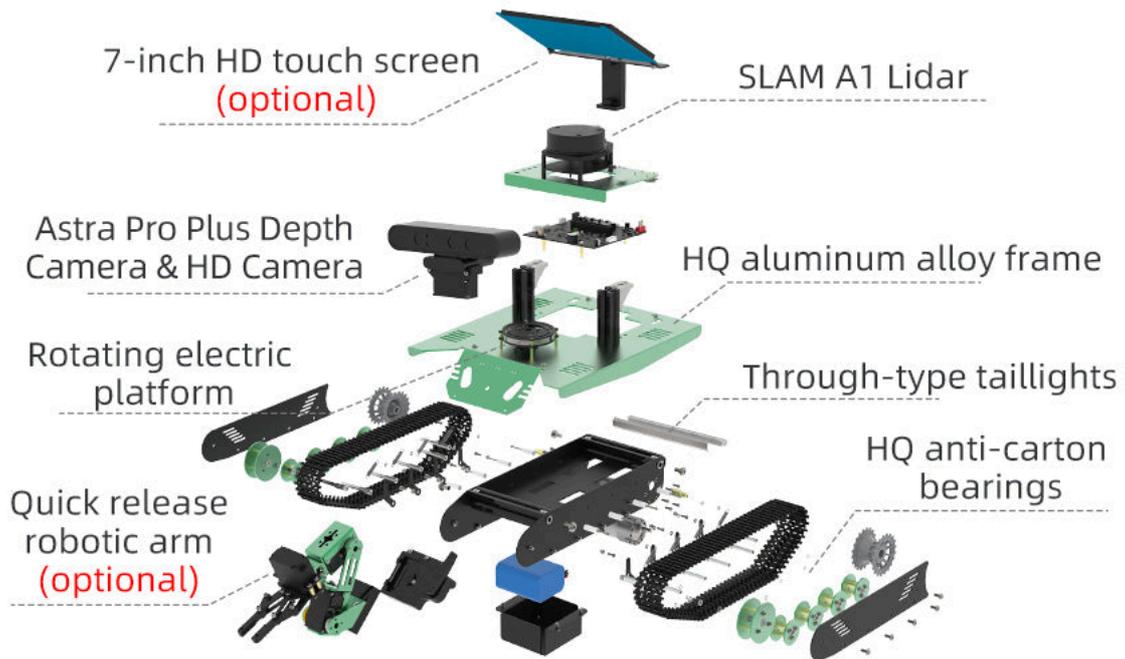
The overall structure of this product has applied for a utility model patent, patent number: 202122169981.0

3 DOF robotic arm

Bus servo can read the servo angles in real time, and can control the robotic arm through Movelt simulation.

Astra Pro Plus depth camera

Realizes 3D point cloud map, depth map, KCF tracking and other functions, combined with lidar can complete RTAB 3D map navigation.
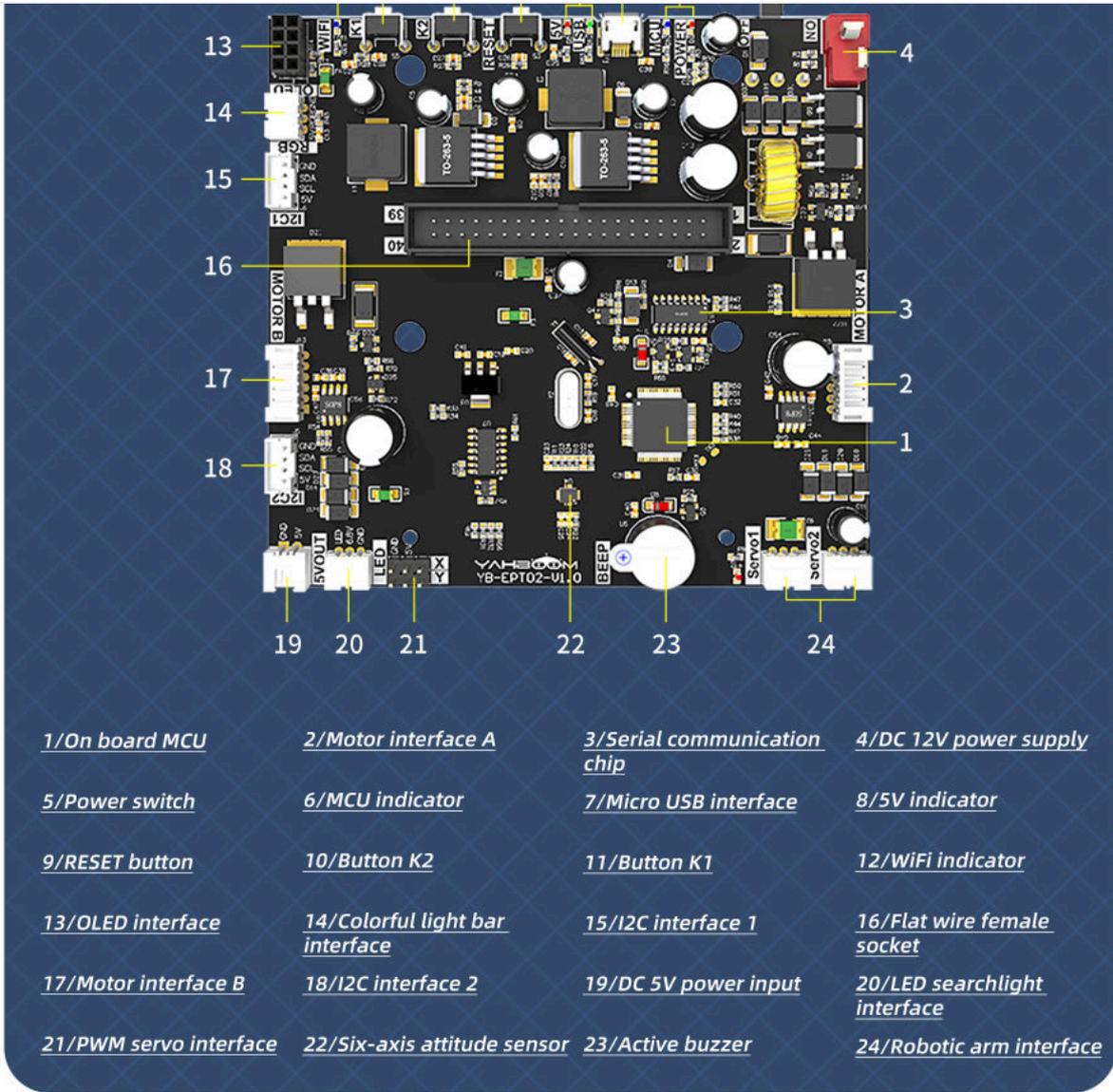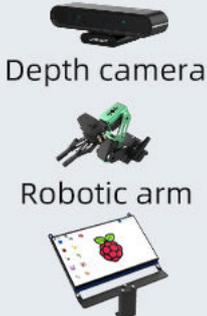
SLAM A1 Lidar

Indoor 2D plane scanning and mapping, single-point and multi-point navigation, avoiding and follow functions.

7-inch HD touch screen

Convenient to debug ROS robot.

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1/On board MCU   2/Motor interface A   3/Serial communication chip   4/DC 12V power supply

5/Power switch   6/MCU indicator   7/Micro USB interface   8/5V indicator

9/RESET button   10/Button K2   11/Button K1   12/WiFi indicator

13/OLED interface   14/Colorful light bar interface   15/I2C interface 1   16/Flat wire female socket

17/Motor interface B   18/I2C interface 2   19/DC 5V power input   20/LED searchlight interface

21/PWM servo interface   22/Six-axis attitude sensor   23/Active buzzer   24/Robotic arm interface

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Help

configuration 2

Recommended reason: joint calibration of depth camera and lidar, 3D visual navigation

Frame
Depth camera

Recommended configuration 3

Recommended reason: Experience the Movelt simulation control manipulator.

Frame
HD camera
Robotic arm

Recommended configuration 4

Recommended reason: Easy to debug ROS robot.

Frame
Depth camera
Robotic arm

Recommended configuration 5

Recommended reason: Full configuration, users can debug the robot anytime and anywhere.

Frame
Depth camera
Robotic arm
7inch screen

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7inch screen

Help

Subtotal
$0.00 USD

Help

Aluminum box size: 41.5cm*28cm*28cm
Product weight: 6.0kg ~ 7.2kg (the weight will vary according to different configurations)

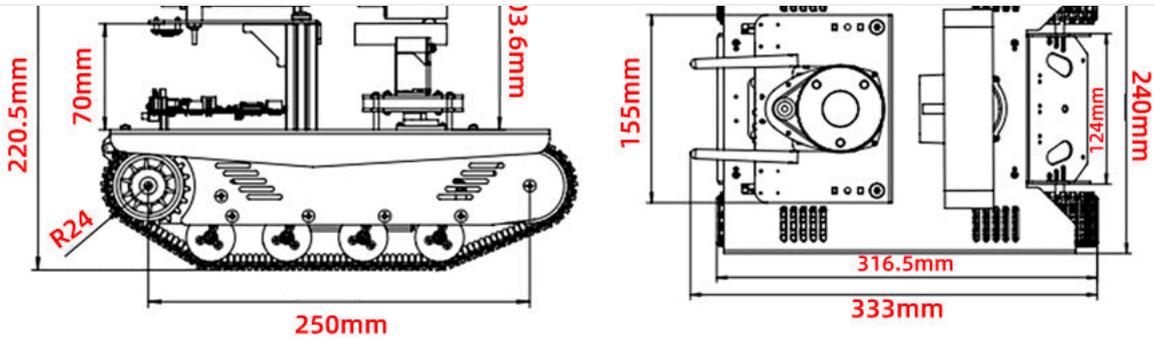Any version Transbots are shipped in black customized aviation aluminum box.

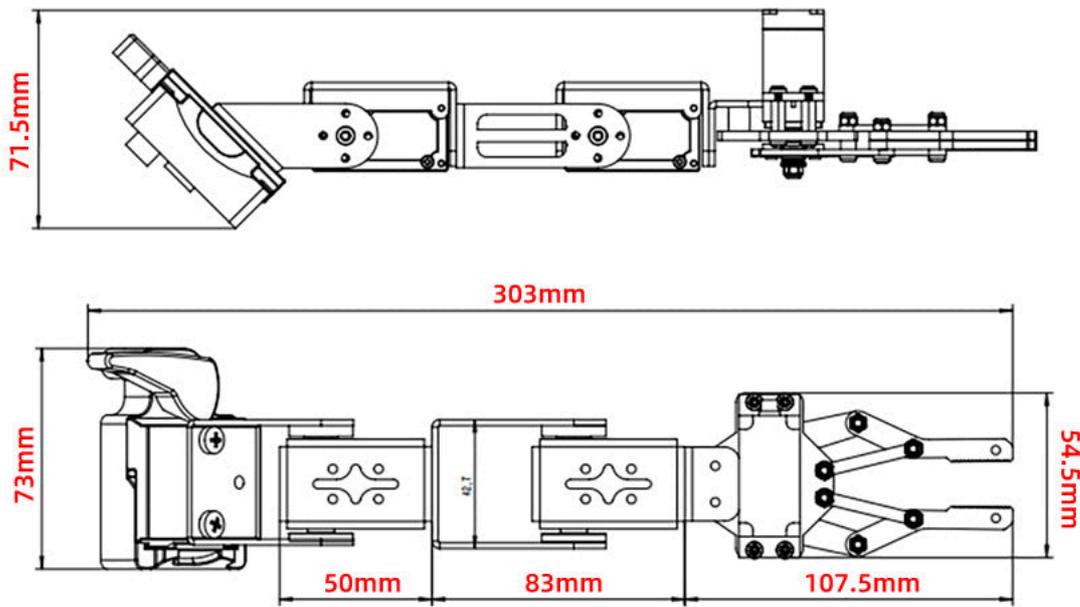All accessories are brand new and original.

After the vehicle is installed, you can also use this aluminum box for storage, and the aluminum box has enough space for the entire vehicle to be stored.
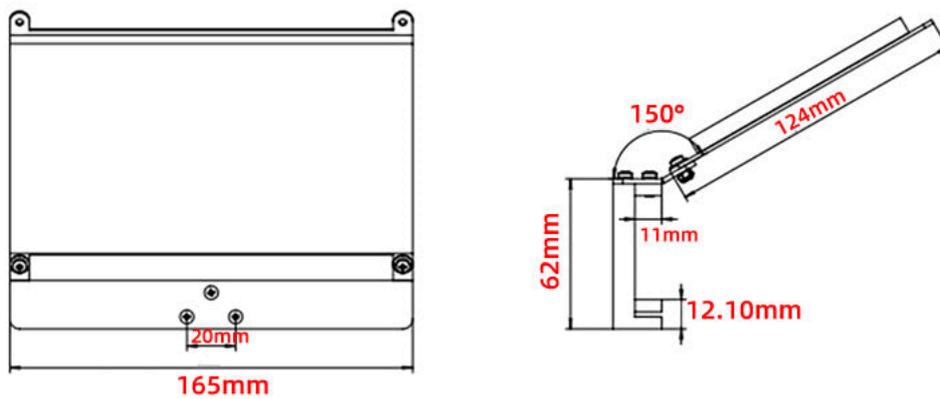
Details

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2、Robotic arm size parameters

3、7-inch display screen size parameters

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Enter	HD camera (Astra Pro Plus depth camera), SLAM A1M8 lidar, PS2 wireless handle, six-axis attitude sensor, motor speed measuring code wheel	Output	RGB colorful taillights, buzzer, 520 motor interface*2, bus servo interface, servo pan/tilt, LED searchlight, OLED display
PTZ servo solution	Metal 9G steering gear	Power scheme	12.6V 4400mah 2C lithium battery pack
Battery life	2 hours	power interface	T-shaped power supply interface, DC4.0*1.7 charging interface
Remote control	Mobile APP, PC computer, PS2 wireless controller	Way of communication	WiFi network (LAN/AP)
Safety protection	overcurrent protection	Body material	Anodized aluminum alloy

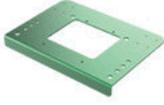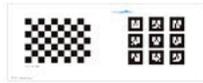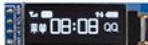| Astra Pro Plus depth camera product parameters			
3D technology	ORBBECR monocular structured light	Range	0.6-8m
Precision	1m: ±3mm	Field of View (FOV)	H 58.4° ×V 45.8°
Resolution	640 ×480@30fps 320×240@30fps 160x 120@30fps	Frame rate	1920*1080@30fps 1280*720@30fps 640*480@30fps
Advanced Processing Chip	MX6000	Close protection	support
RGB field of view	H66.73° V40.19° @1920*1080 H66.99° V40.37° @1280*720 H60.60° V46.81° @640*480	UVC(RGB)	support
Supported operating system	Android / Linux / Windows	Data interface	USB2.0
Size	164.85* 48.25* 40	Microphone	two-channel stereo
Power consumption	<2.5W	Safety	Class1 laser
Operating temperature	10℃-40℃		

Help

YB-PO9M metal servo (electric rotating platform)			
Servo	YB-P09M	Maximum angle	180°
Voltage	4.8-6V	Torque	1.5kgf.cm 4.8V/1.8kgf.cm 6V
Reaction speed	0.12sec/60°4.8V/0.10sec/60° 6V	Servo type	Digital servo
Gear	Metal gear	Weight	14g

Serial bus servo parameters (Robotic arm)			
Servo YB-S06 (mechanical claw 6KG)		Servo YB-SD15M (robotic arm 15kg)	
Maximum angle	90°	Maximum angle	300°±15°
Voltage	4.8V-6V	Voltage	6.0-7.4V
Torque	8kgf.cm 6V	Torque	15kgf.cm 7.4V
Reaction speed	0.20sec/60° 6V	Reaction speed	0.30sec/60° 7.4V
Servo type	Serial bus servo	Servo type	Serial bus servo
Gear	Plastic gear	Gear	Metal gear
Weight	52±1g	Weight	50±1g
Working dead zone	5μs	Working dead zone	5μs
Characteristic	Locked rotor 5s power-off protection, lifting weight 5kgf.cm clutch protection	Characteristic	Locked for 3 seconds to enter the protection, and receive a new signal to release

520 encoder motor parameters (robot power motor)			
Rated voltage	12V	Rated power	≤4W
Motor type	Permanent magnet with brush	Locked-rotor current	4A
Locked-rotor torque	8.3kgf,cm	Rated current	0.3A
Rated torque	6.5kgf.cm	Reduction ratio	1:56
Speed before deceleration	12000	Speed after deceleration	205±10rpm
Output shaft	6mm diameter D-type eccentric shaft	Encoder type	Hall encoder
Number of lines	11	Supply voltage	3.3-5V
Interface Type	PH2.0		

Power battery pack parameters			
Capacity	4400mAh	Rated discharge current	8.8A (2C)
Size	68*55*37mm	Maximum discharge current	10A
Weight	300g	Plug	T-plug discharge+4017 female
Charger	12.6V 800mA	Protect	Over current, over charge, over discharge, short circuit protection

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Frame	Lidar fixed plate	**Optional** Raspberry Pi 4B	Raspberry Pi accessory kit	Expansion board
USB wireless handle	Handle mobile phone holder	Charger	Several cables	micro USB data cable
Cable tie	Screwdriver	Mechanical code & checkerboard paper	Card reader + TF card	transbot manual
Parts package	OLED screen	Battery pack	Battery case	Packing box + anti-collision sponge

SLAM A1 Lidar pack

SLAM A1 Lidar	micro USB data cable	No.6 package

HD camera pack

HD camera + searchlight	HD camera bracket (assembly)	Several cables	No.5 package

Astra Pro Plus depth camera pack

Astra Pro Plus depth camera	Depth camera support (assembly)	Depth camera fixed bracket	No.4 package

Help

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| 7 inch screen | 7 inch screen fixed bracket | 7 inch screen support | No.8 package |

Tutorial link

[Yahboom Raspberry Pi Transbot Robot](#)

Customer Reviews

★★★★★
Based on 13 reviews

★★★★★ ▓▓▓▓░░░░ 85% (11)
★★★★☆ ▓░░░░░░░ 15% (2)
★★★☆☆ ░░░░░░░░ 0%   (0)
★★☆☆☆ ░░░░░░░░ 0%   (0)
★☆☆☆☆ ░░░░░░░░ 0%   (0)

Most Recent ▼

Help
■

E   ★★★★★ 10/29/2024
    Verified **Elia Ferrari**

Molto bello
Complimenti bel lavoro, fatto bene e completo

D   ★★★★★ 10/11/2024
    Devendra Sookia

Just received the package, the packaging is as shown in the picture.
I am very satisfied!
I will bring it to my lab next week and officially start my DIY project.

L   ★★★★☆ 05/17/2023
    Lucas Rodrigues Souza

I was really impressed with this Raspberry Pi Tracked Transbot Car. First, its structural design and build quality are excellent. The trolley is made of strong and durable materials, ensuring its stability and durability.

Secondly, I am very satisfied with the control and programming flexibility of it. With Raspberry Pi, we can customize and optimize the behavior of the car. It allows us to write our own code to implement various functions such as automatic navigation, path planning, etc.

In the end, the performance and responsiveness of the little car is excellent. It responds quickly to commands and moves with just the right speed. This makes controlling and operating the trolley smoother and easier.

Last week, I purchased this Raspberry Pi Transbot car from this website and I am generally satisfied with my purchase. Shipping list inlcude all the necessary parts and tools for assembly, which was straightforward.

The AI capabilities are impressive and the car is able to detect and avoid obstacles with relative ease. However, the programming was a bit more challenging than I anticipated and I had to do some research and troubleshooting to get it working properly.

Additionally, the seller's customer service could have been more responsive to my inquiries.

B   ★★★★★ 03/23/2023
Benjamin Netanyahu

As an experienced programmer, I was looking for a challenge and this programming car delivered. The open-source platform allowed me to customize the code to my liking and the car's functionality is impressive. It's fast, responsive and the sensors work flawlessly.
Thanks for fast and safe logistics from Yahboom!

1   2   3   ›   ›|

Questions & Answers

Have a Question?   ? Ask a Question

I will I will draft an order and send it to you.

Q **I bought it, but I have an error with the astra camera launching , also the frame rate is very low (1 fps), is there a method to modify this?**

A Hello friend,
Sorry for lata reply. Could you send your question to this E-mail:support@yahboom.com
Our Technical Support will reply you ASAP.

Q **Can this recognize other things (not faces). For example, a date bunch?**

A Hello friend,
Thanks for your message.
This is a programmable product, and we currently only provide routines to recognize a person's face.
If you need to identify a group of people, you can do that by modifying the code.

Q **If I formatted the memory by wrong, how could I restore the files again? Can I get another memory card?**

A Hi friend,
Could you contact our technical support is via email or WhatsAPP. He will provide professional services to help you solve the problem ASAP.
E-mail: support@yahboom.com   WhatsAPP: +86 18682378128

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